

# Mixed Precision Training

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# Training large models

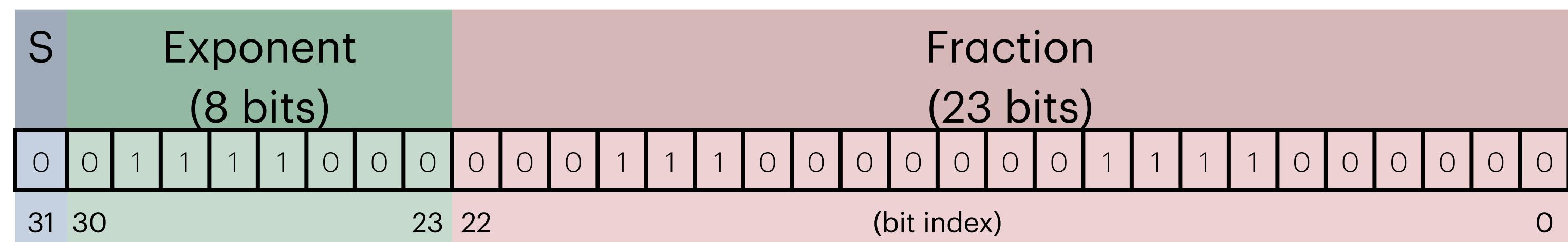
## Memory requirements

- Without optimization
  - Model parameters:  $N$
  - Weights:  $N$  floats
  - Gradients:  $N$  floats
  - Momentum:  $N$  floats
  - 2nd momentum (ADAM):  $N$  floats
  - $16N$  bytes without counting activations



# float32

<b>float32</b>	
Sign	1 bit
Exponent	8 bit
Mantissa	23 bit
Precision (relative)	1E-07
Max value	3E+38
Min value (normal)	1.7E-38



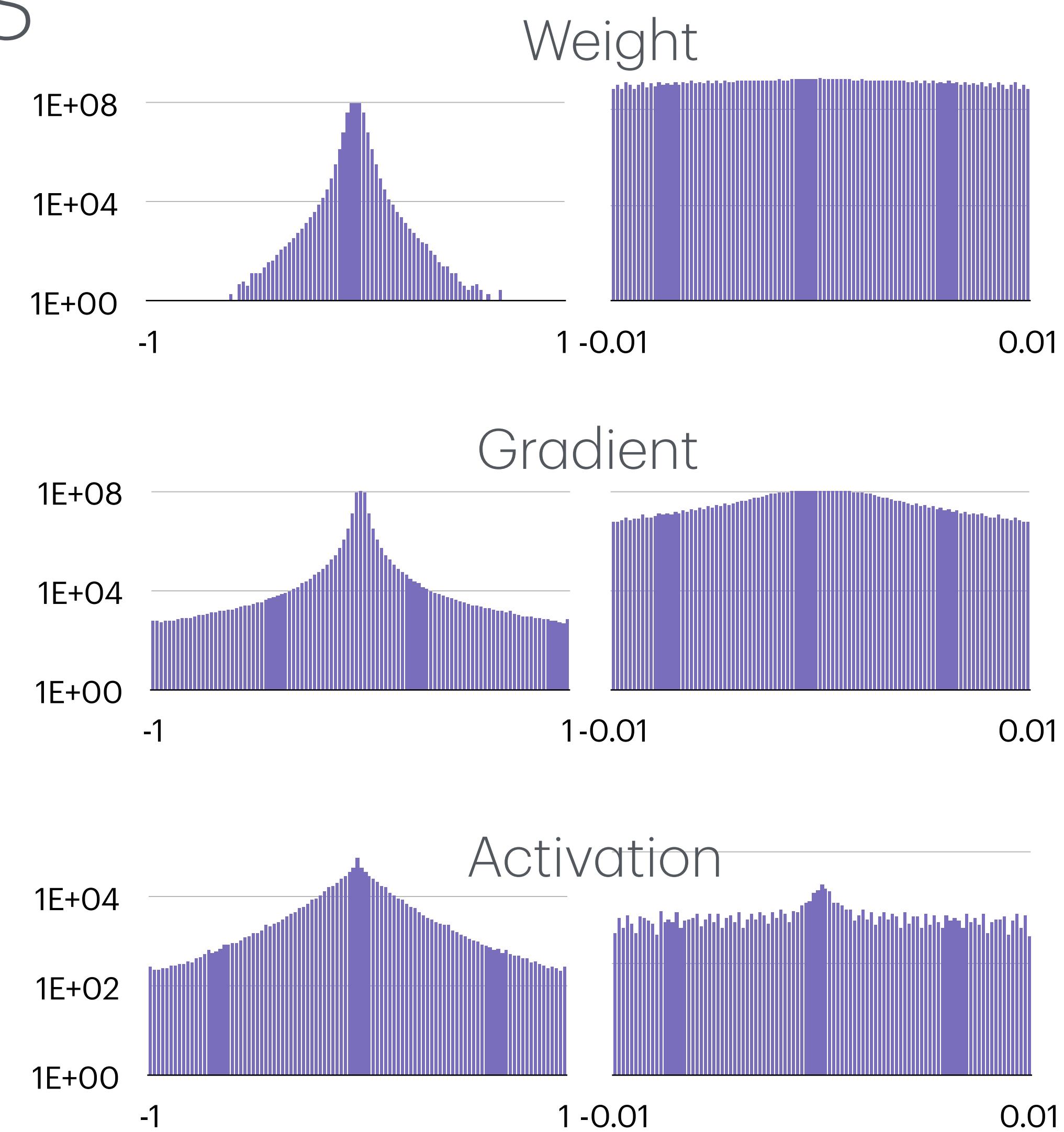
$$\text{Precision (relative)} = \frac{x_2 - x_1}{x_1}$$

where  $x_2$  is smallest value  $x_2 > x_1$

# float32 vs deep networks

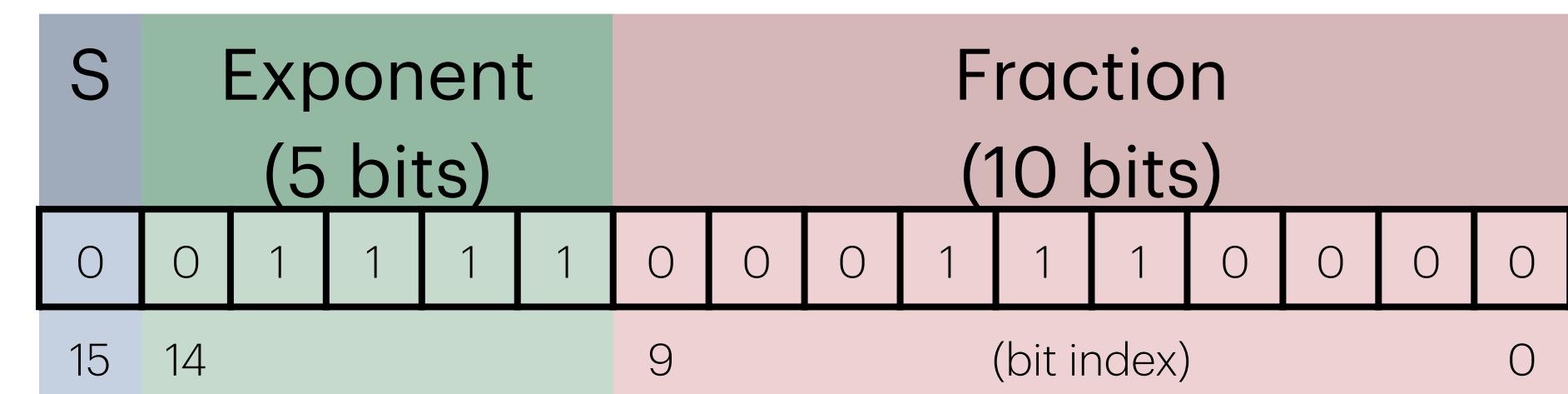
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<b>Llama 3.1 8b</b>	
Largest weight	3.21
Smallest weight	-0.83
Largest gradient	5.09
Smallest gradient	-4.41
Largest activation	227.42
Smallest activation	-206.84



# Float16

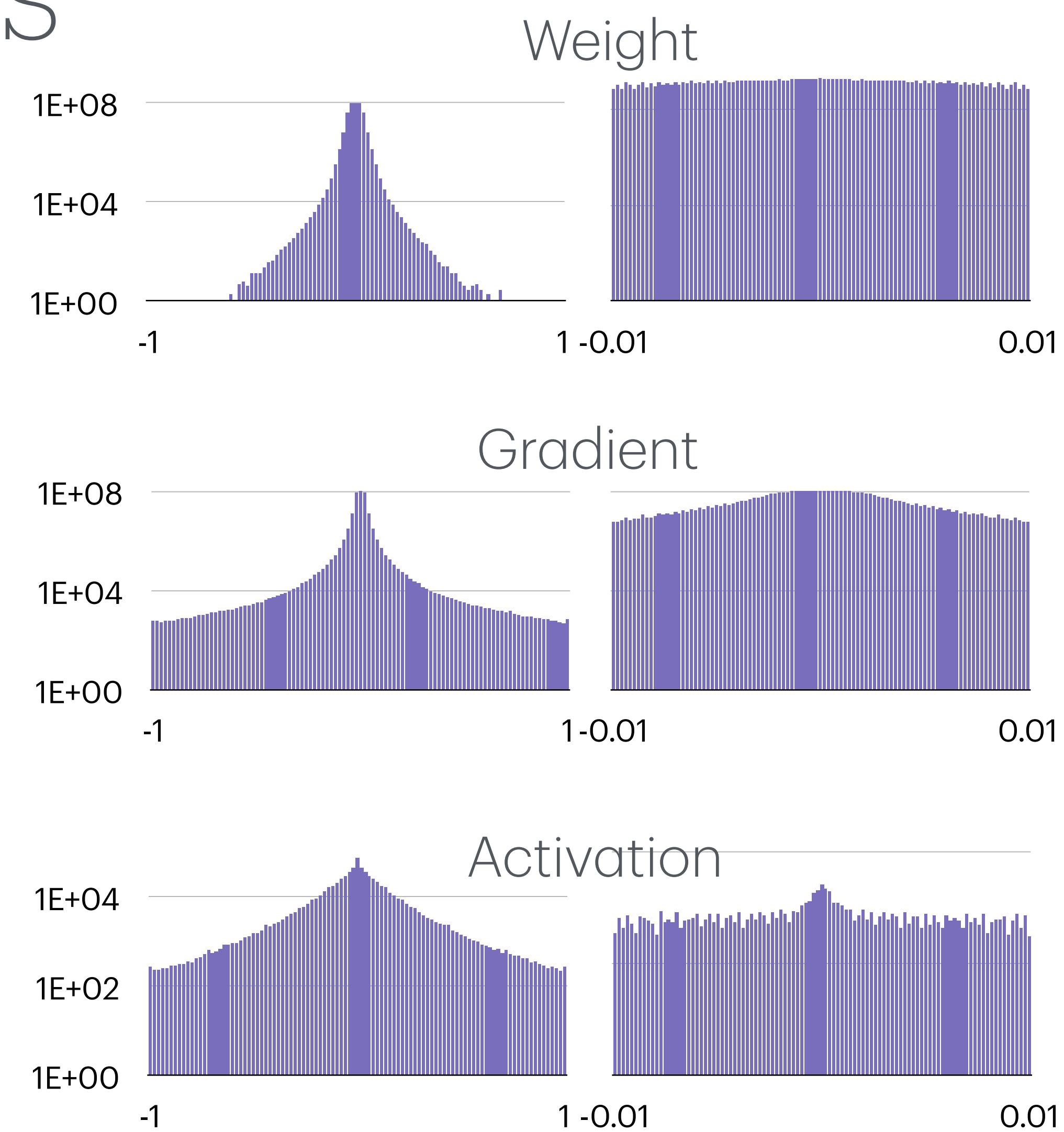
Float16	
Sign	1 bit
Exponent	5 bit
Mantissa	10 bit
Precision (relative)	1E-04
Max value	65504
Min value (normal)	6E-05



# Float16 vs deep networks

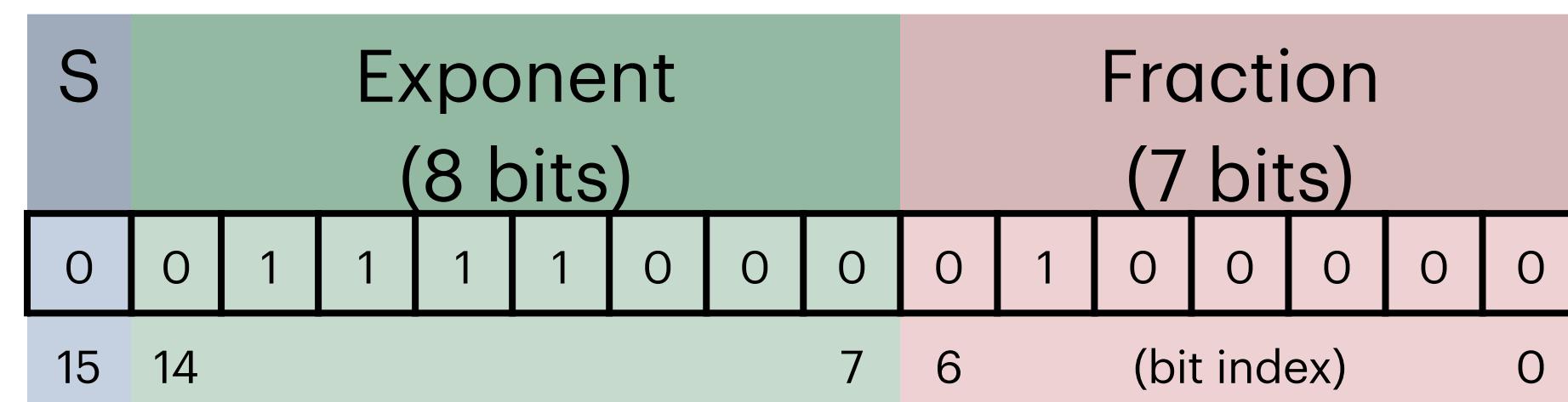
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# Bfloat16

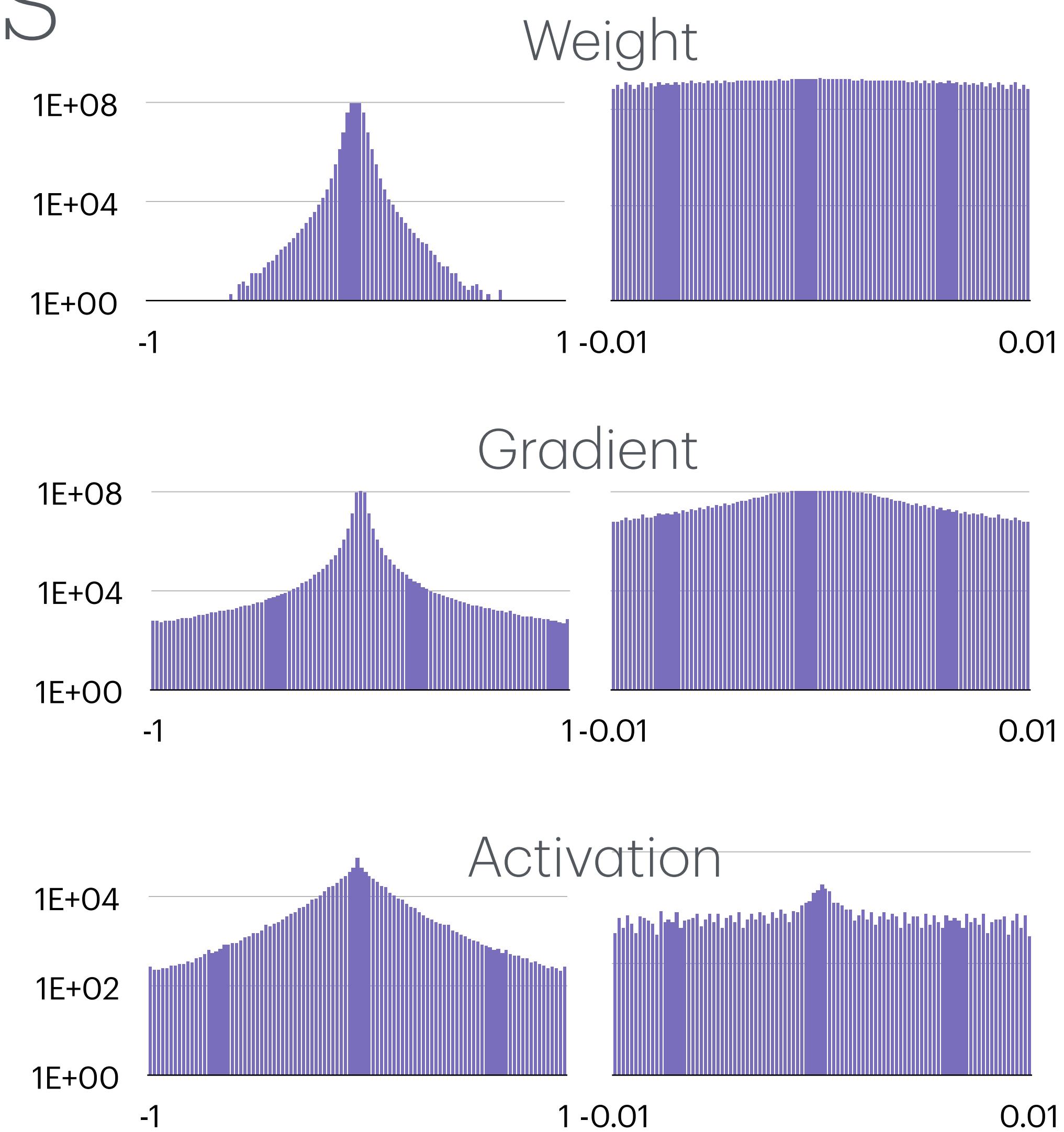
<b>Bfloat16</b>	
Sign	1 bit
Exponent	8 bit
Mantissa	7 bit
Precision (relative)	7.8E-03
Max value	3E+38
Min value (normal)	1.7E-38



# Float16 vs deep networks

<b>Bfloat16</b>	
Sign	1 bit
Exponent	8 bit
Mantissa	7 bit
Precision (relative)	7.8E-03
Max value	3E+38
Min value (normal)	1.7E-38

<b>Llama 3.1 8b</b>	
Largest weight	3.21
Smallest weight	-0.83
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Smallest activation	-206.84



# Float32 vs (b)float16

- (B)float16 uses **half** the memory
- (B)float16 can be more than twice as fast
  - Why more than twice?

	V100 SXM	A100 SXM	H100 SXM
TF32 FLOPs Tensor Core	N/A	156T	494.7T
FP16 FLOPs Tensor Core	125T	312T	989.4T

[1] NVIDIA, [V100 Datasheet](#), 2020

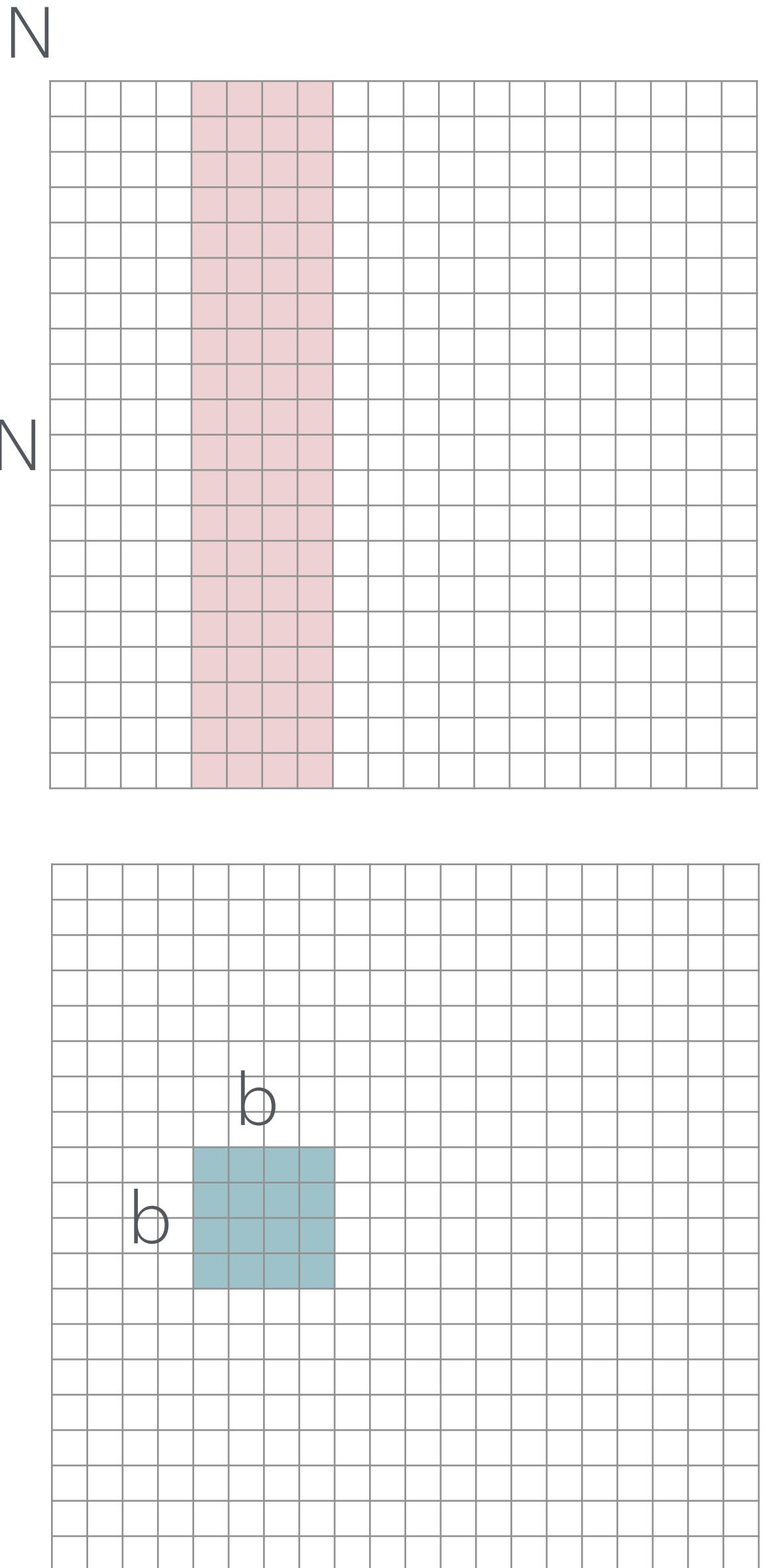
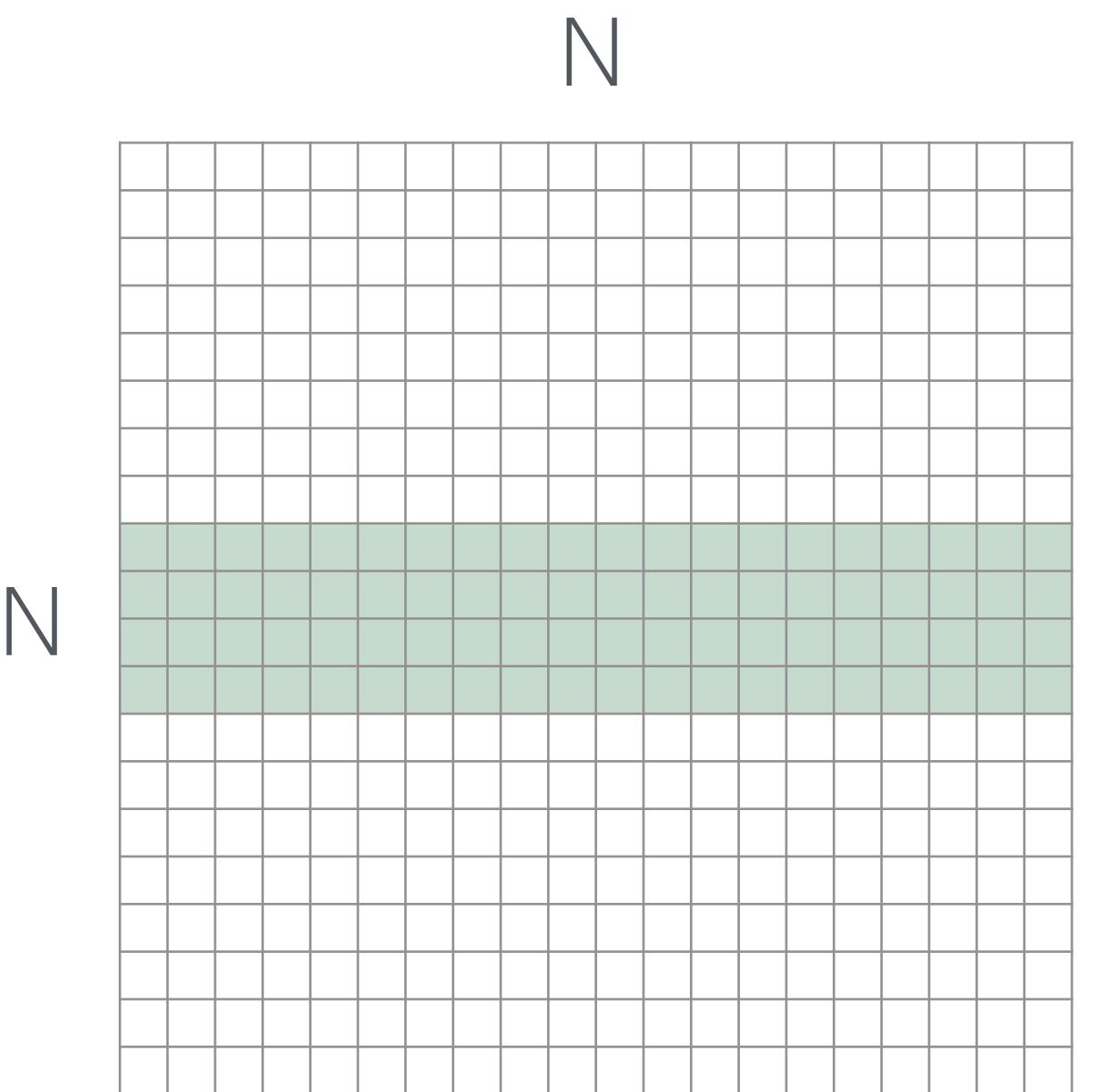
[2] NVIDIA, [A100 Datasheet](#), 2021

[3] NVIDIA, [H100 Datasheet](#), 2023

# Computation in bfloat16

Case study: matmul

- $C = AB$
- $C_{ij} = \sum_k A_{ik}B_{kj}$
- What is the bottleneck in modern GPUs?
  - Memory read and writes



# Computation in bfloat16

Case study: matmul

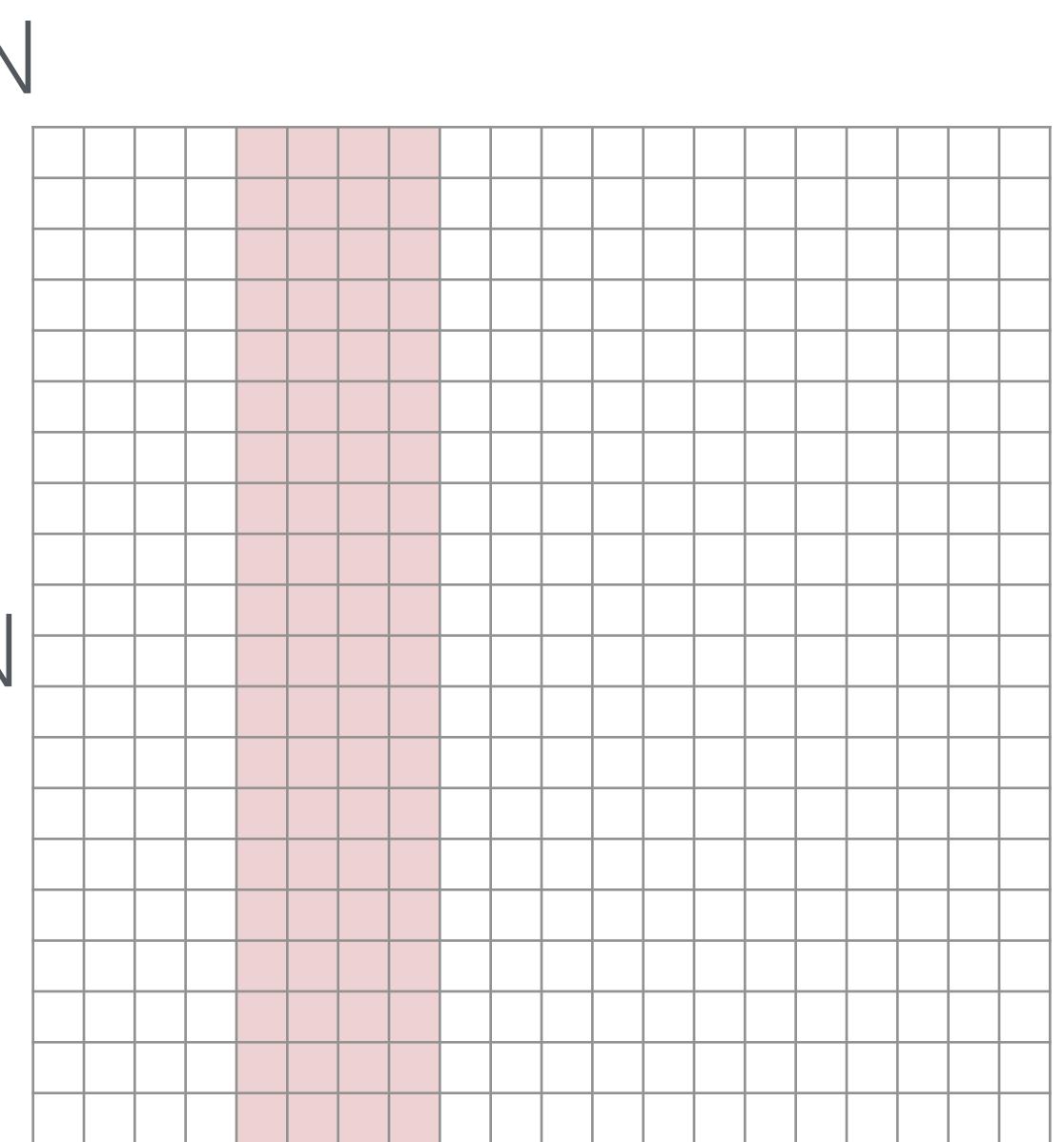
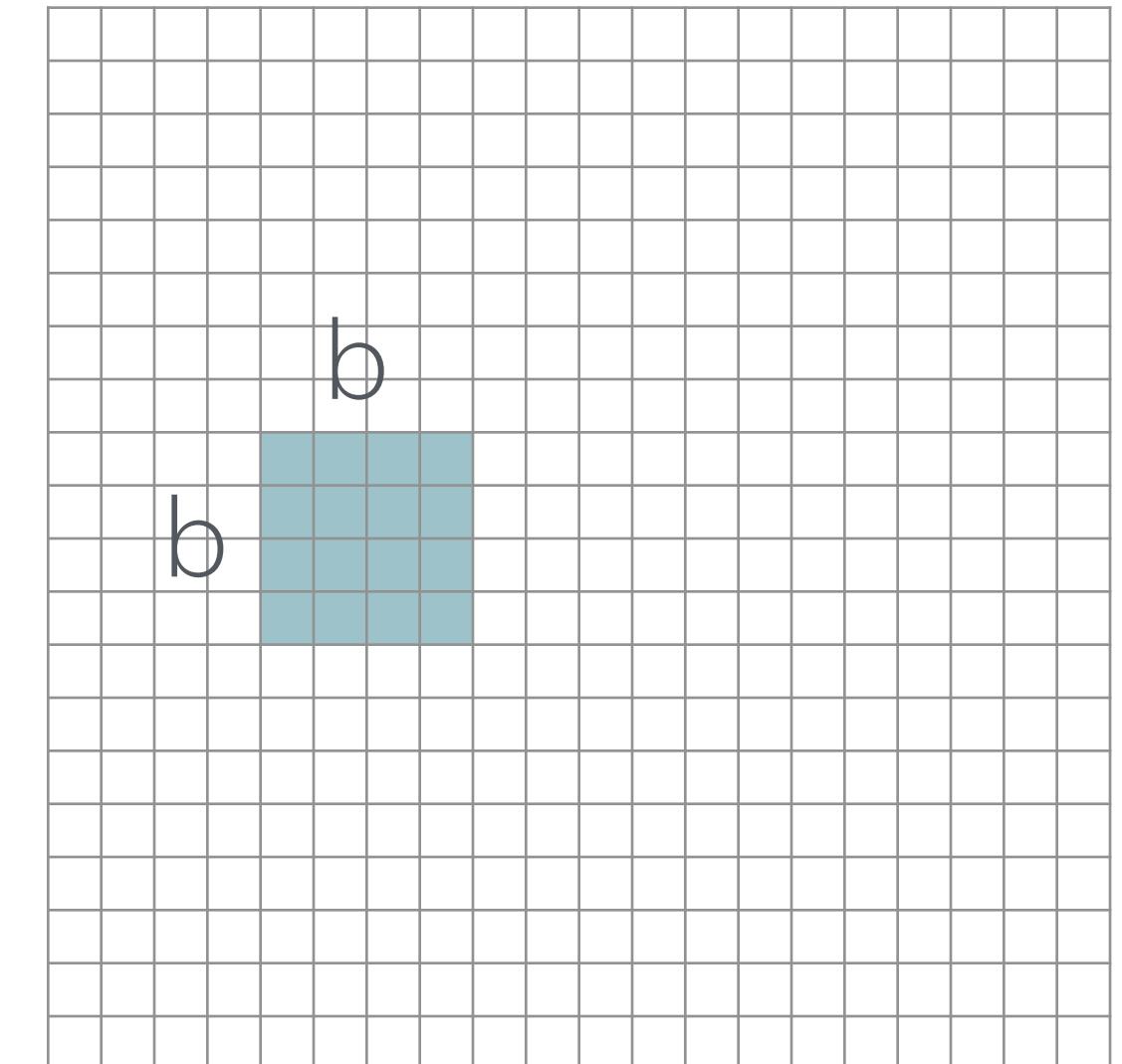
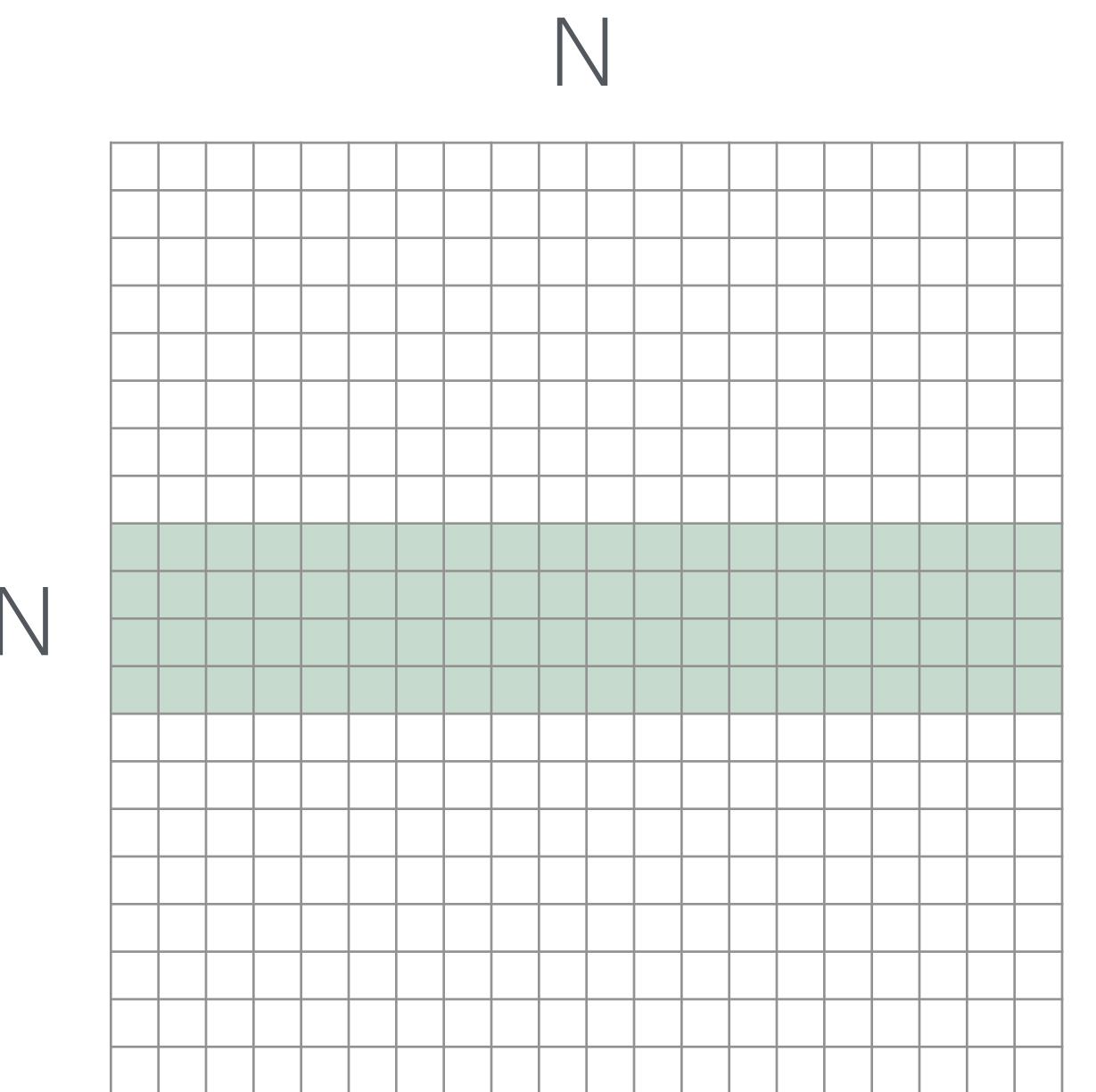
- Naive implementation

```
c_ij = 0
```

```
for k = 1 ... N:
```

```
    c_ij += A_ik B_kj
```

- Number of memory reads  $2N^3$



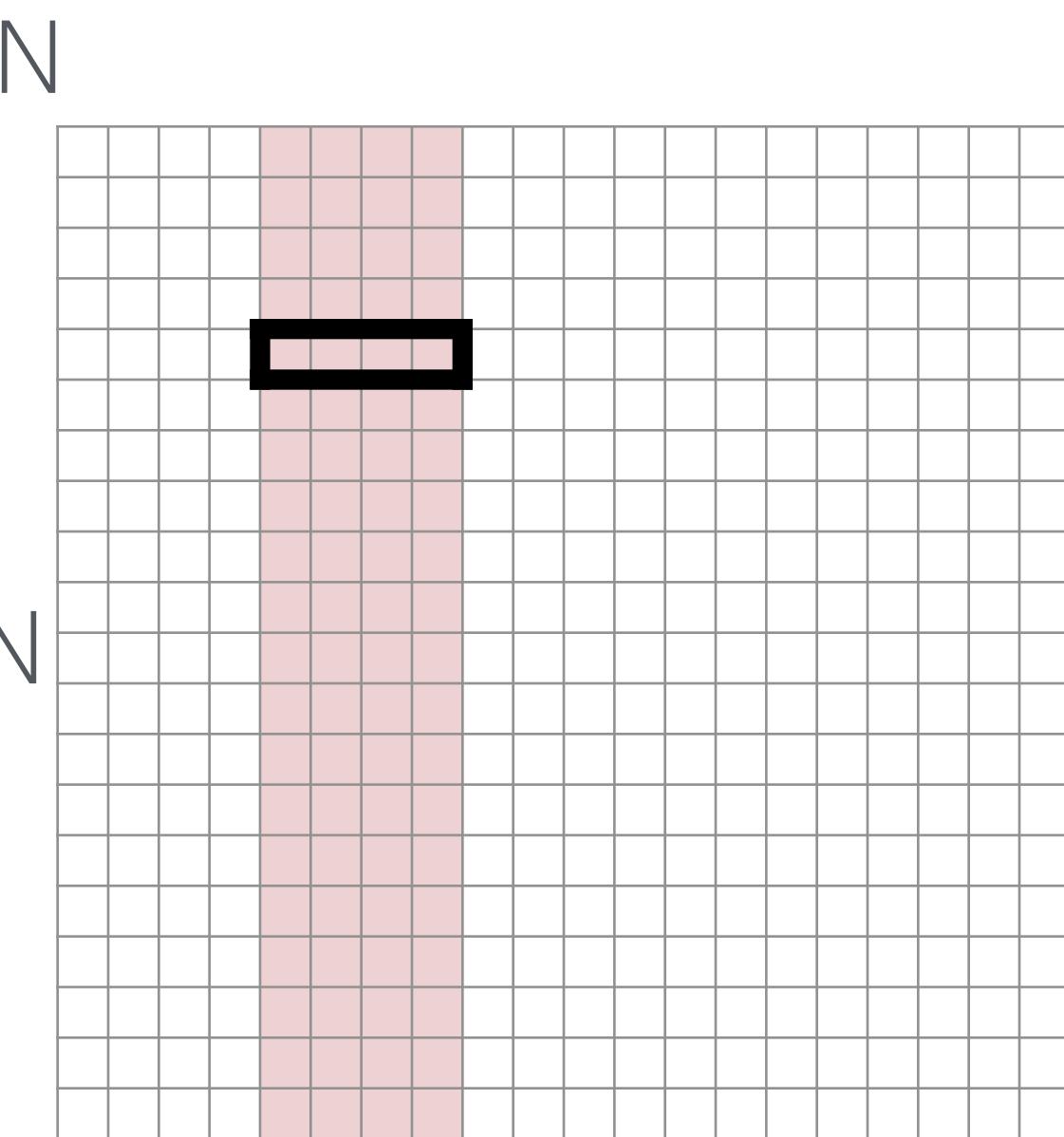
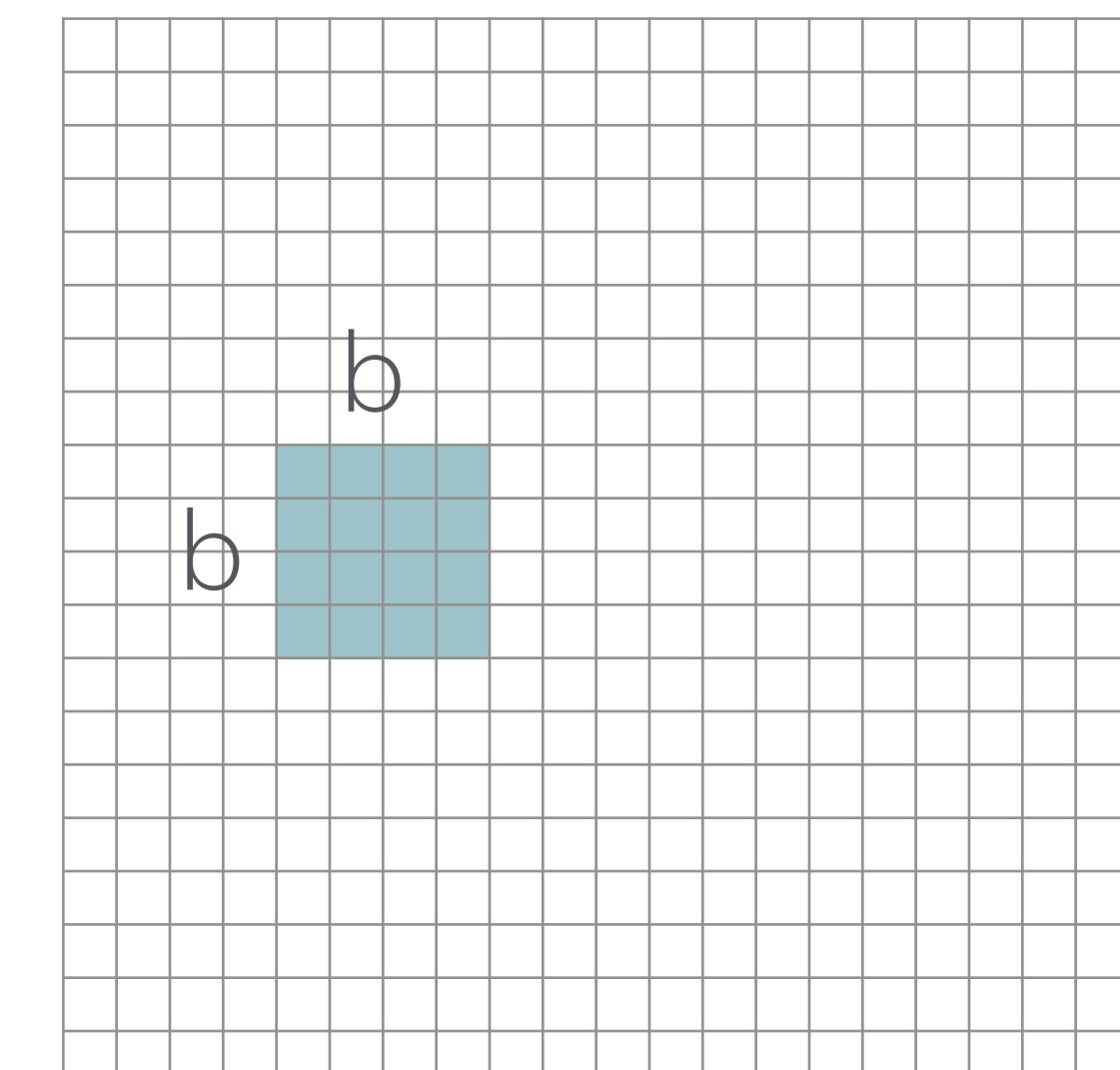
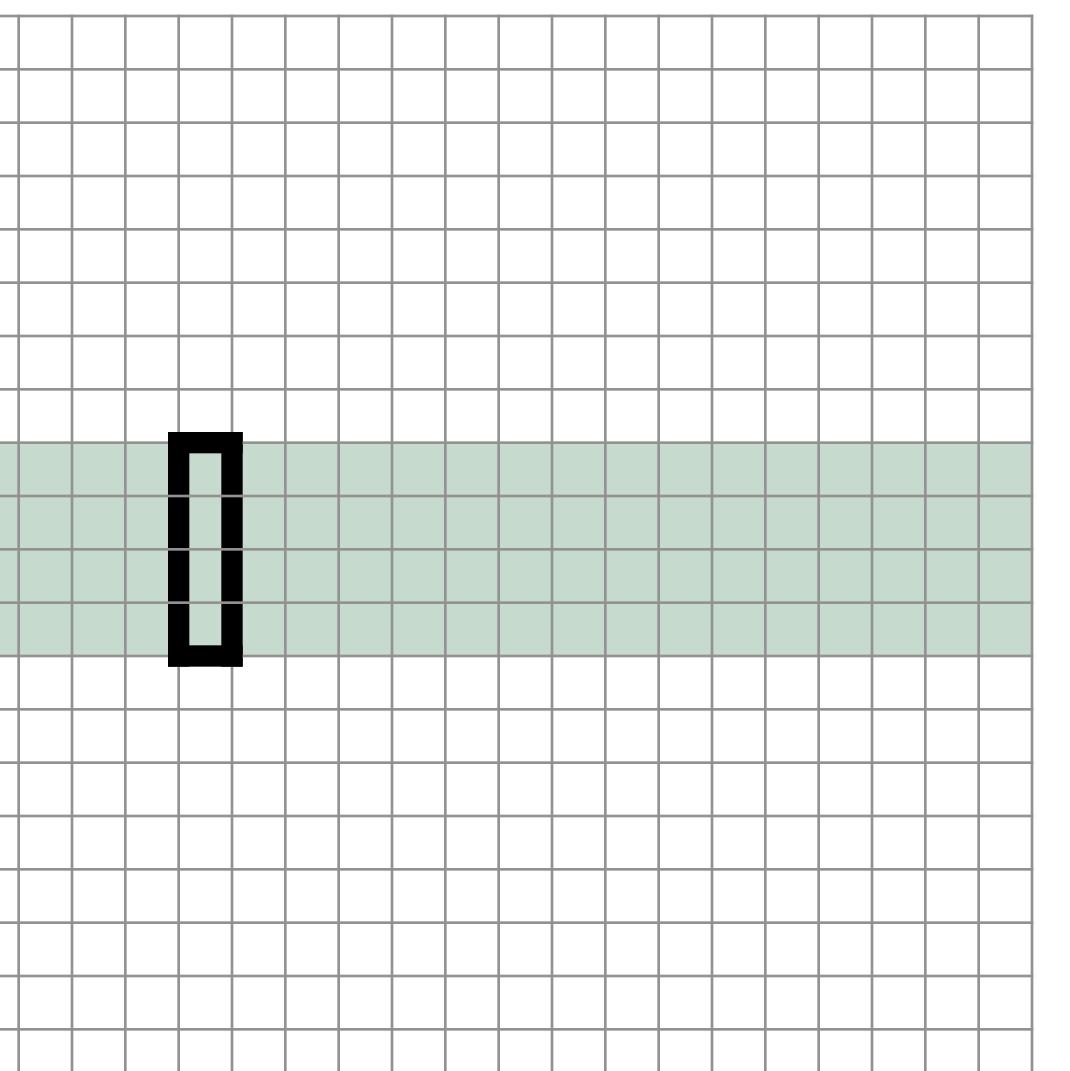
# Computation in bfloat16

## Case study: matmul

- Faster matmul

```
# for each bxb block  
C_ij = 0  
for k = 1 ... N:  
    # load all A_:k B_:j in  
    # block into shared memory  
    C_ij += A_ik B_kj
```

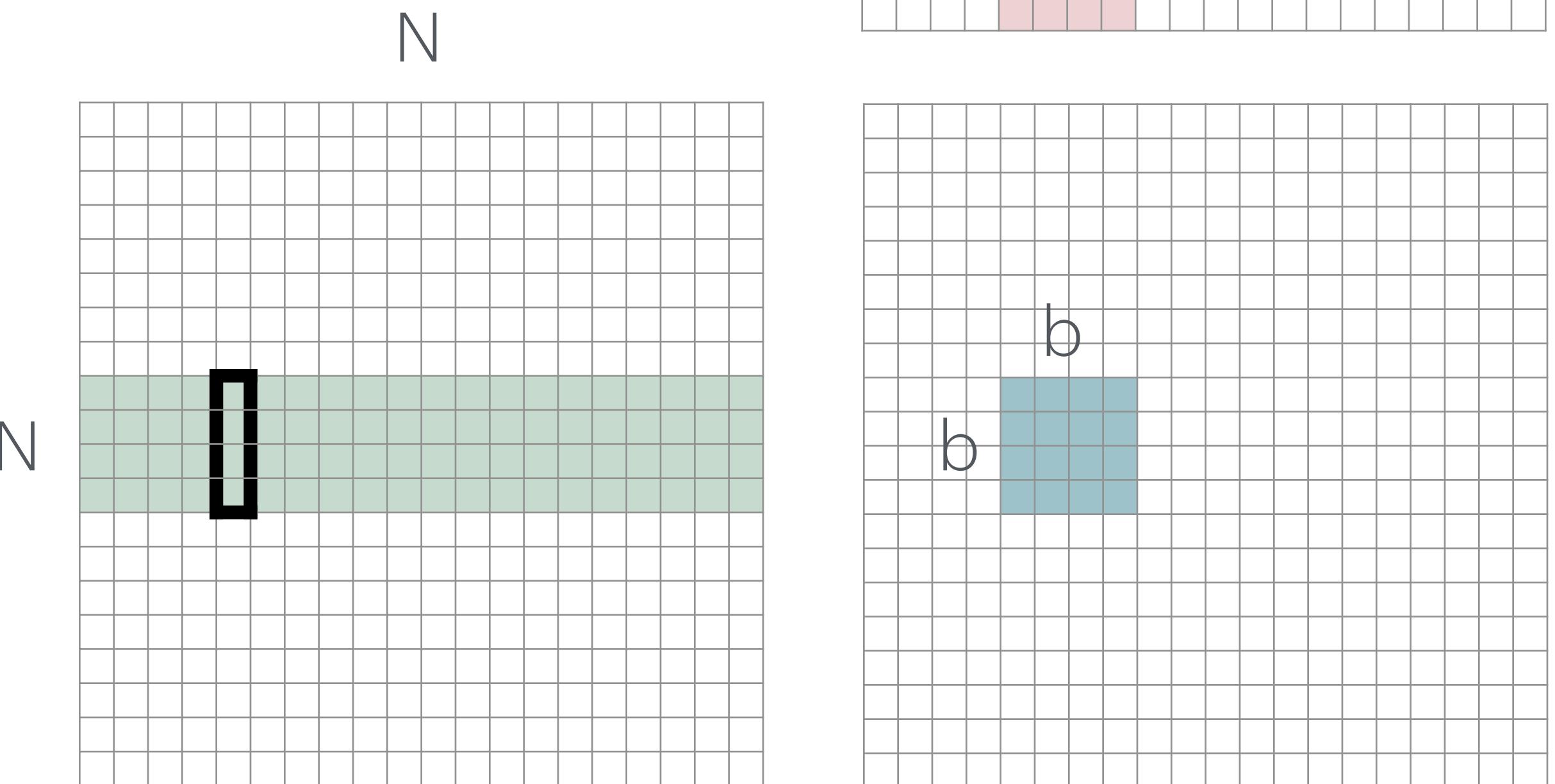
- Number of memory reads  $\frac{2N^3}{b}$



# Why is bfloat16 faster

Case study: matmul

- Each read is half size
  - $2 \times$  faster
  - Block size  $b^2$  can be  $2 \times$  larger
    - $\sqrt{2} \times$  faster
  - In total  $2.82 \times$  faster



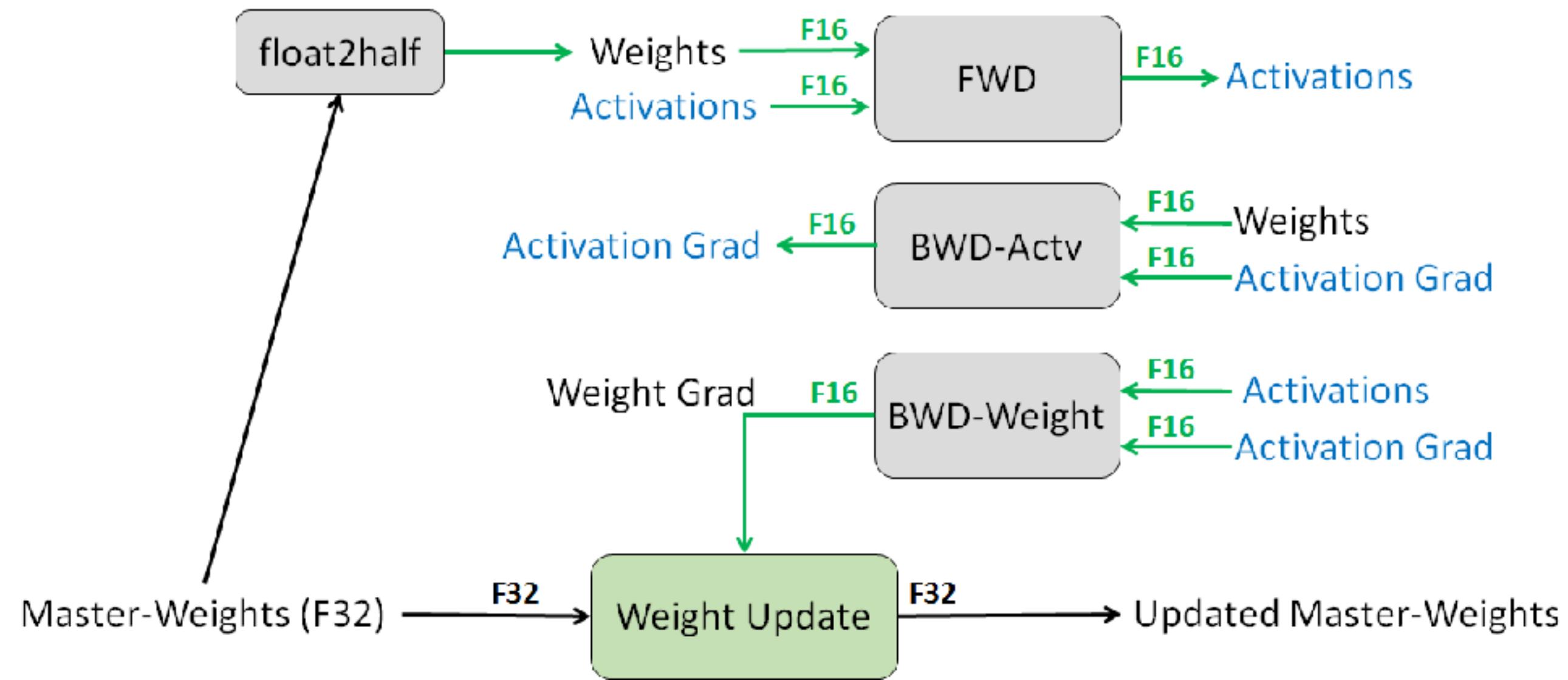
# Float32 vs (b)float16

- (B)float16 uses **half** the memory
- (B)float16 can be more than twice as fast
  - Most operations are memory bound
  - Some operations have super-linear memory access patterns

	V100 SXM	A100 SXM	H100 SXM
TF32 FLOPs Tensor Core	N/A	156T	494.7T
FP16 FLOPs Tensor Core	125T	312T	989.4T

# Training with BF16

- Original paper
  - Weights in fp32
  - Forward/backward in fp16/bf16
- Variants (llama3.1)
  - Weights in bf16
  - Gradient accumulation in bf16, but can be unstable

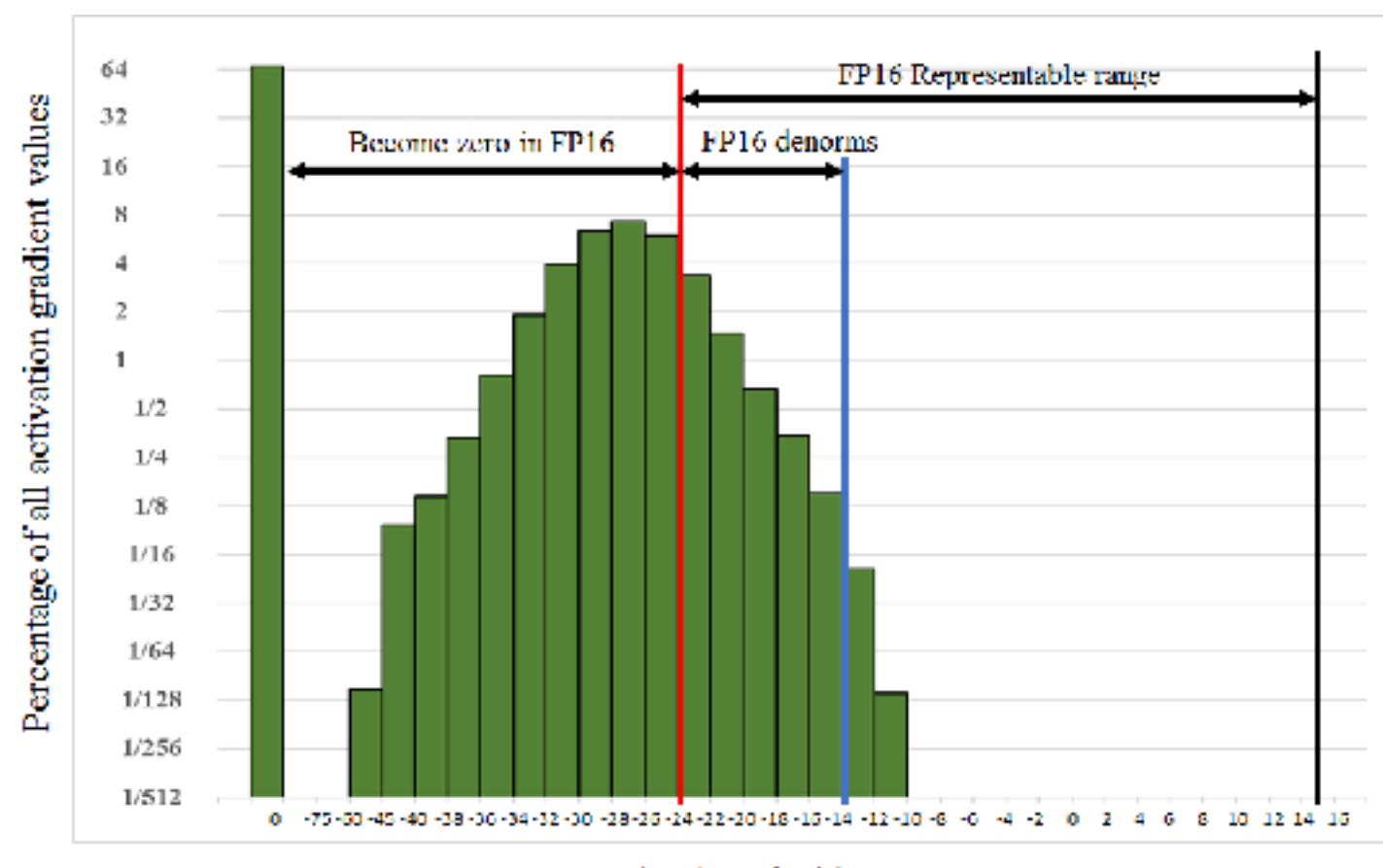


```
for epoch in range(...):
    for input, target in zip(data, targets):
        with torch.autocast(device_type=device, dtype=torch.bfloat16):
            output = net(input)
            loss = loss_fn(output, target)

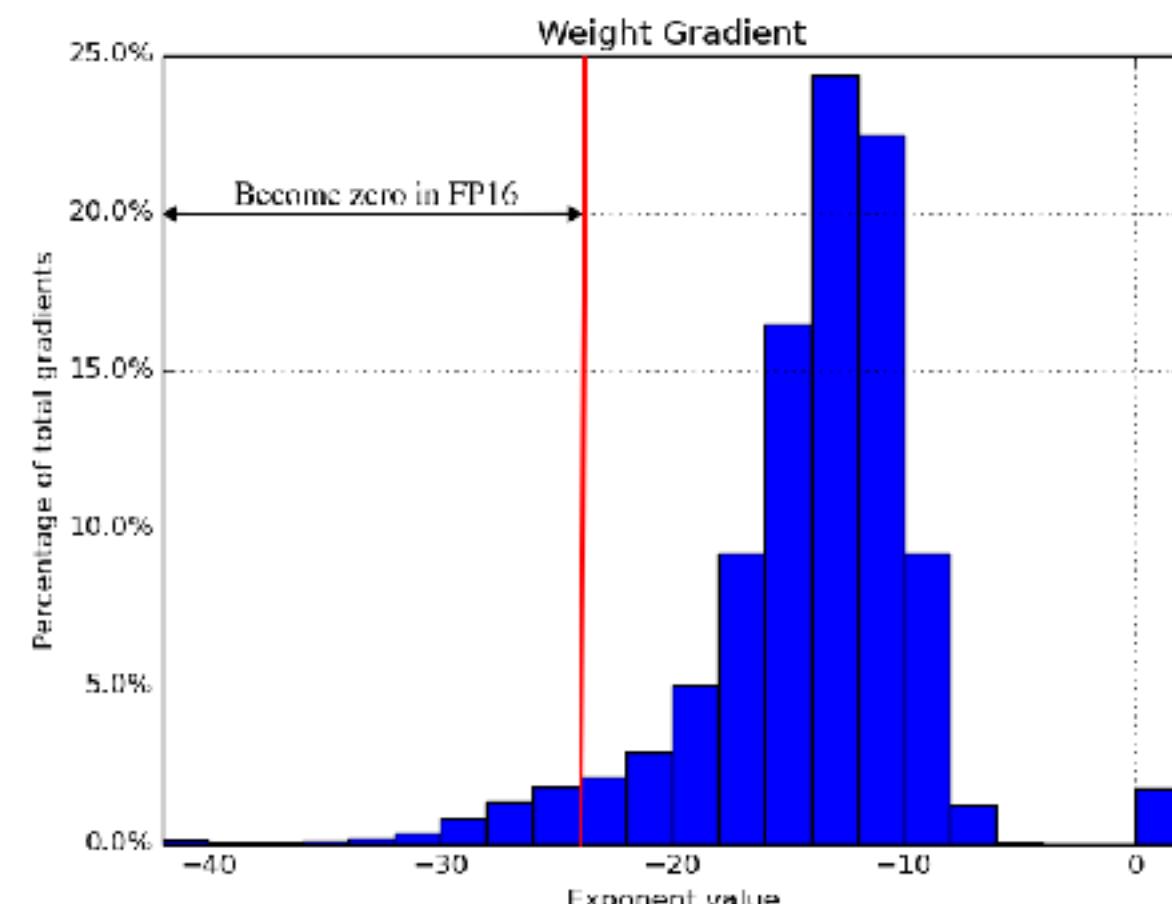
        opt.zero_grad()
        loss.backward()
        opt.step()
```

# Training with BF16

- Issue: Loss of precision (underflows)
- Solution: Gradient Scaling
  - Multiple loss by a large value (i.e.  $2^{16}$ )
  - If overflow (inf or NaN)
    - ignore gradient (set to 0)
    - Lower gradient scale



Multibox SSD network



Mandarin speech recognition

```
scaler = torch.cuda.amp.GradScaler()

for epoch in range(...):
    for input, target in zip(data, targets):
        with torch.autocast(device_type=device, dtype=torch.bfloat16):
            output = net(input)
            loss = loss_fn(output, target)

            opt.zero_grad()
            scaler.scale(loss).backward()
            scaler.step(opt)
            scaler.update()
```

# Training with BF16

- Issue: Loss of precision (underflows) in normalizations
- Solution: Keep normalization in float32
  - Use `torch.autocast`
  - Do not use `model.to(torch.float16)`

```
scaler = torch.cuda.amp.GradScaler()

for epoch in range(...):
    for input, target in zip(data, targets):
        with torch.autocast(device_type=device, dtype=torch.bfloat16):
            output = net(input)
            loss = loss_fn(output, target)

        opt.zero_grad()
        scaler.scale(loss).backward()
        scaler.step(opt)
        scaler.update()
```

# Adam in (b)float16

- First momentum: possible
- Second momentum: Unstable, Not recommended [1]
- Specialized very low-bit Adam implementations exist [2]

[1] Zhai, et al. Scaling Vision Transformers. 2021

[2] Tang, et al. 1-bit Adam: Communication Efficient Large-Scale Training with Adam's Convergence Speed, 2021

# Training large models

## Memory requirements

- Mixed precision
  - Model parameters:  $N$
  - Weights:  $N$  floats
  - Gradients:  $N$  bfloat16
  - Momentum:  $N$  bfloat16
  - 2nd momentum (ADAM):  $N$  floats
  - $12N$  bytes without counting activations



Training is faster

# References

- [1] Micikevicius, et al. Mixed Precision Training. 2017 ([link](#))
- [2] Llama Team, The Llama 3 Herd of Models. 2024 ([link](#))
- [3] Zhai, et al. Scaling Vision Transformers. 2021 ([link](#))
- [4] Tang, et al. 1-bit Adam: Communication Efficient Large-Scale Training with Adam's Convergence Speed, 2021 ([link](#))