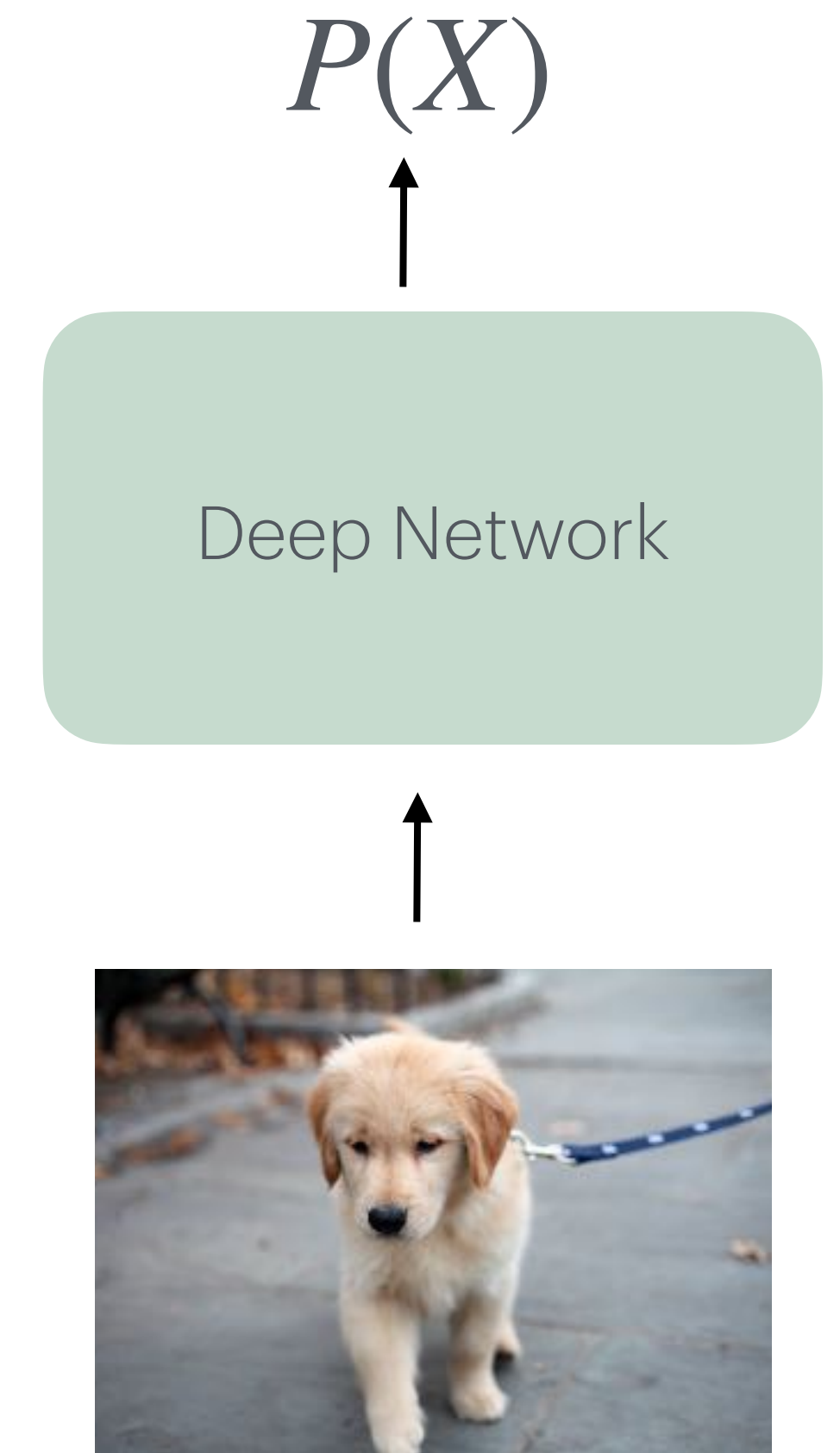
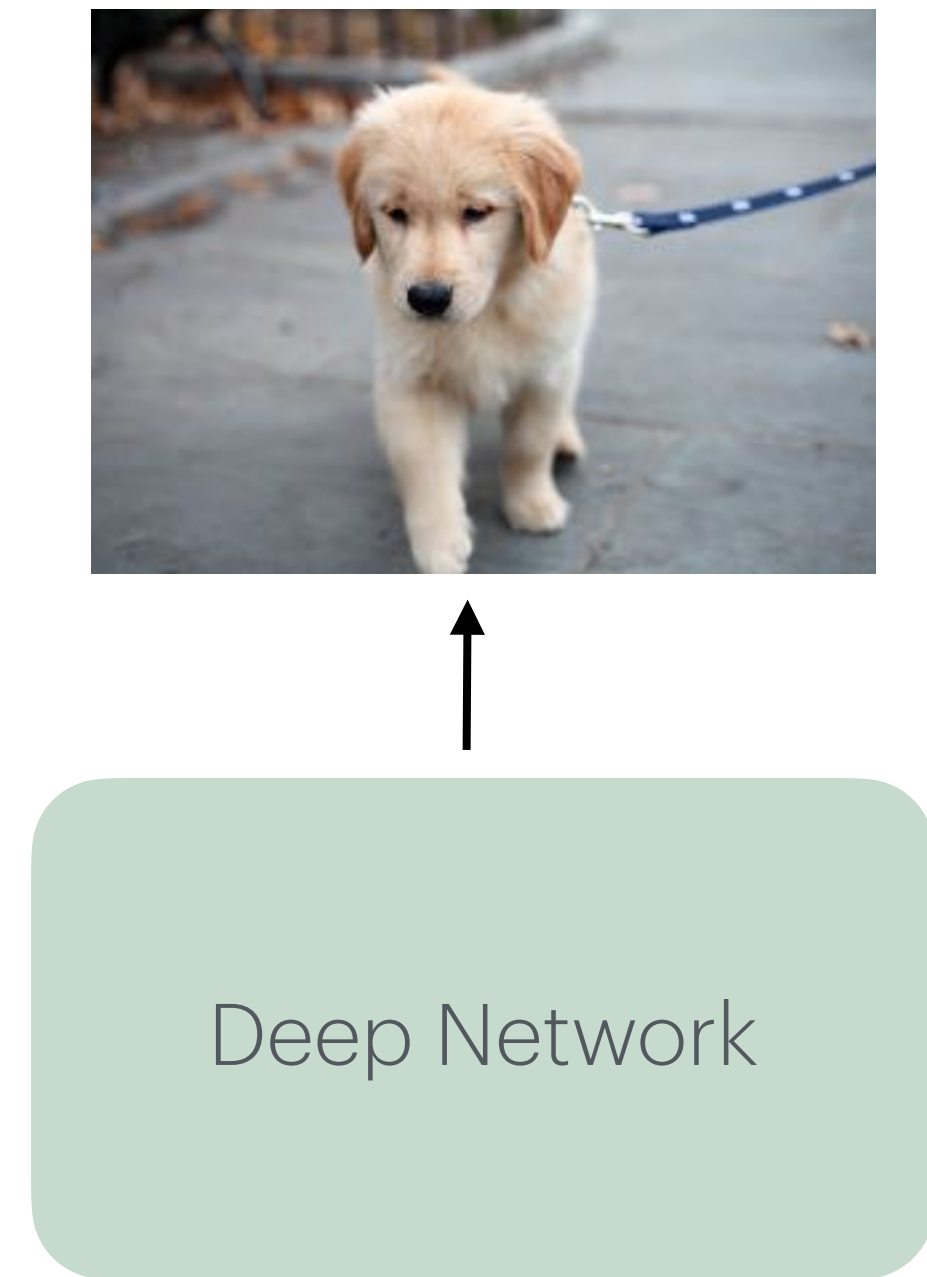


Generative Adversarial Networks

Generative models

- Two tasks of a generative model $P(X)$
 - Sampling: $x \sim P(X)$
 - Density estimation: $P(X = x)$



Generative modeling is hard

- Density estimation $P(X = x)$
 - How to ensure $\sum_x P(x) = 1$ for all x
 - Impossible to compute (in general)
- Sampling $x \sim P(X)$
 - What is the input to the network?



Deep Network

$P(X)$



Deep Network

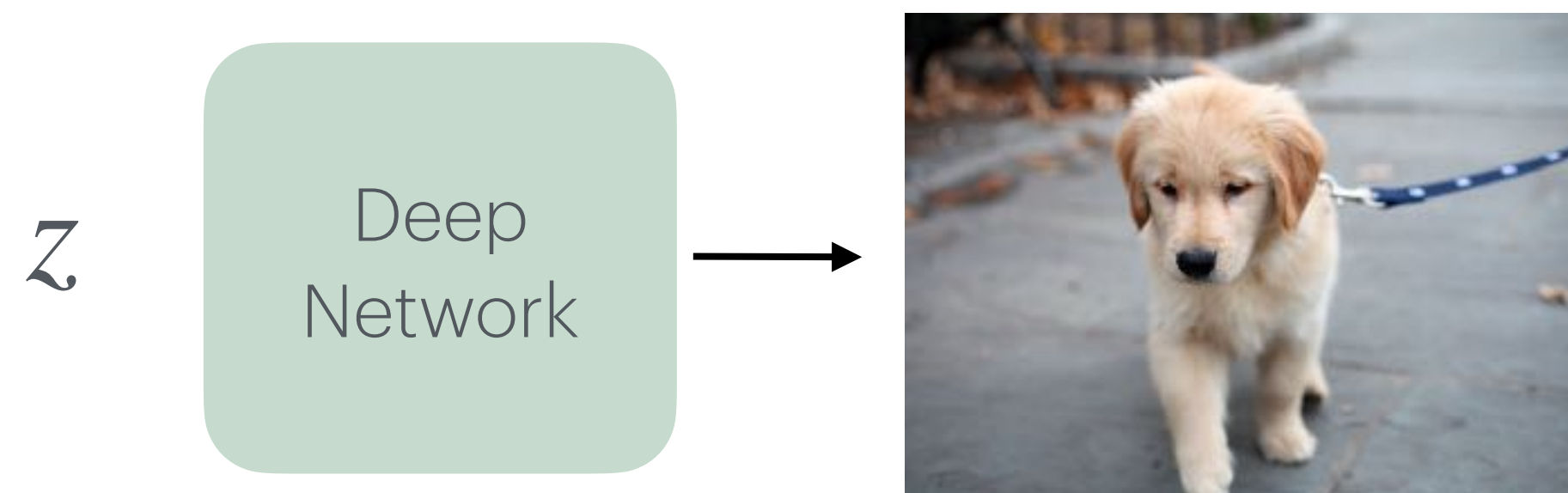


Generative models

Two kinds of models

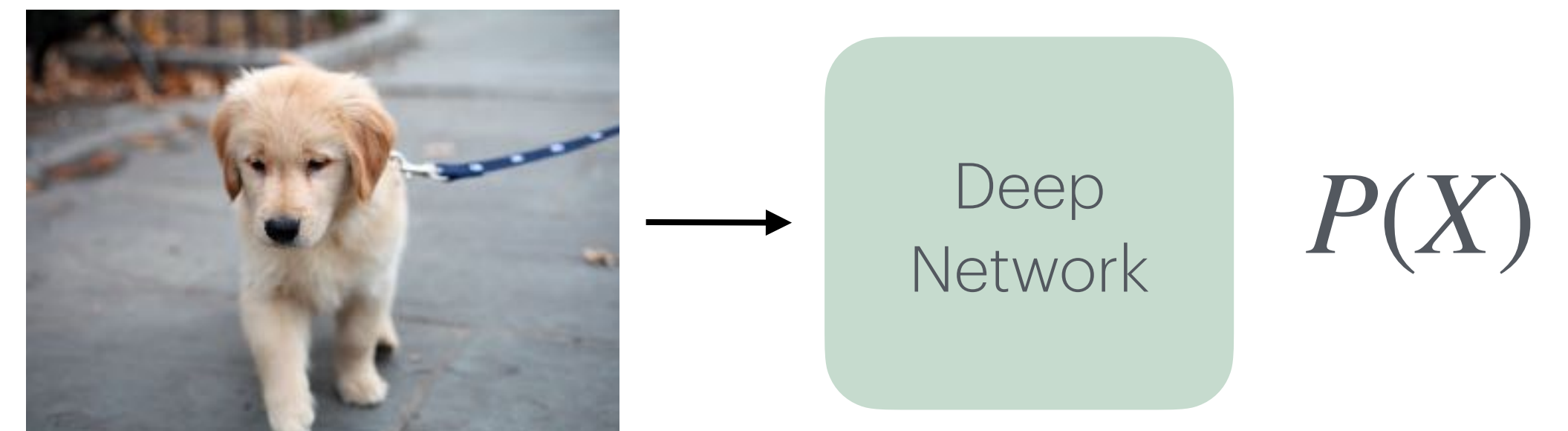
Sampling based $x \sim P(X)$

- Sample $z \sim P(Z)$
- Learn transformation
 - $P(x|z)$ or $f: z \rightarrow x$



Density estimation based $P(X)$

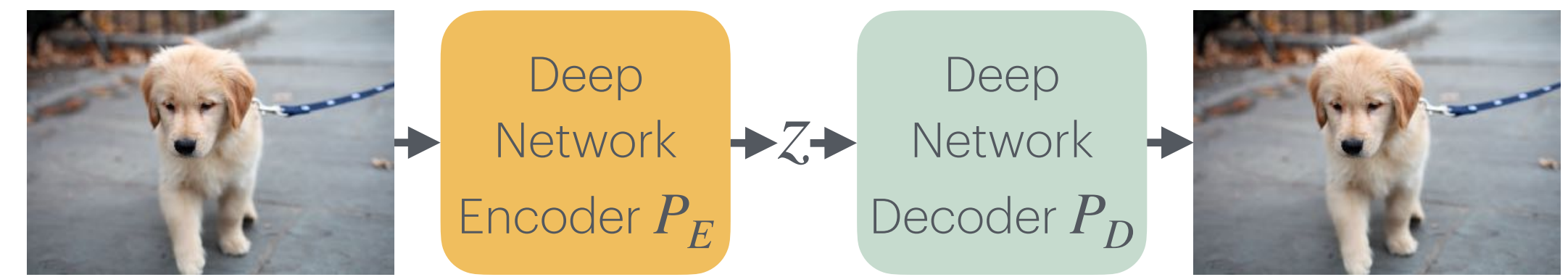
- Learn special form of $P(X)$
- Model specific sampling / generation



Variational auto-encoder

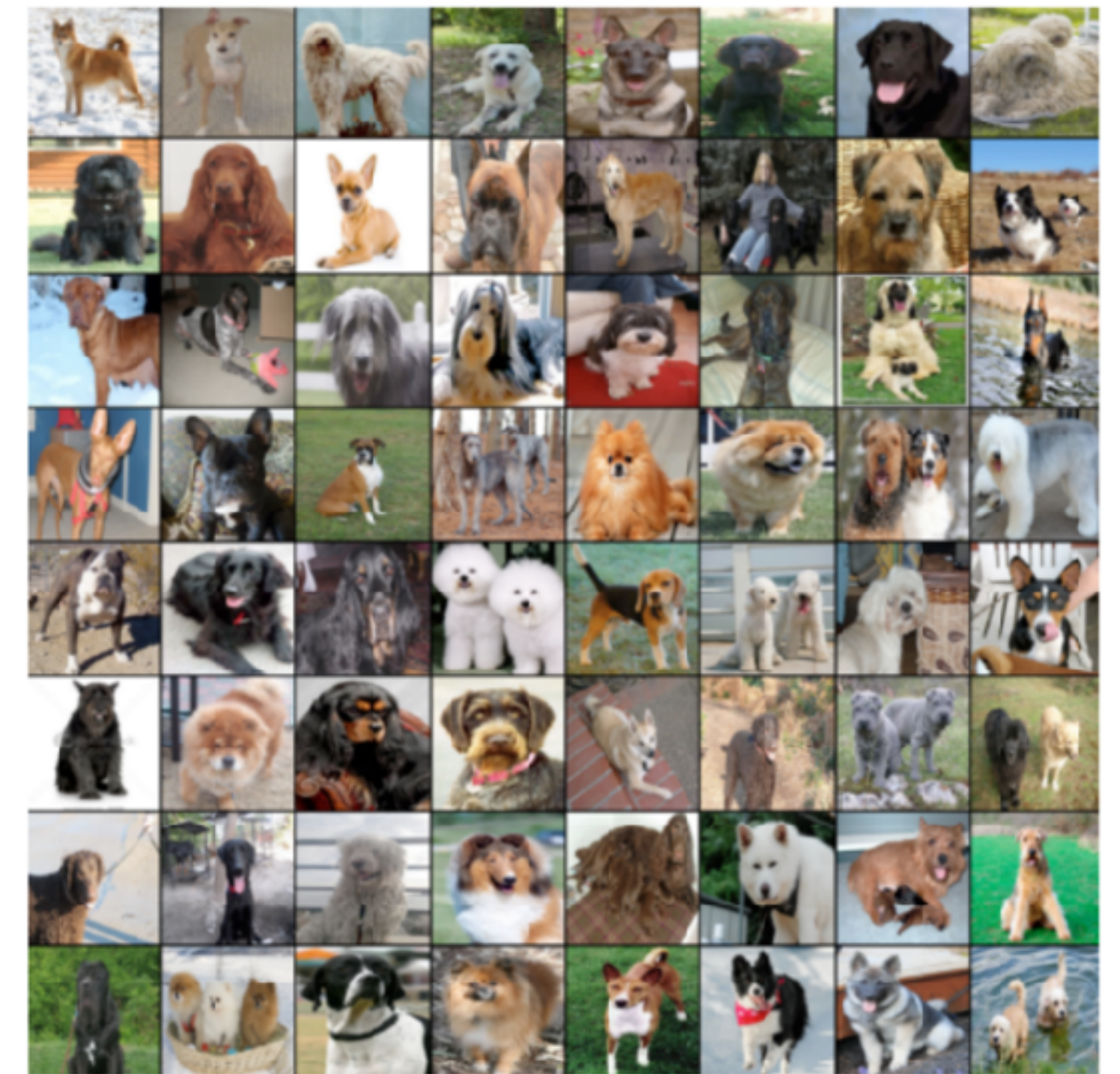
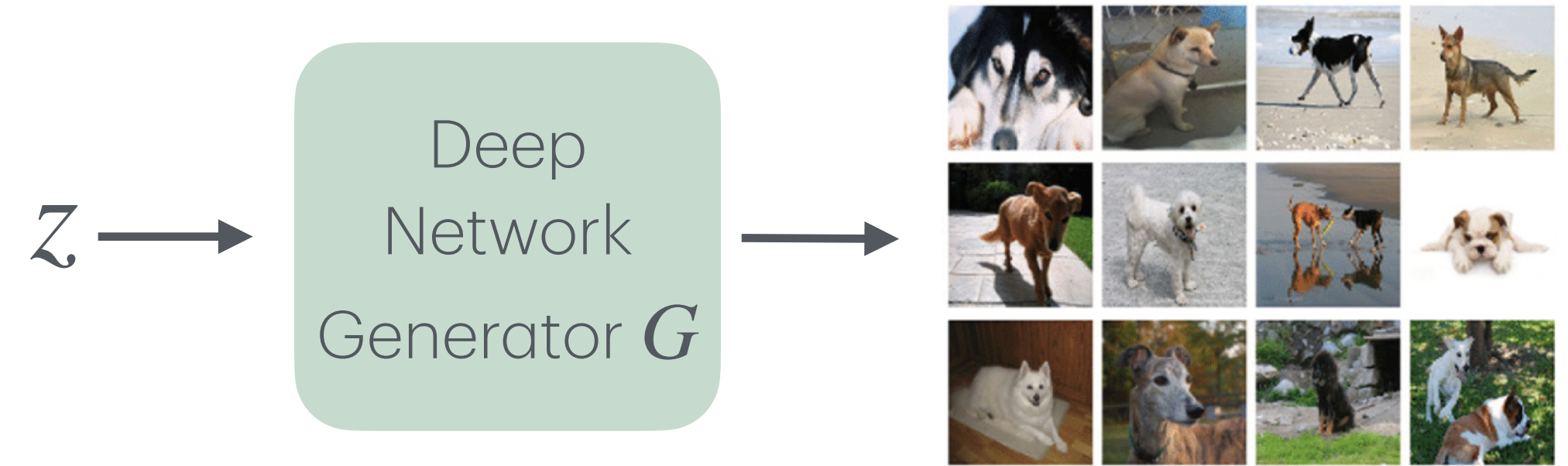
A “probabilistic” auto-encoder

- Learn a model of $P(x) = P_D(x | z)P(z)$ with $P(z) = \mathcal{N}(z; 0, 1)$
- Approximate $Q \approx P_E$
- Maximize $P(x)$ of data



Generative Adversarial Networks

- Learn a model of $P(x)$
 - Sampling distribution (model)
 - $x = G(z); z \sim \mathcal{N}(0,1)$
 - Match data distribution
 - $x \sim \mathcal{D}$

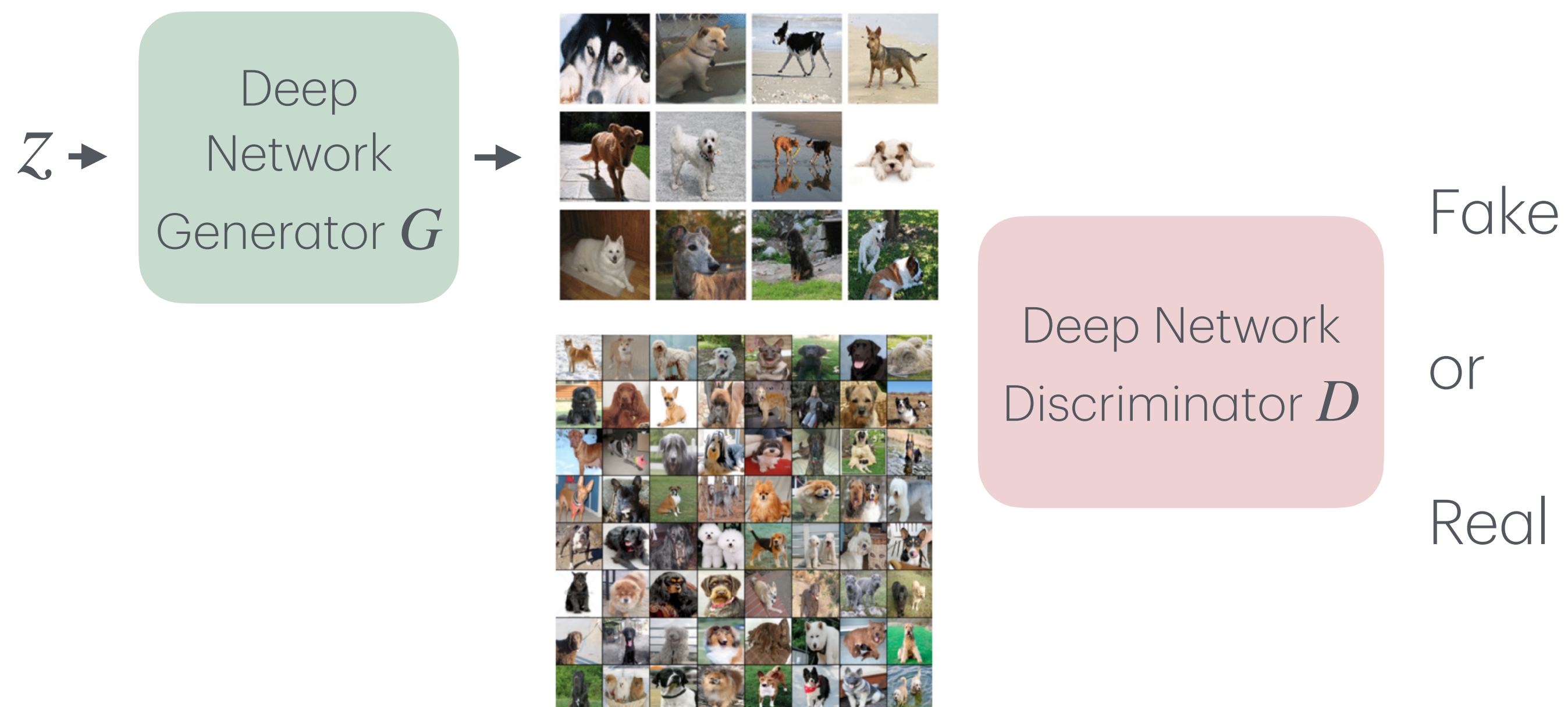


Columbia University Dogs dataset [3]

[2] Generative Adversarial Networks, Goodfellow et al., NeurIPS 2014

[3] Dog breed classification using part localization, Liu et al., ECCV 2012

Generative Adversarial Networks



- Objective: Match sampling distributions as two player game

- Payer 1: Generator G

- Generate images from noise

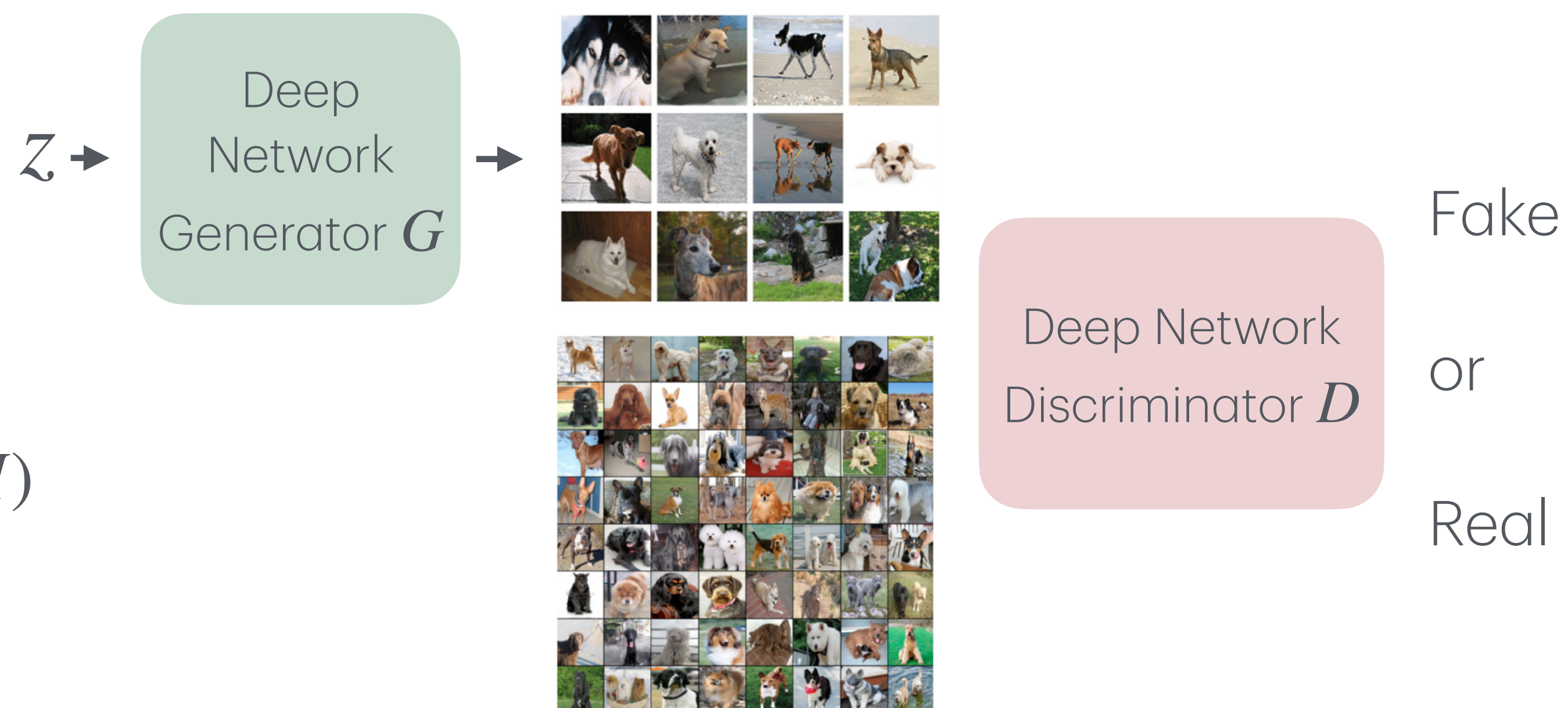
- Payer 2: Discriminator D

- Tell real from fake images

$$\min_G \max_D E_{x \sim G} [\log D(x)] + E_{x \sim \mathcal{D}} [\log(1 - D(x))] =$$

$$\min_G \max_D E_{z \sim \mathcal{N}} [\log D(G(x))] + E_{x \sim \mathcal{D}} [\log(1 - D(x))]$$

Generative Adversarial Networks



- Minimizes Jensen-Shannon-Divergence

$$JSD(P, Q) = \max_M D_{KL}(P | M) + D_{KL}(Q | M)$$

$$\min_G \max_D E_{x \sim G} [\log D(x)] + E_{x \sim \mathcal{D}} [\log(1 - D(x))] =$$

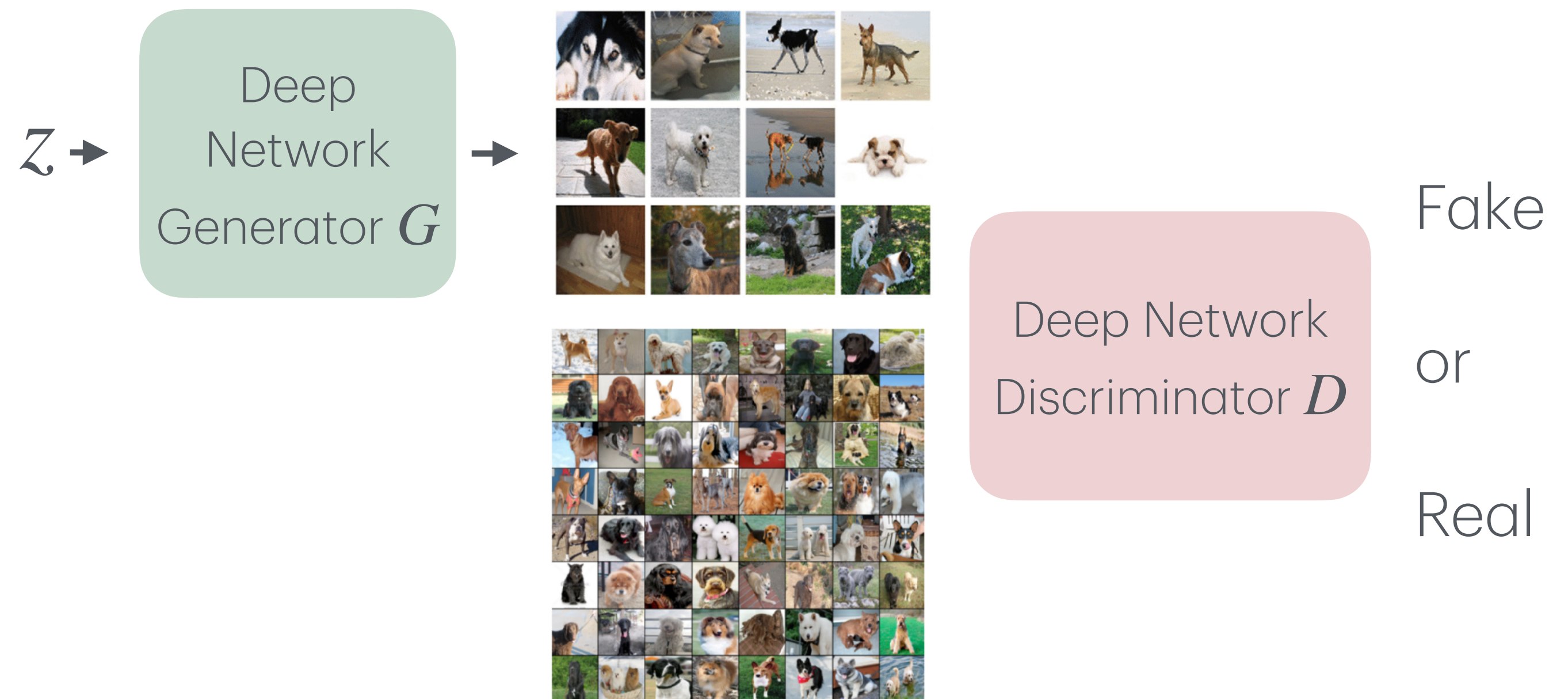
$$\min_G \max_D E_{z \sim \mathcal{N}} [\log D(G(z))] + E_{x \sim \mathcal{D}} [\log(1 - D(x))]$$

Generative Adversarial Networks

Optimization

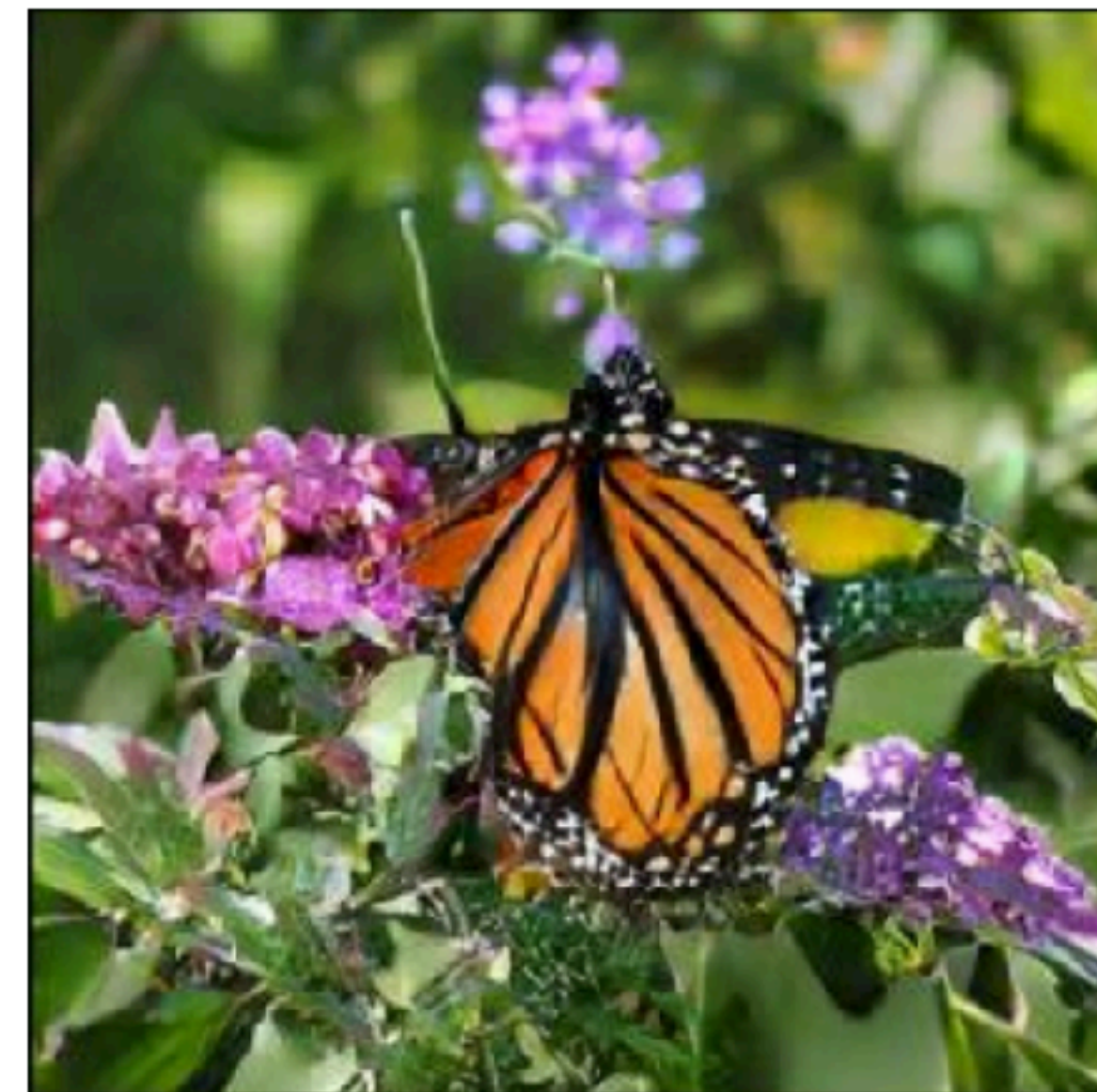
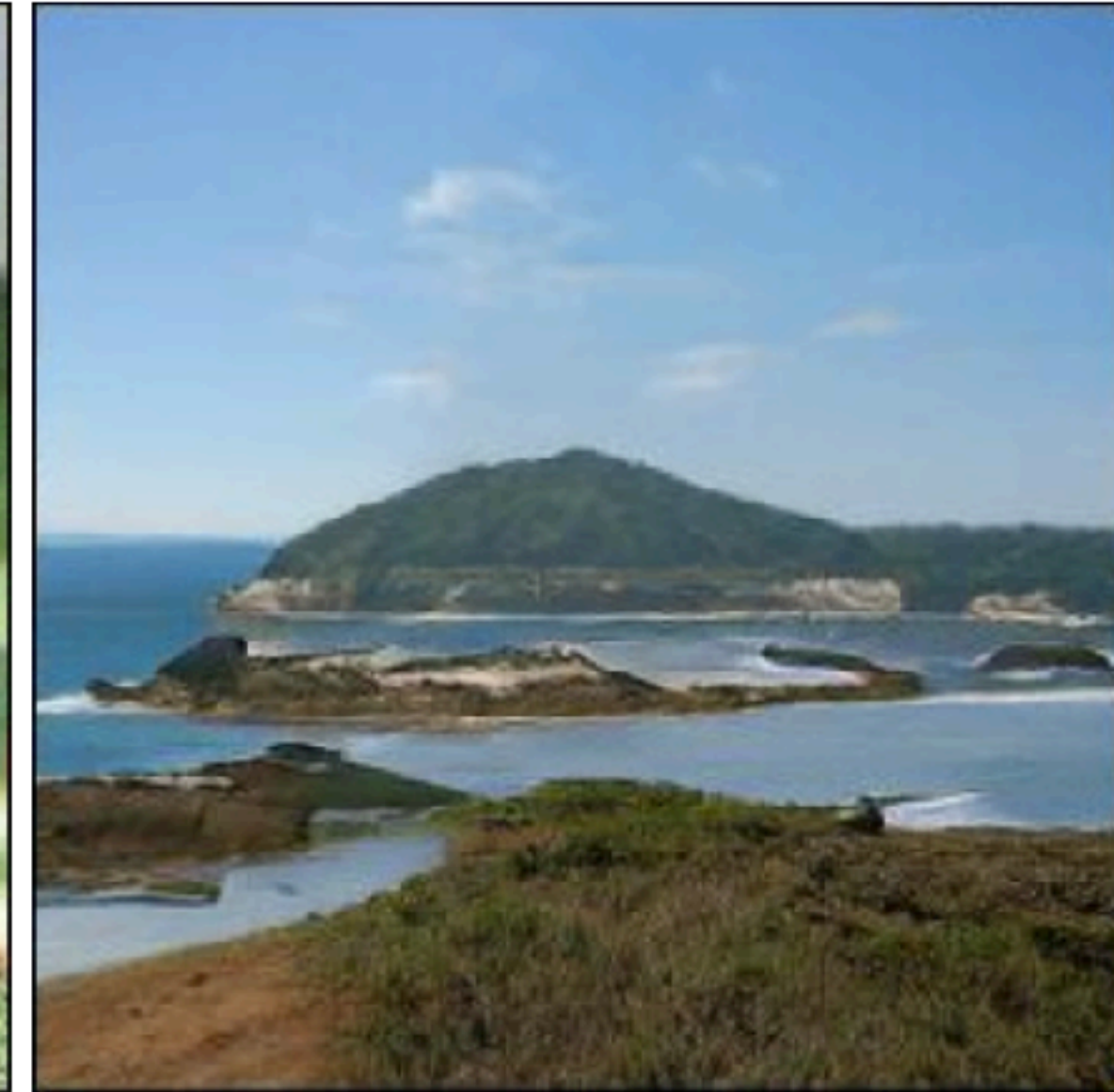
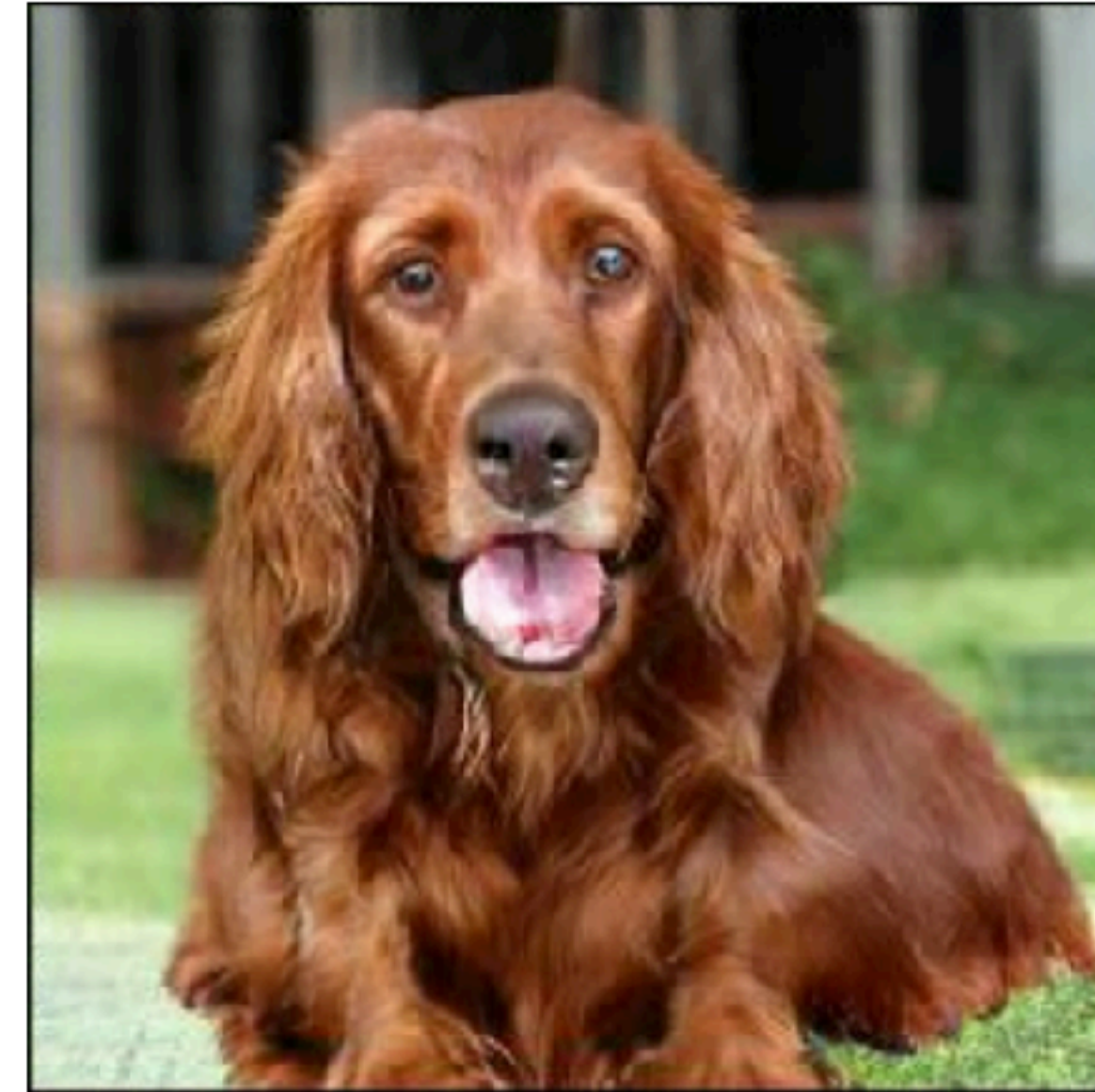
$$\min_G \max_D E_{z \sim \mathcal{N}} [\log D(G(x))] + E_{x \sim \mathcal{D}} [\log(1 - D(x))]$$

- Hard to optimize
 - Mathematically correct
 - For every step in G , run a full optimizer pass for D
 - In practice
 - One step G , one step D
 - Pray for convergence



GANs work!

- Sampling is easy
- Learned pixel-distance
 - No blurriness
- Loss on distributions
 - Requires a few tricks



Application

Super resolution

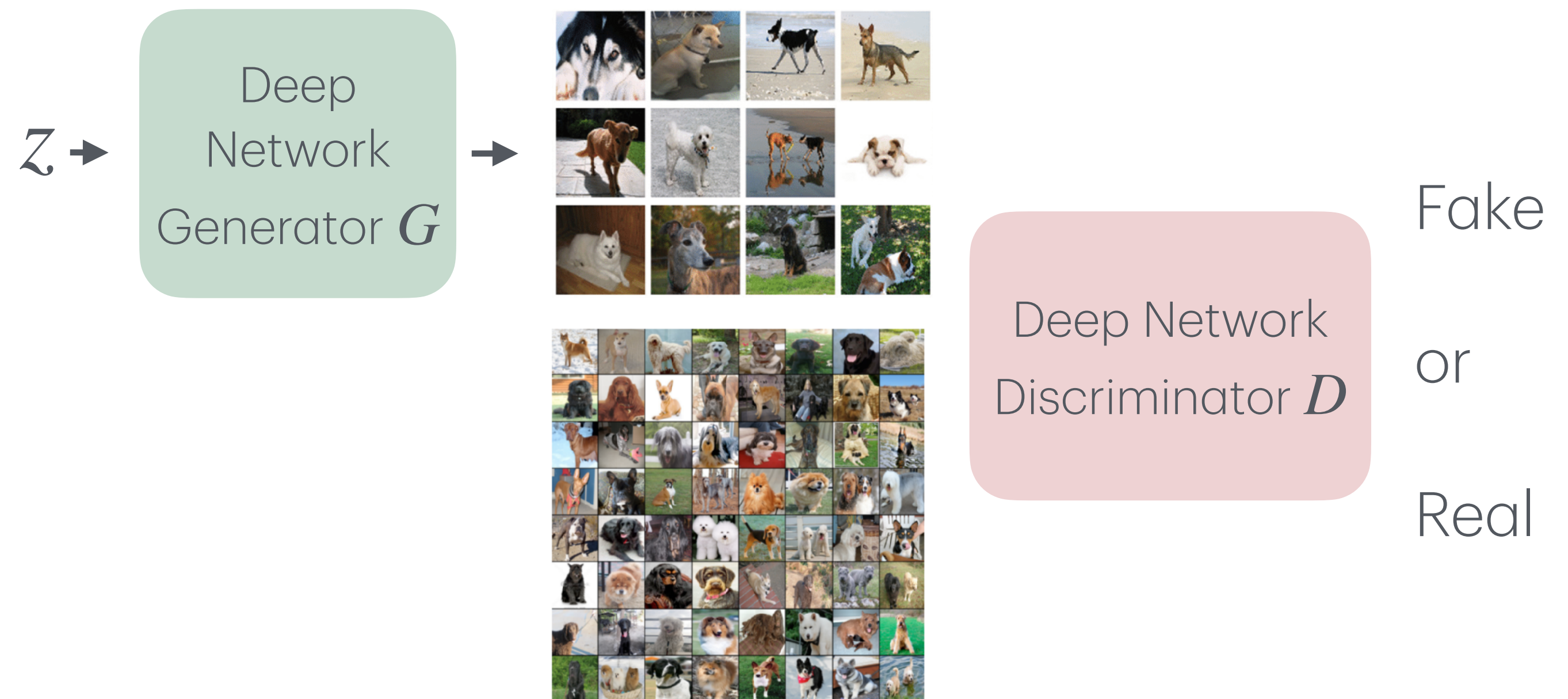
- Supervised training task
 - Take high-res image, downsample
- GANs as loss
 - Leads to sharper reconstruction than just reconstruction



Deep Net



Generative Adversarial Networks



- Two player game
 - Generator: Transform noise into images
 - Discriminator: Tell difference between real and generated images
 - Leads to sharp images
 - Used in conditioned generation

Generative models

Two kinds of models

Sampling based $x \sim P(X)$

- Sample $z \sim P(Z)$
- Learn transformation
- $P(x|z)$ or $f: z \rightarrow x$

z

Deep
Network



Density estimation based $P(X)$

- Learn special form of $P(X)$
- Model specific sampling / generation



Deep
Network

$P(X)$

References

- [1] Auto-Encoding Variational Bayes, Kingma et al., ICLR 2014 ([link](#))
- [2] Generative Adversarial Networks, Goodfellow et al., NeurIPS 2014 ([link](#))
- [3] Dog breed classification using part localization, Liu et al., ECCV 2012 ([link](#))
- [4] Large Scale GAN Training for High Fidelity Natural Image Synthesis, Brock et al., ICLR 2019 ([link](#))
- [5] Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network, Ledig et al., CVPR 2017 ([link](#))