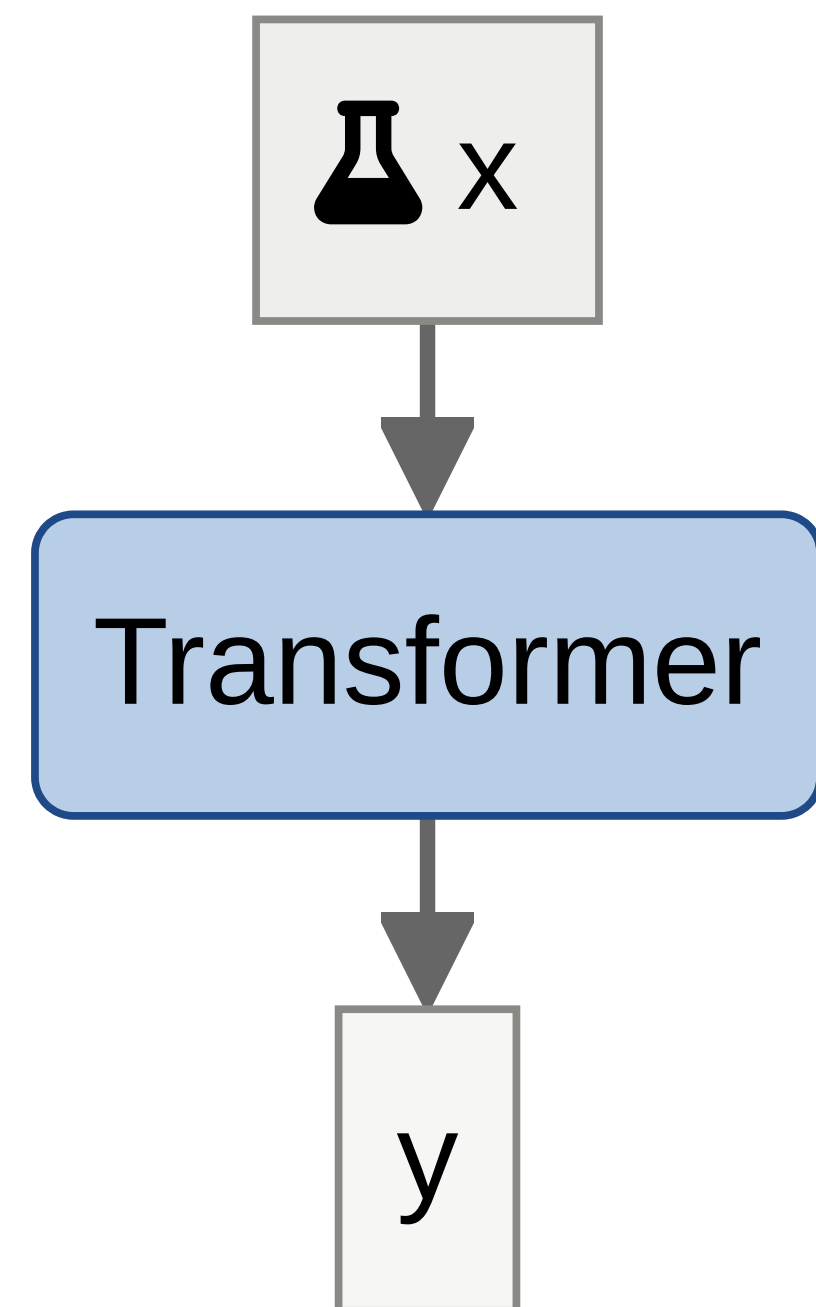


# Generative Models

# Recap

Model



Data



Optimization

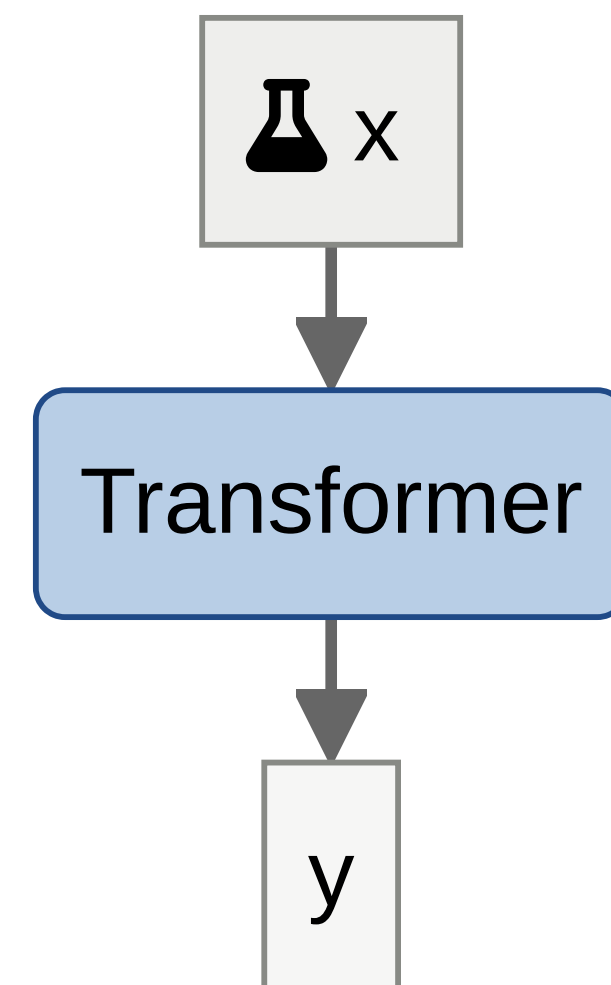
```
m = 0
for epoch in range(n):
    for (x, y) in dataset:
        J =  $\nabla l(\theta|x,y)$ 
        m = J + momentum * m
         $\theta = \theta - \epsilon * m.mT$ 
```

# Recap: How to train a network?

Collect Data



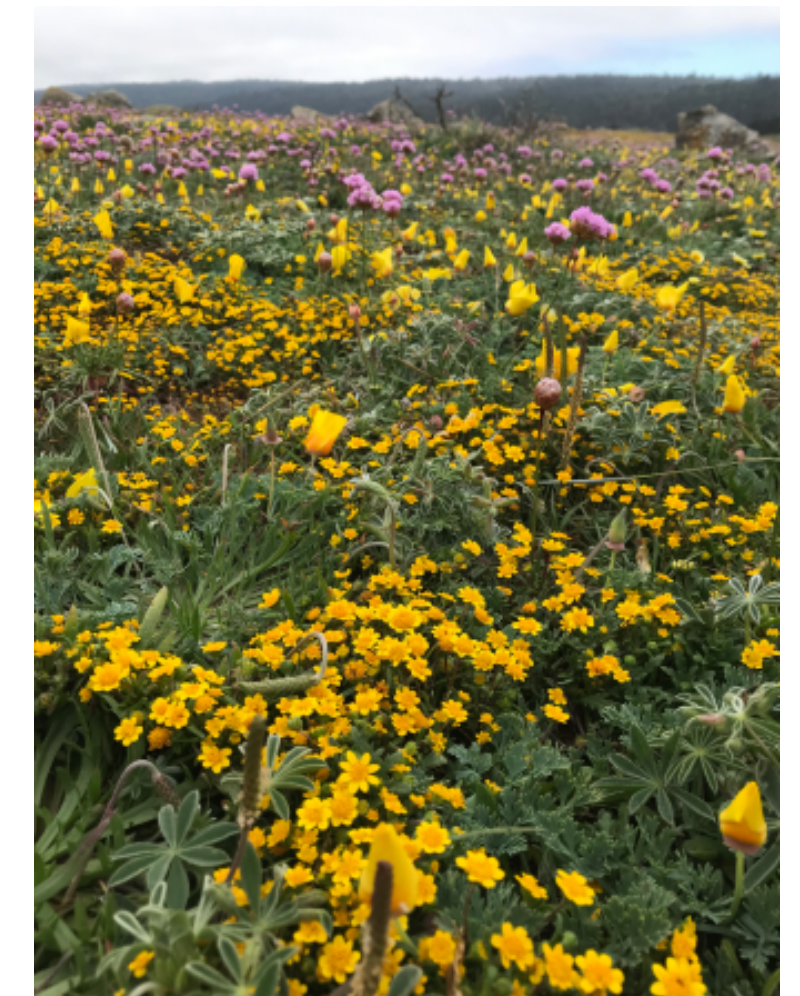
Design / download  
architecture



Train  
model



Apply model  
to real world



This never works !!!



# Recap: How to train a network?

Training is an iterative process

Step 2: **Training**

5-10% of work

Step 1: **Data curation**

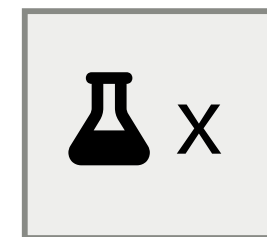
70-80% of work

Collect Data



Look at  
your data

Design / download  
architecture



Transformer

y

Train  
model



Apply model  
to real world



Step 3: **Testing**

15-20% of work



# Part I: Done

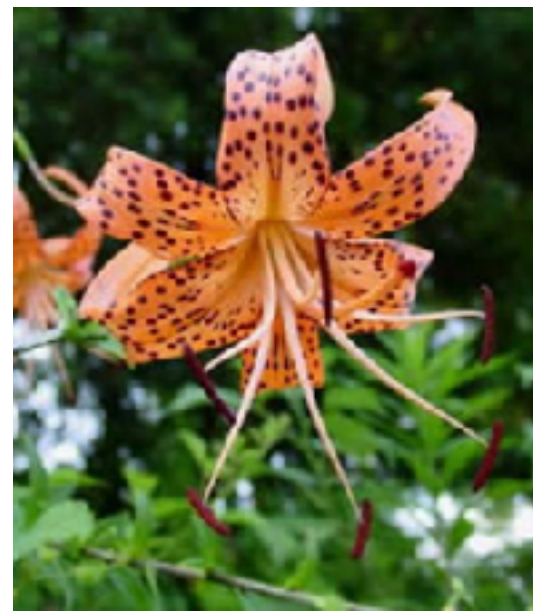
Data

$x_i, y_i$

...



pink primrose

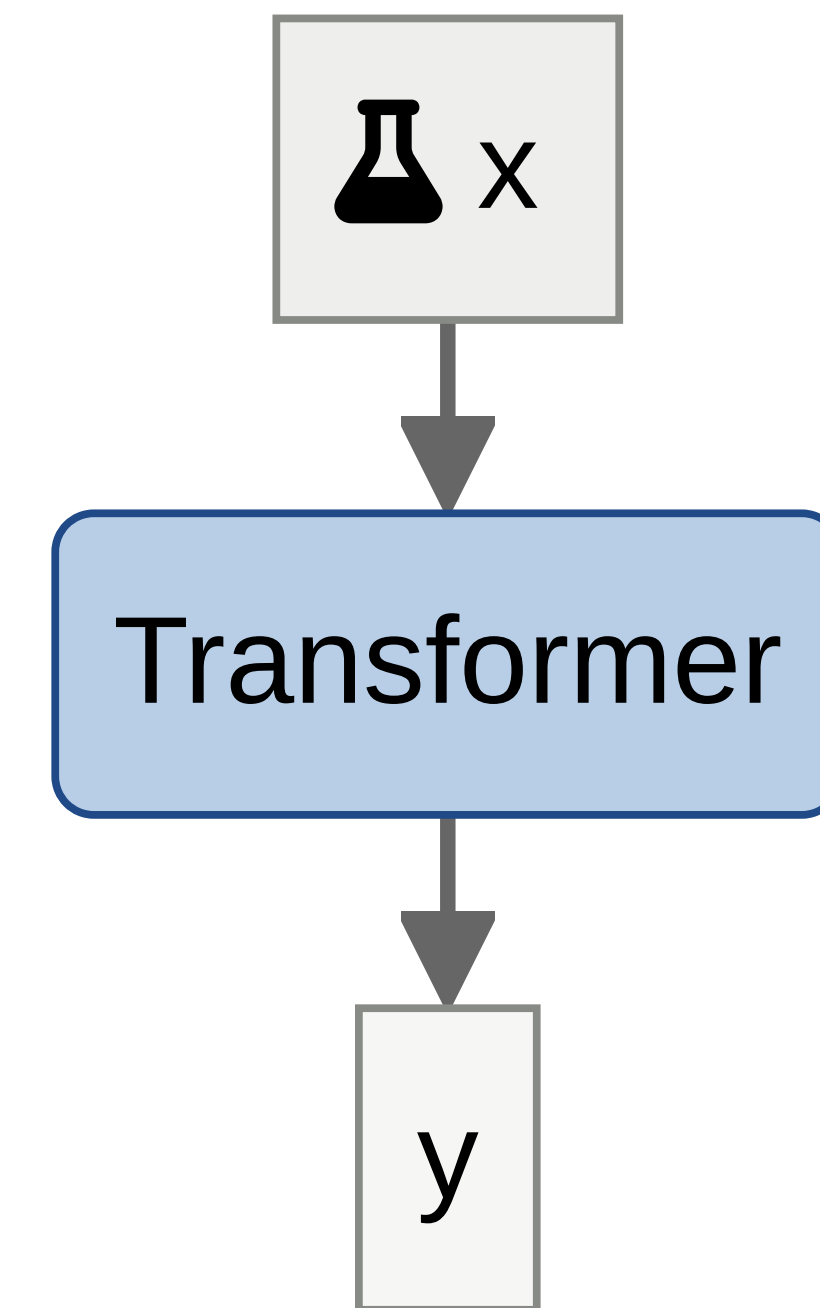


tiger lily

...

Train model

$f: x \rightarrow y$



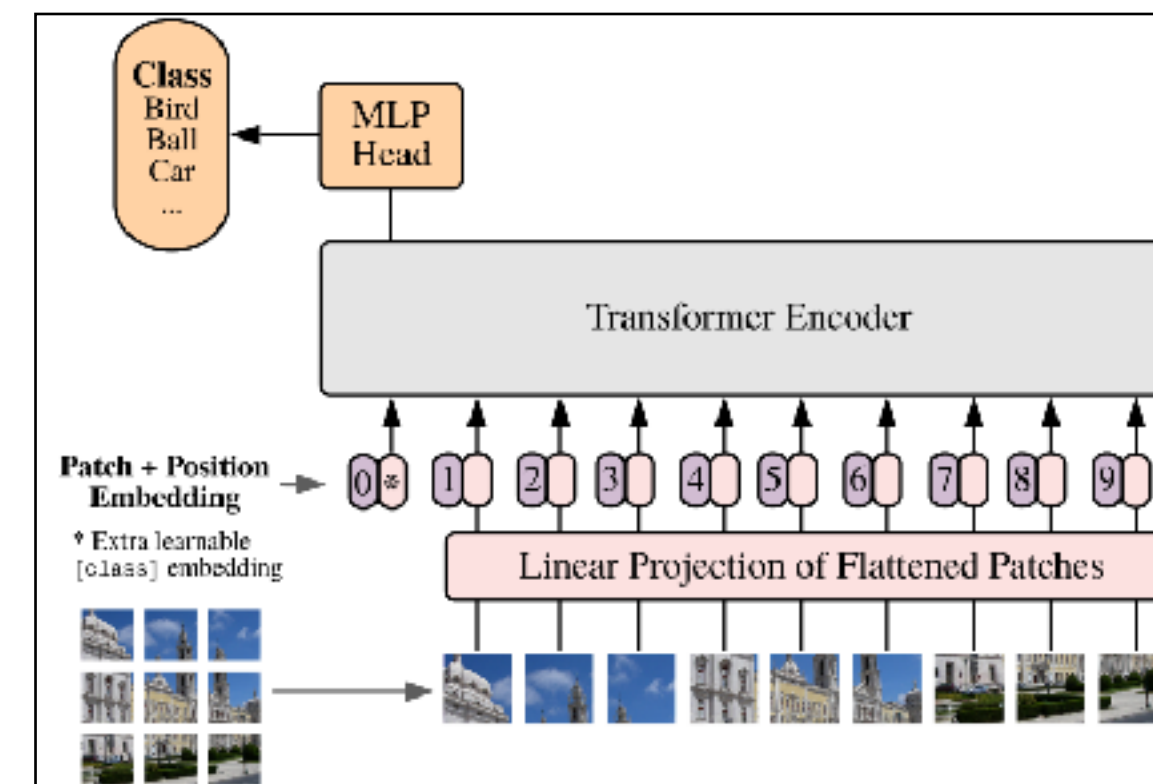
# Generative Models

Philipp Krähenbühl, UT Austin

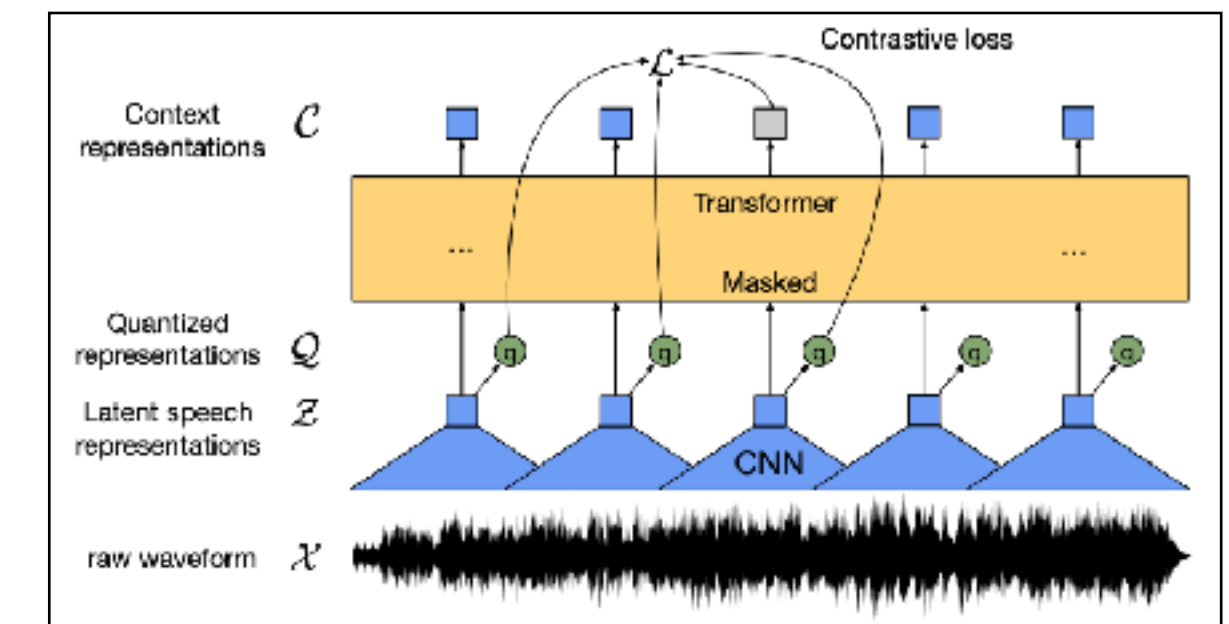


# Discriminative models

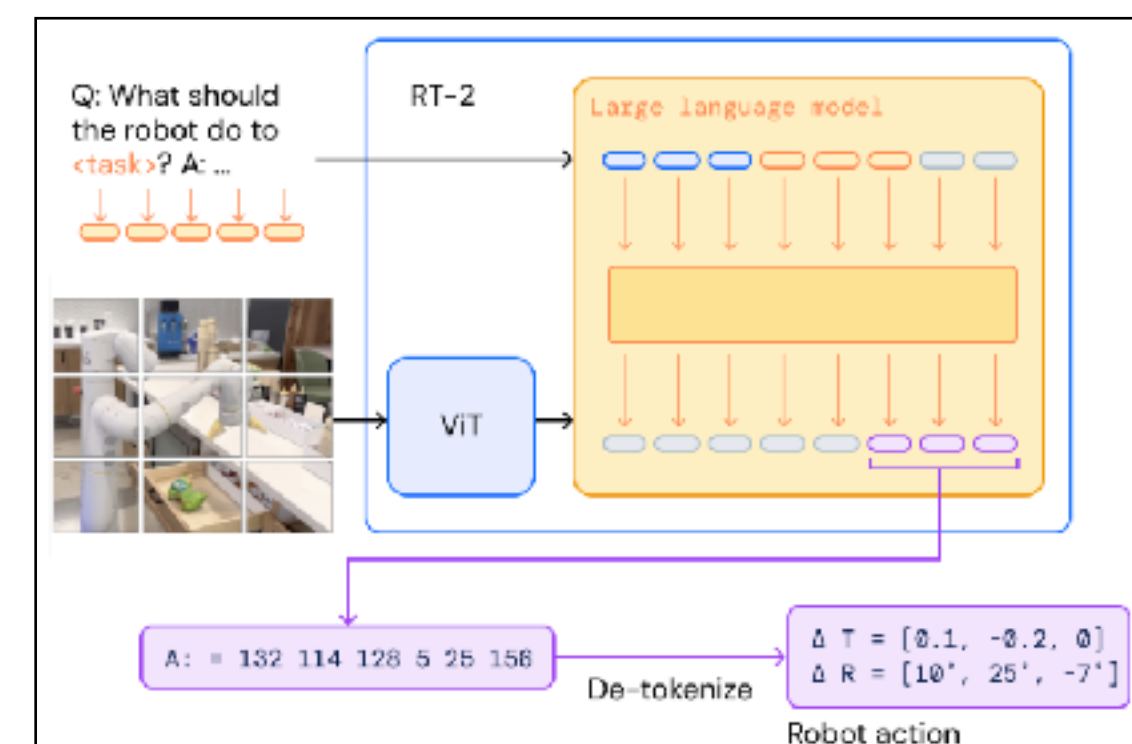
- Discriminative model:  $P(Y|X)$
- Examples:
  - Image/video recognition
  - Speech recognition
  - Control policies
  - Weather prediction
  - ...



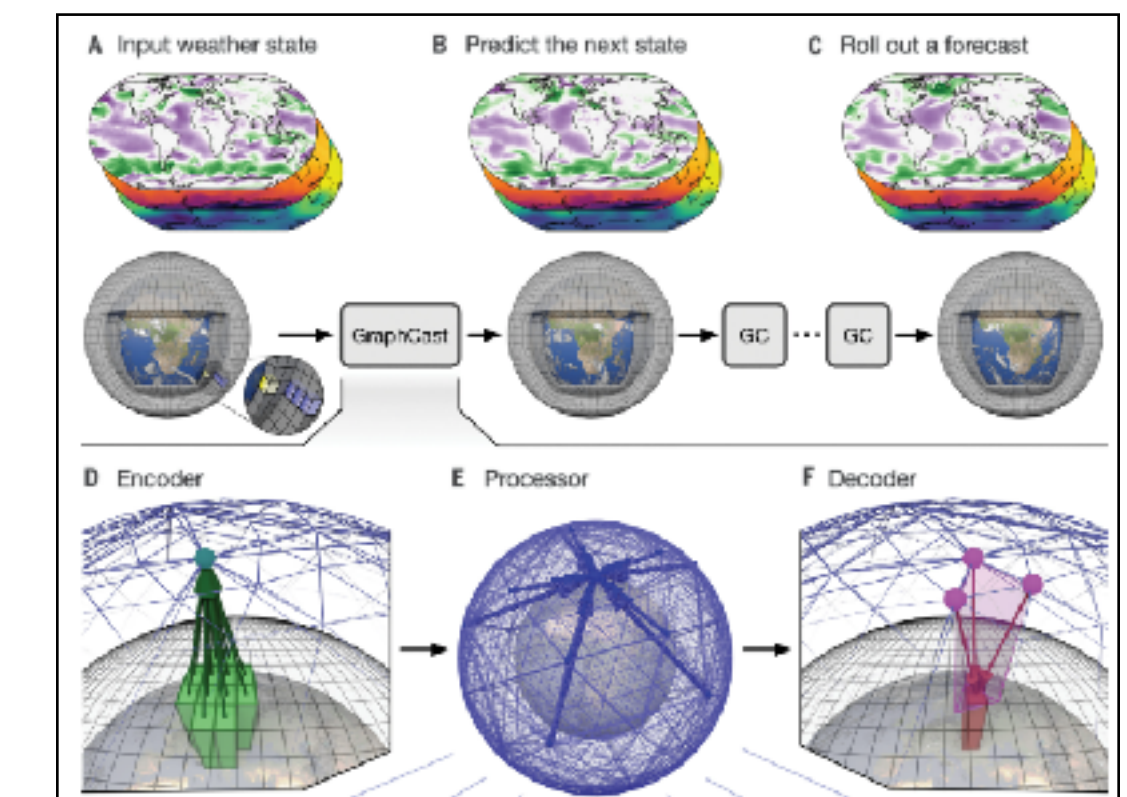
[1] Vision Transformer



[2] Wave2vec 2.0



[3] RT-2



[4] GraphCast

[1] Dosovitskiy, Alexey, et al. "An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale." International Conference on Learning Representations. 2020.

[2] Baevski, Alexei, et al. "wav2vec 2.0: A framework for self-supervised learning of speech representations." Advances in neural information processing systems 33 (2020): 12449-12460.

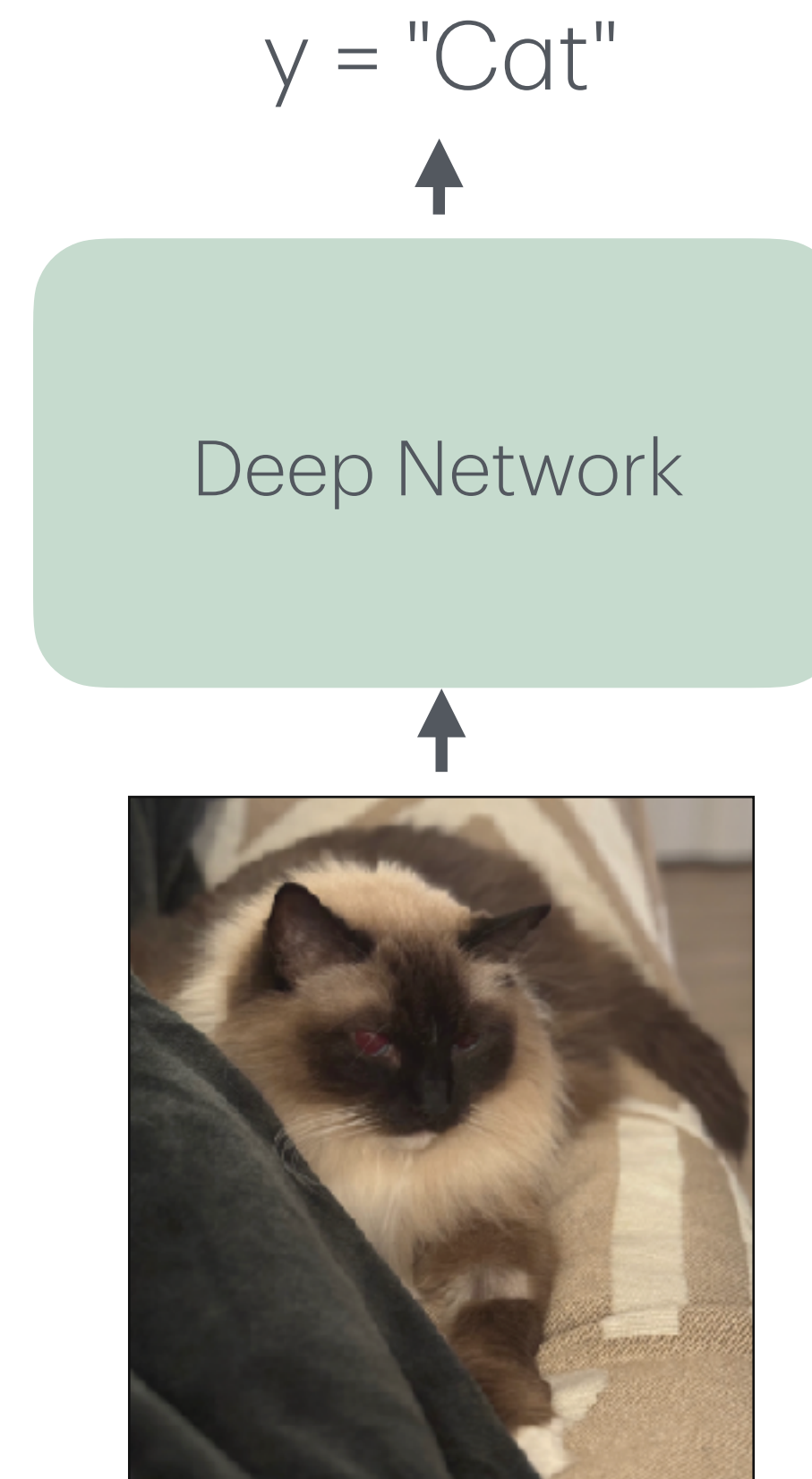
[3] Brohan, Anthony, et al. "Rt-2: Vision-language-action models transfer web knowledge to robotic control." arXiv preprint arXiv:2307.15818 (2023).

[4] Remi Lam et al. ,Learning skillful medium-range global weather forecasting.Science382,1416-1421(2023).



# Discriminative models in deep learning

- Discriminative model:  $P(Y|X)$
- Examples:
  - Image/video recognition
  - Speech recognition
  - Control policies
  - Weather prediction
  - ...



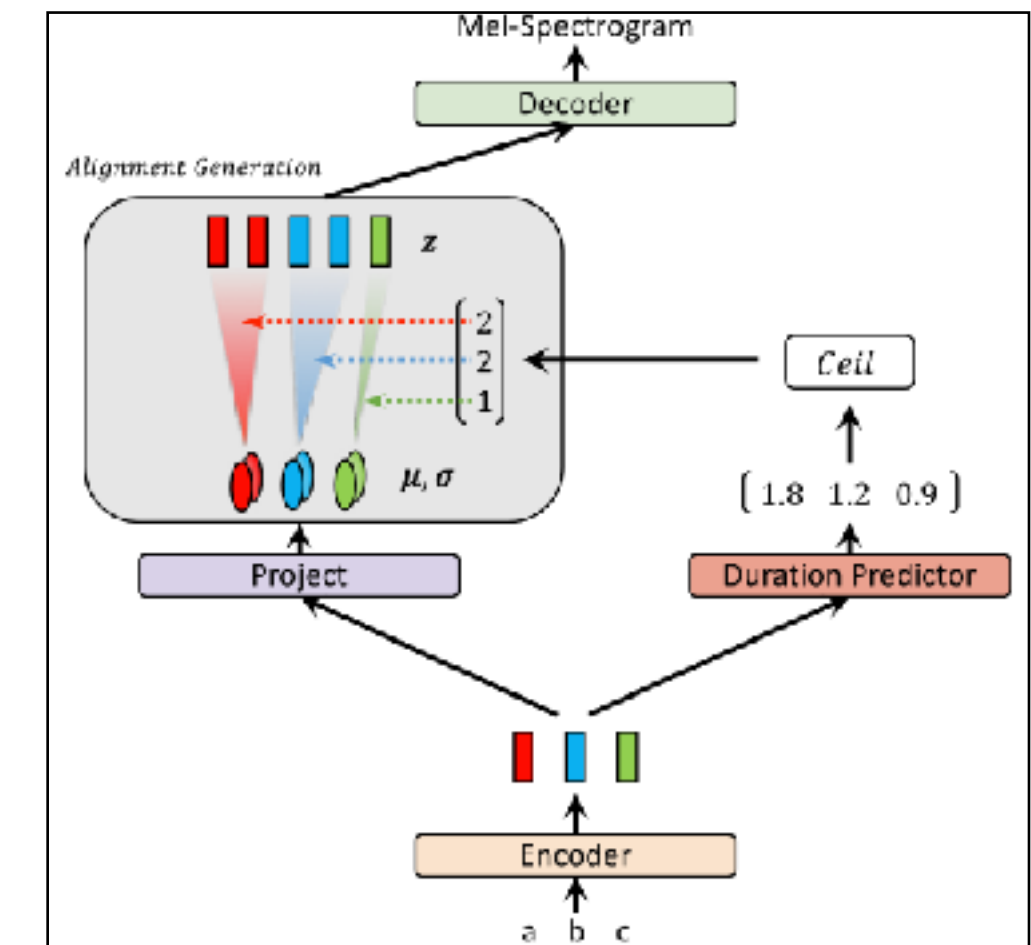


# Generative models

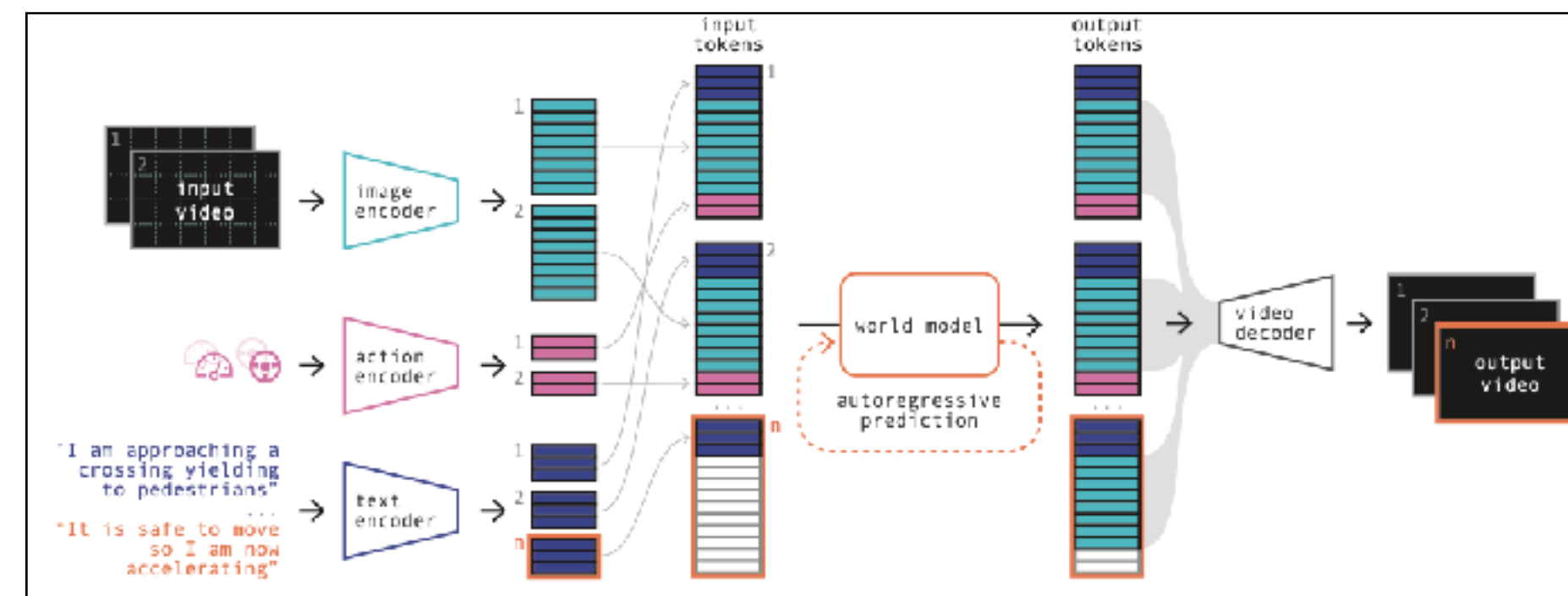
- Generative model:  $P(X)$
- Examples:
  - Image/video generation
  - Speech synthesis
  - Physics simulation / world modeling
  - Weather simulation (gaming)
  - ...



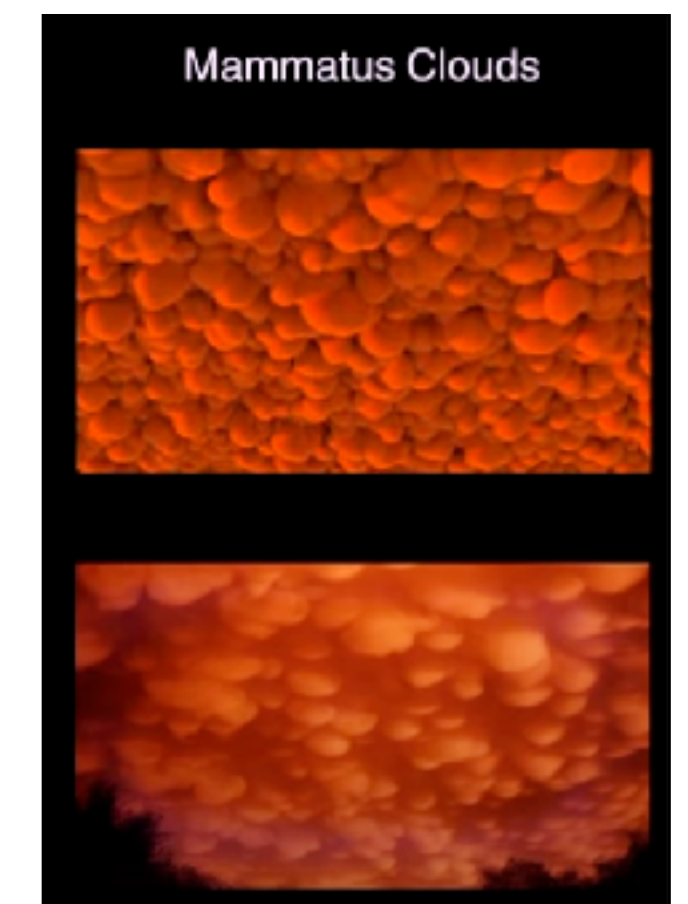
[1] Sora



[2] Glow-TTS



[3] GAIA-1



[4] Weatherscapes

[1] Brook, Tim, et al. "Video generation models as world simulators" OpenAI Blog (2024)

[2] Kim, Jaehyeon, et al. "Glow-tts: A generative flow for text-to-speech via monotonic alignment search." Advances in Neural Information Processing Systems 33 (2020): 8067-8077..

[3] Hu, Anthony, et al. "Gaia-1: A generative world model for autonomous driving." arXiv preprint arXiv:2309.17080 (2023).

[4] J. A. Amador Herrera, et al. "Weatherscapes: Nowcasting Heat Transfer and Water Continuity." ACM Transactions on Graphics (SIGGRAPH Asia 2021), Vol. 40, No. 6, Article 204..



# Generative modeling in deep learning

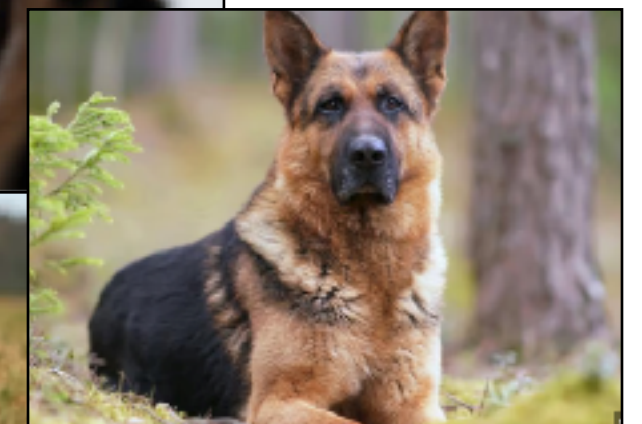
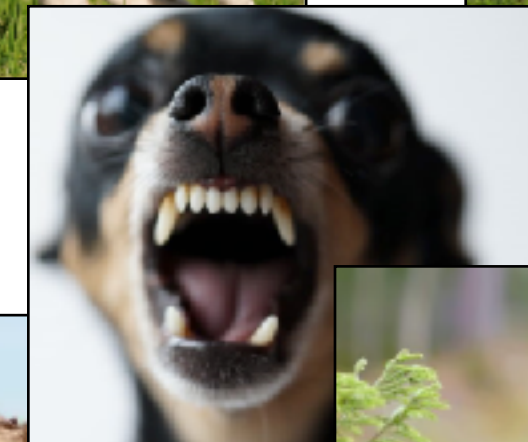
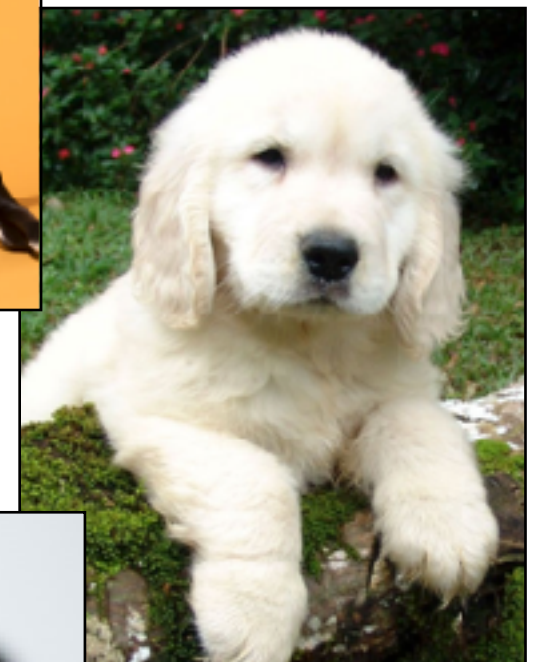
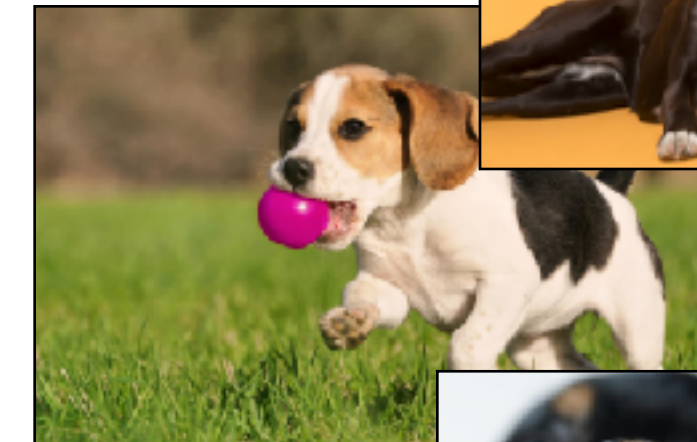
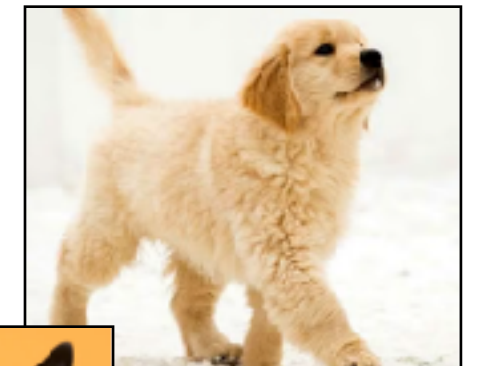
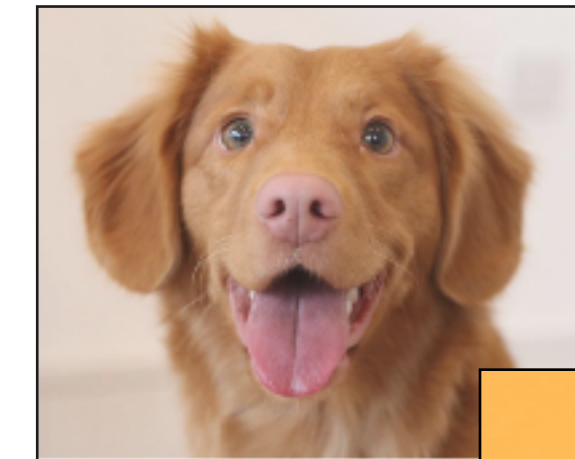
- Generative model:  $P(X)$
- Examples:
  - Image/video generation
  - Speech synthesis
  - Physics simulation / world modeling
  - Weather simulation (gaming)
  - ...



Deep Network



Training





# Generative models

- Two tasks of a generative model  $P(X)$ 
  - Sampling:  $x \sim P(X)$
  - Density estimation:  $P(X = x)$



Deep Network

$P(X)$



Deep Network



# Generative modeling is hard

- Density estimation  $P(X = x)$ 
  - How to ensure  $\sum_x P(x) = 1$  for all  $x$
  - Impossible to compute (in general)
- Sampling  $x \sim P(X)$ 
  - What is the input to the network?



Deep Network

$P(X)$



Deep Network





# Generative vs Discriminative models

## Generative

- Density estimation  $P(X = x)$ 
  - How to ensure  $\sum_x P(x) = 1$  for all  $x$
  - Impossible to compute
- Sampling  $x \sim P(X)$ 
  - What is the input to the network?

## Discriminative

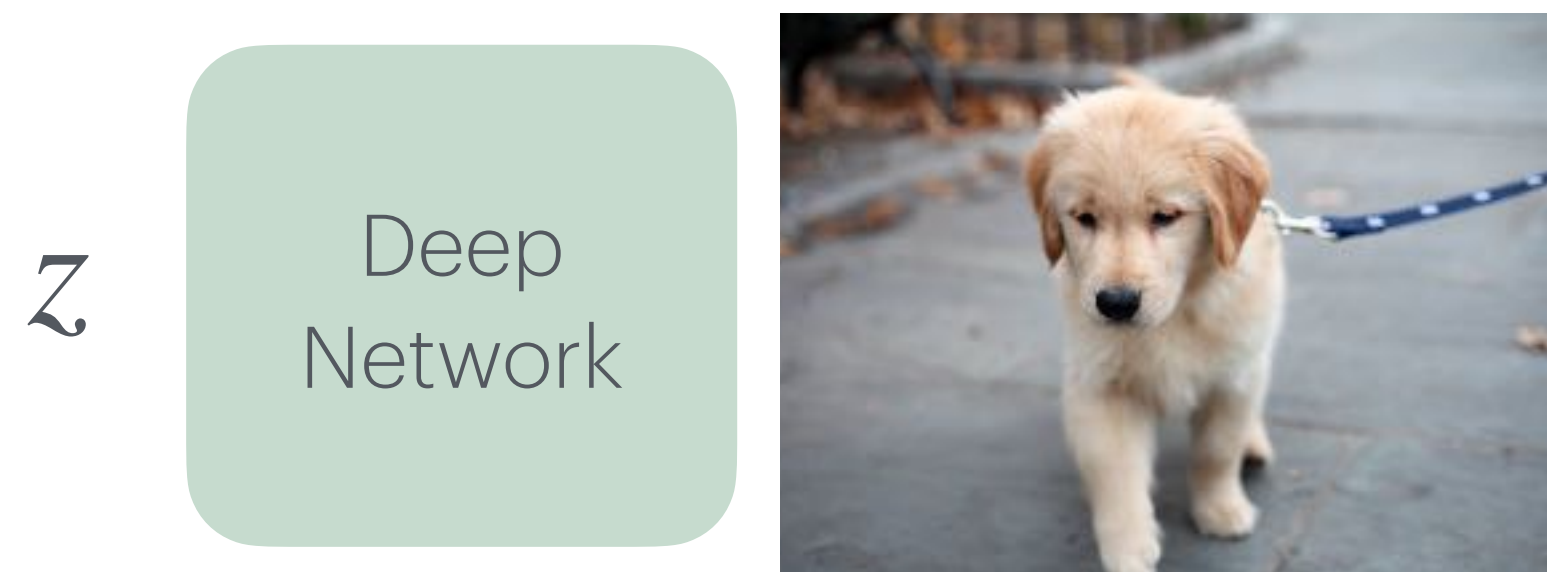
- Prediction  $P(Y | X)$ 
  - Simple, explicit distribution
    - Discrete  $P(y | x) = c_y^\top f(x)$
    - Continuous  $P(y | x) = \mathcal{N}(y; \mu(x), \sigma(x))$
- Well defined input  $y$

# Generative models

## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$



Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation



# References

- [1] Dosovitskiy, Alexey, et al. "An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale." International Conference on Learning Representations. 2020.
- [2] Baevski, Alexei, et al. "wav2vec 2.0: A framework for self-supervised learning of speech representations." Advances in neural information processing systems 33 (2020): 12449-12460.
- [3] Brohan, Anthony, et al. "Rt-2: Vision-language-action models transfer web knowledge to robotic control." arXiv preprint arXiv:2307.15818 (2023)
- [4] Remi Lam et al. "Learning skillful medium-range global weather forecasting." Science 382, 1416-1421(2023).
- [5] Brook, Tim, et al. "Video generation models as world simulators" OpenAI Blog (2024)
- [6] Kim, Jaehyeon, et al. "Glow-tts: A generative flow for text-to-speech via monotonic alignment search." Advances in Neural Information Processing Systems 33 (2020): 8067-8077.
- [7] Hu, Anthony, et al. "Gaia-1: A generative world model for autonomous driving." arXiv preprint arXiv:2309.17080 (2023).
- [8] J. A. Amador Herrera, et al. "Weatherscapes: Nowcasting Heat Transfer and Water Continuity." ACM Transactions on Graphics (SIGGRAPH Asia 2021), Vol. 40, No. 6, Article 204..



# Variational Auto Encoders

# Generative models

- Two tasks of a generative model  $P(X)$ 
  - Sampling:  $x \sim P(X)$
  - Density estimation:  $P(X = x)$



Deep Network

$P(X)$



Deep Network



# Generative modeling is hard

- Density estimation  $P(X = x)$ 
  - How to ensure  $\sum_x P(x) = 1$  for all  $x$
  - Impossible to compute (in general)
- Sampling  $x \sim P(X)$ 
  - What is the input to the network?



Deep Network

$P(X)$



Deep Network



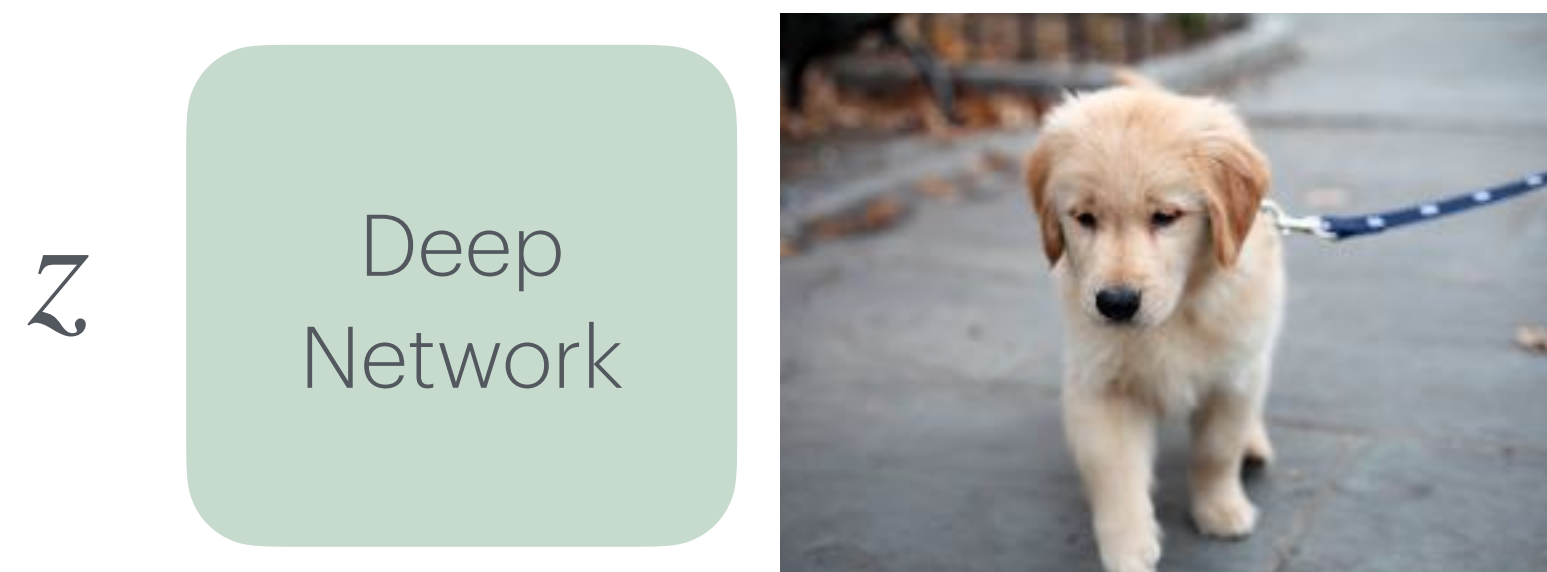


# Generative models

## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$



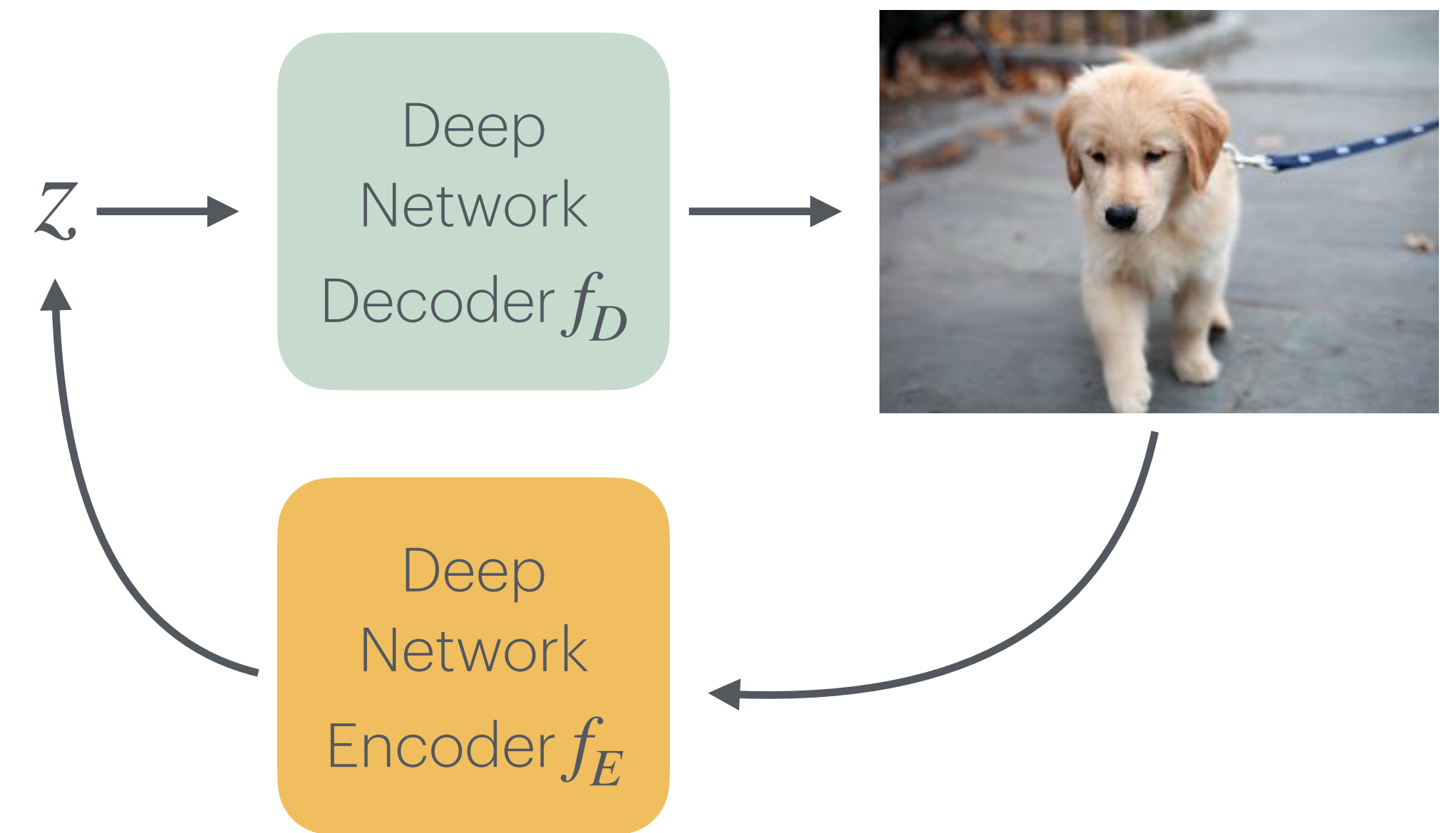
Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation



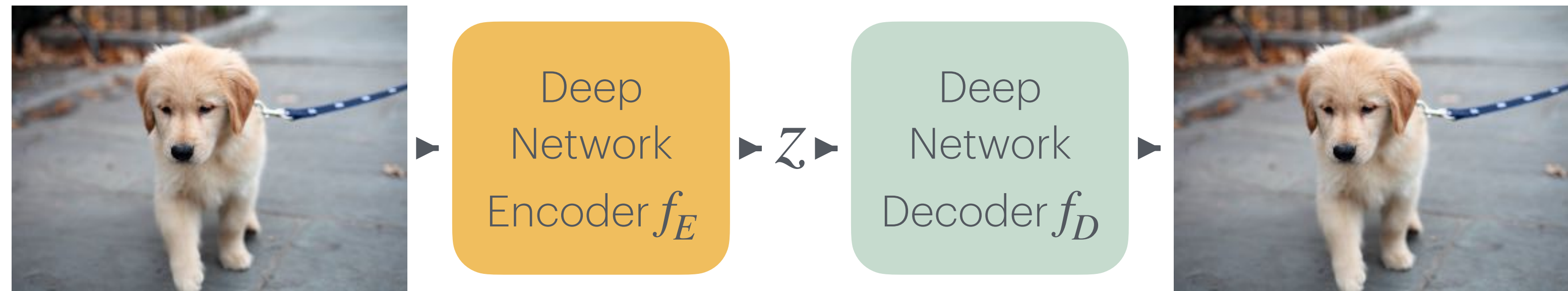
# Generative models

- Goal: Learn decoder  $f_D : z \rightarrow x$
- What should  $z$  be?
  - Let a deep network decide
    - Encoder  $f_E : x \rightarrow z$





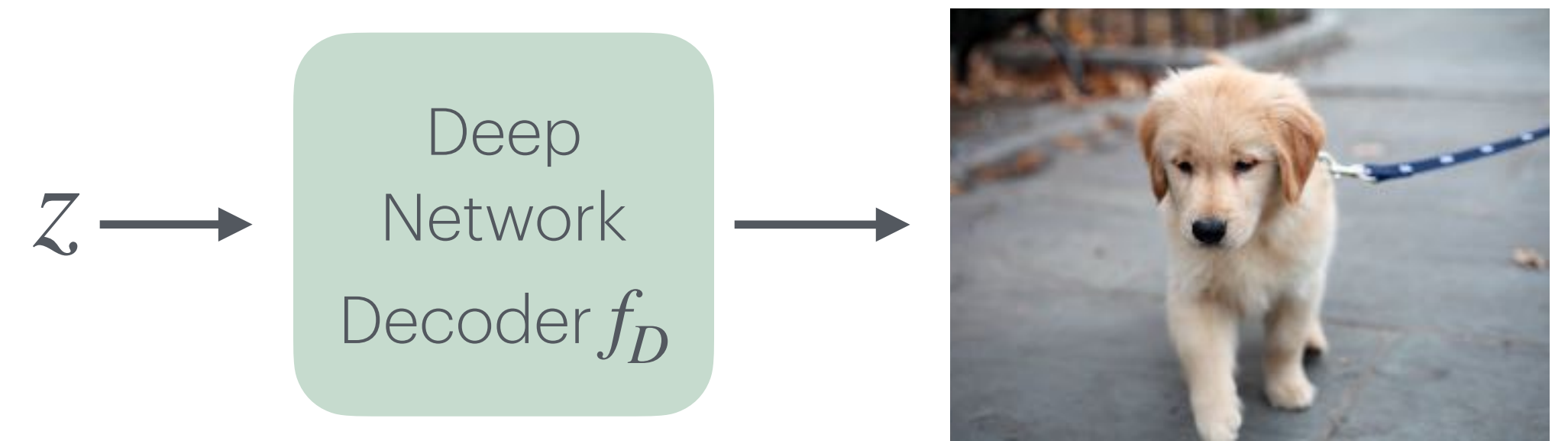
# Auto-encoder



- encoder  $z = f_E(x)$
- decoder  $\hat{x} = f_D(z)$
- Training
  - Supervised learning on large dataset
  - $\ell = E_x [|f_D(f_E(x)) - x|]$

# Auto-encoder as a Generative model

- Decoder  $f_D : z \rightarrow x$
- Inference / Sampling
  - What is  $z$  at test time?

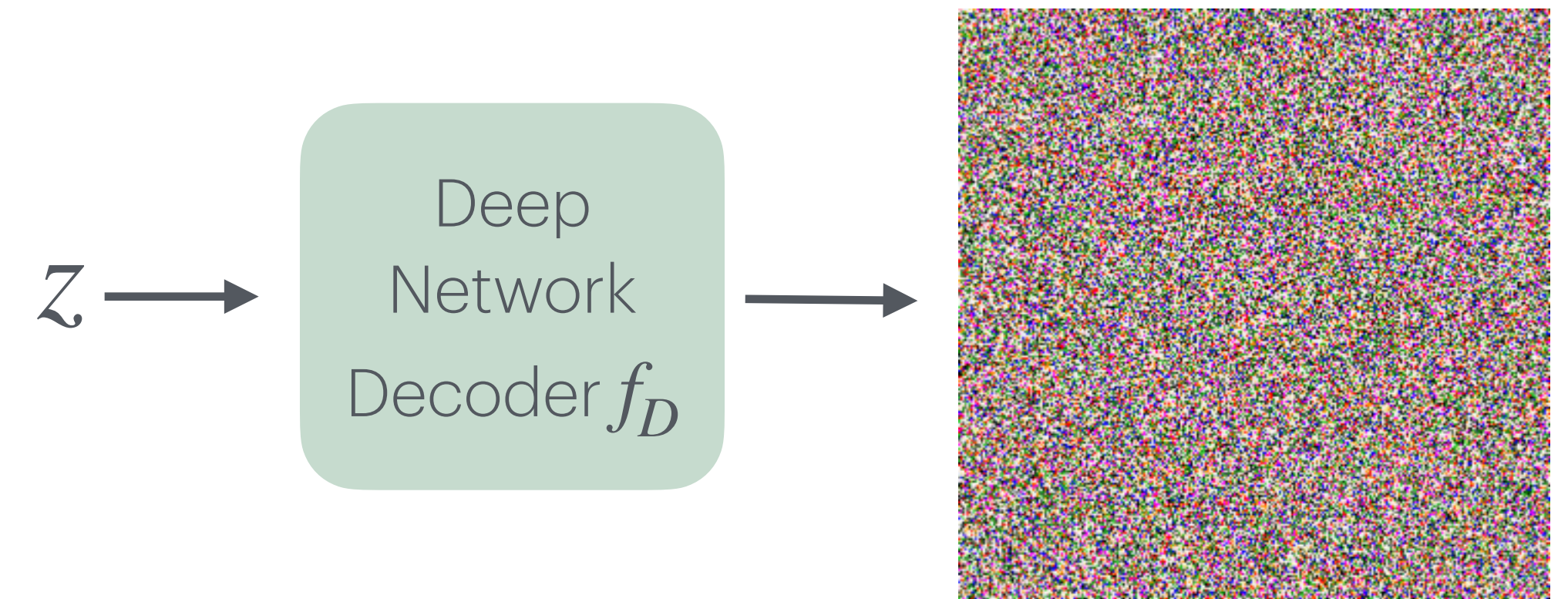




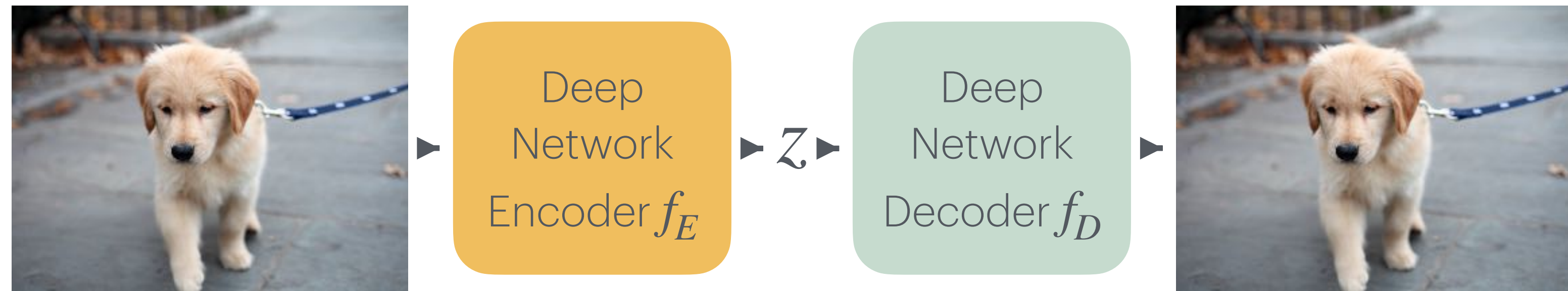
# Auto-encoder

## Generation

- Decoder  $f_D : z \rightarrow x$
- Inference / Sampling
  - What is  $z$  at test time?
    - Network output -> no new image
    - Random input -> Garbage
    - Interpolation -> Garbage



What does an auto-encoder learn?

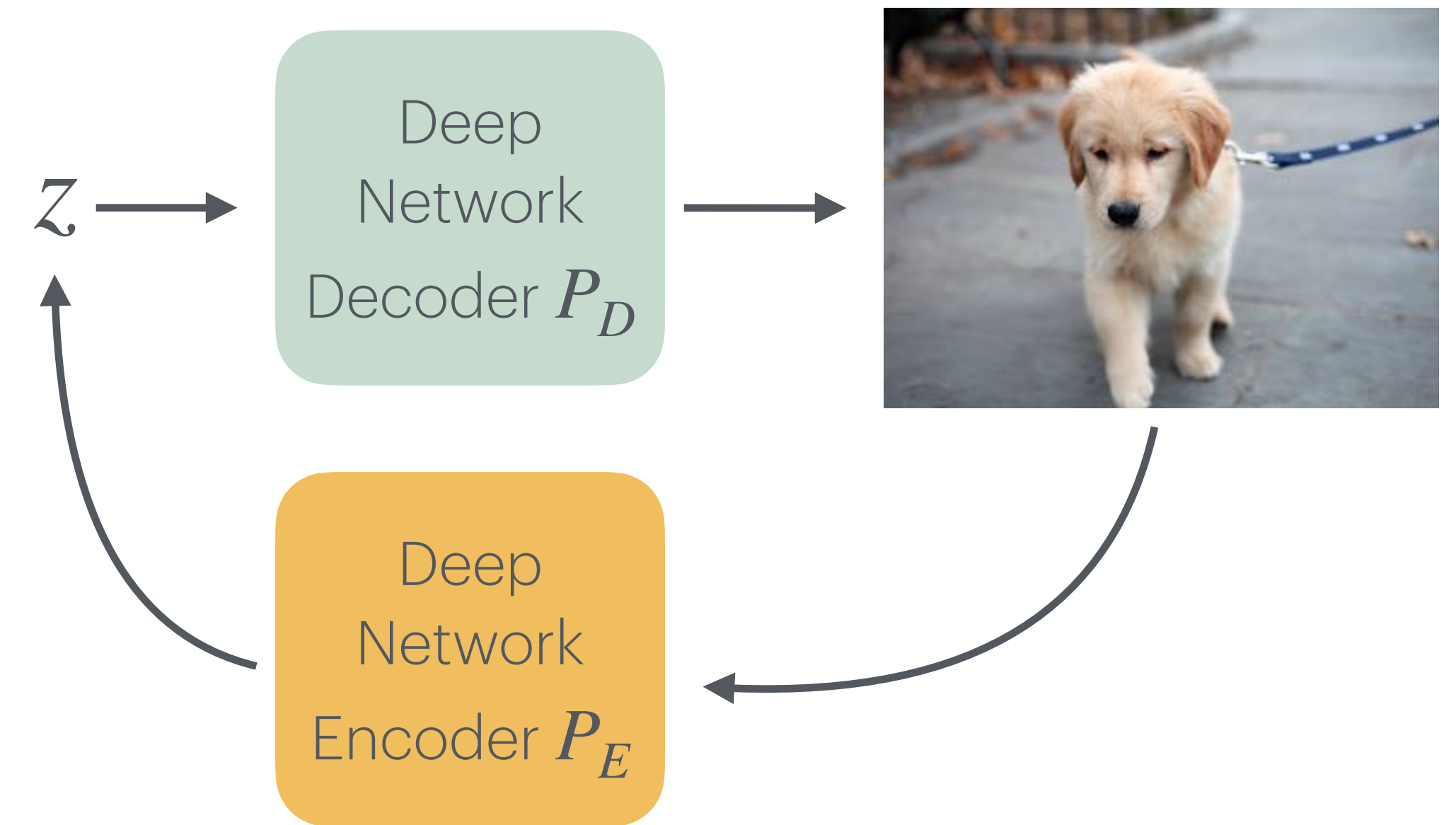


- Compression
- “Invertible” mapping
- Does it learn the structure of images?
  - Only in the limit
  - Perfect compression = understanding
- Poor generation

# Variational auto-encoder

A “probabilistic” auto-encoder

- Goal: Learn decoder  $P_D(x | z)$
- What should  $z$  be?
  - Let a deep network decide
    - Encoder  $P_E(z | x)$





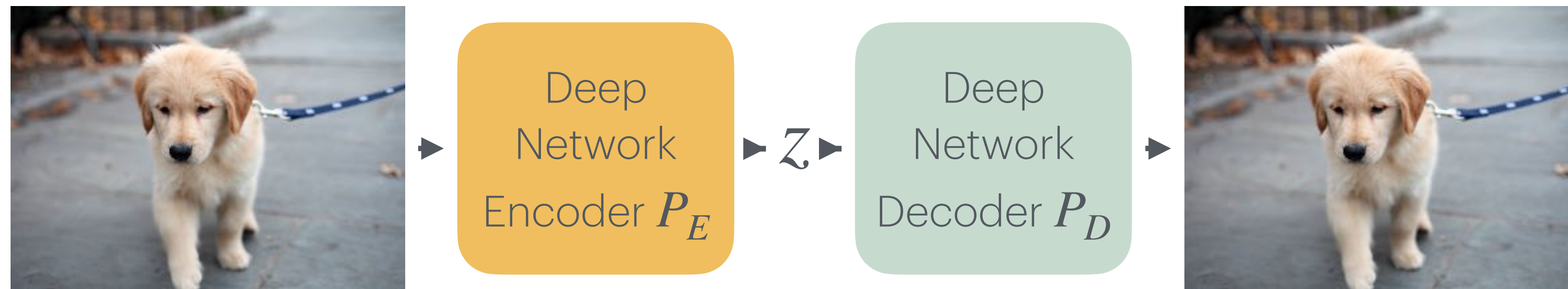
# Variational auto-encoder

A “probabilistic” auto-encoder

- Decoder  $P_D(x | z)$  (similar to discriminative model)
- Encoder  $P_E(z | x)$  (similar to discriminative model)
- Assume  $P(Z) = \mathcal{N}(0,1)$

- $$P(x) = \sum_z P_D(x | z)P(z)$$

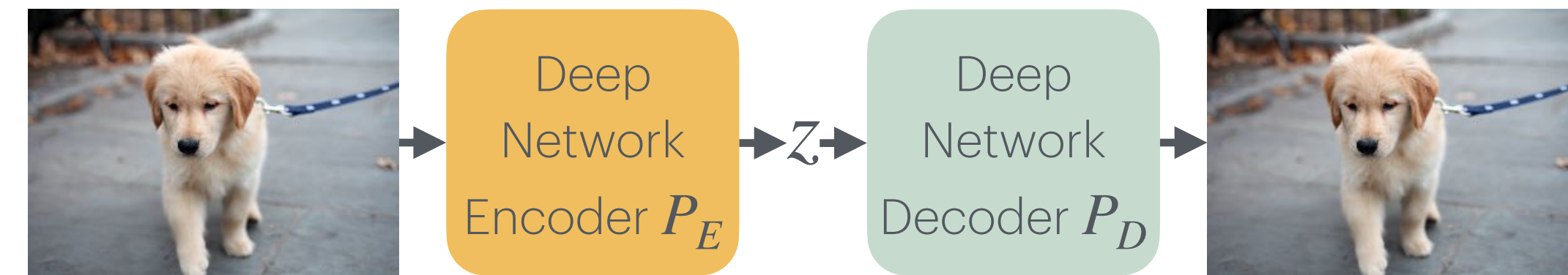
- $z \sim P(X)$  is equivalent to  
 $z \sim P(Z)$  and  $x \sim P(x | z)$



# Variational auto-encoder

A “probabilistic” auto-encoder

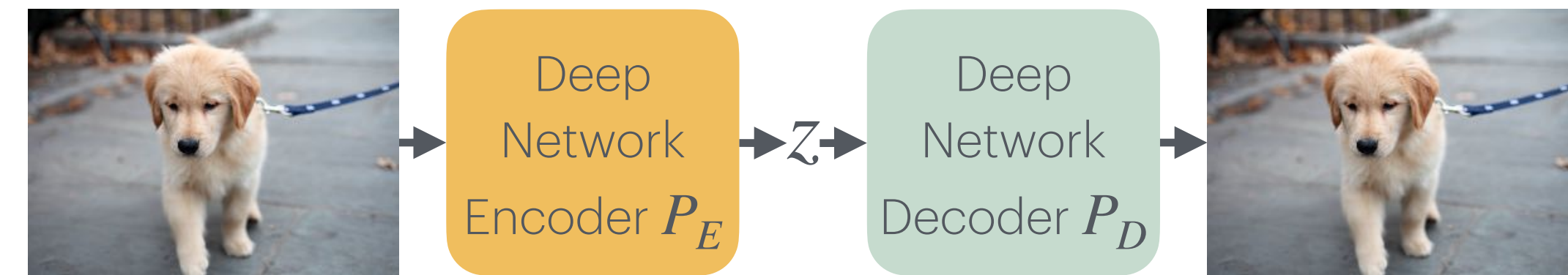
- Decoder  $P_D(x | z)$  (similar to discriminative model)
- Encoder  $P_E(z | x)$  (similar to discriminative model)
- Assume  $P(Z) = \mathcal{N}(0,1)$ 
  - Bayes rule  $P_E(z | x) = \frac{P_D(x | z)P(z)}{P(x)}$  ← intractable



# Variational auto-encoder

A “probabilistic” auto-encoder

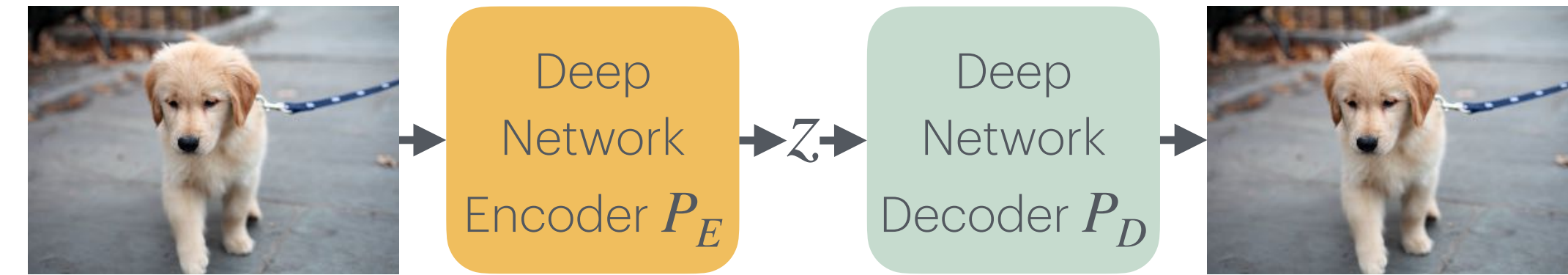
- Decoder  $P_D(x | z)$  (similar to discriminative model)
- Encoder  $Q(z | x)$  (similar to discriminative model)
- Assume  $P(Z) = \mathcal{N}(0,1)$ 
  - Bayes rule  $P_E(z | x) = \frac{P_D(x | z)P(z)}{P(x)}$  ← intractable
- Learn  $Q \approx P_E$  that minimizes  $D_{KL}(Q | P_E)$





# Variational auto-encoder

A “probabilistic” auto-encoder



- Learn  $Q \approx P_E$  that minimizes

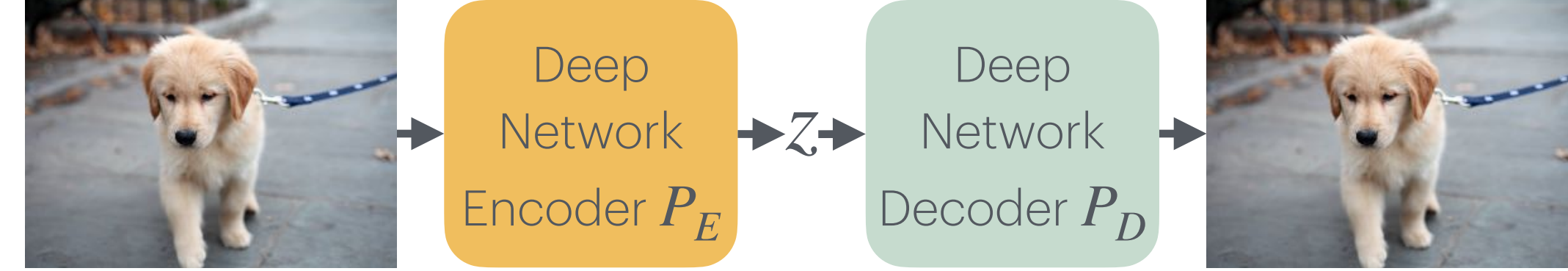
$$D_{KL}(Q(z|x) \| P_E(z|x)) = \log P(x) + E_{z \sim Q} \left[ \log \frac{P(z)P_D(x|z)}{Q(z|x)} \right]$$

- Maximize  $\log P(x)$  of real data, minimize  $D_{KL}$   
 $\log P(x) - D_{KL}(Q(z|x) \| P_E(z|x)) = E_{z \sim Q} \left[ \log \frac{Q(z|x)}{P(z)P_D(x|z)} \right]$

- Known as ELBO (Evidence Lower BOund)

# Variational auto-encoder

A “probabilistic” auto-encoder



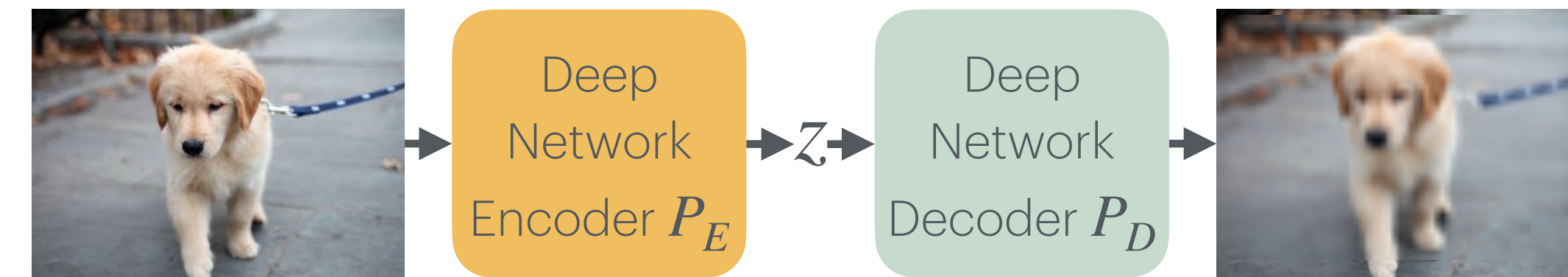
- ELBO  $E_{z \sim Q} \left[ \log \frac{Q(z | x)}{P(z)P_D(x | z)} \right]$  for Gaussians
  - $-\frac{1}{2} \mathbb{E}_{z \sim Q} [\|x - \mu_D(z)\|_2^2] - \frac{1}{2} \left( N\sigma_Q(x)^2 + \|\mu_Q(x)\|_2^2 - 2N \log \sigma_Q(x) \right) + Const$
- Reparametrization trick
  - For  $Q(z | x) = \mathcal{N}(z; \mu_Q(x), \sigma_Q^2(x))$
  - $\mathbb{E}_{z \sim Q} [\|x - \mu_D(z)\|_2^2] = \mathbb{E}_{\varepsilon \sim \mathcal{N}(0,1)} [\|x - \mu_D(\mu_Q(x) + \varepsilon \sigma_Q(x))\|_2^2]$



# Variational auto-encoder

A “probabilistic” auto-encoder

- Can learn  $P(X)$  and sampling function  $x \sim P$
- Issues
  - Reconstruction loss: Pixel-level l2 loss
    - Blurry outputs
  - Approximation  $Q$ : Gaussian assumption
    - Sphere packing in higher dimensions
    - Lots of empty space

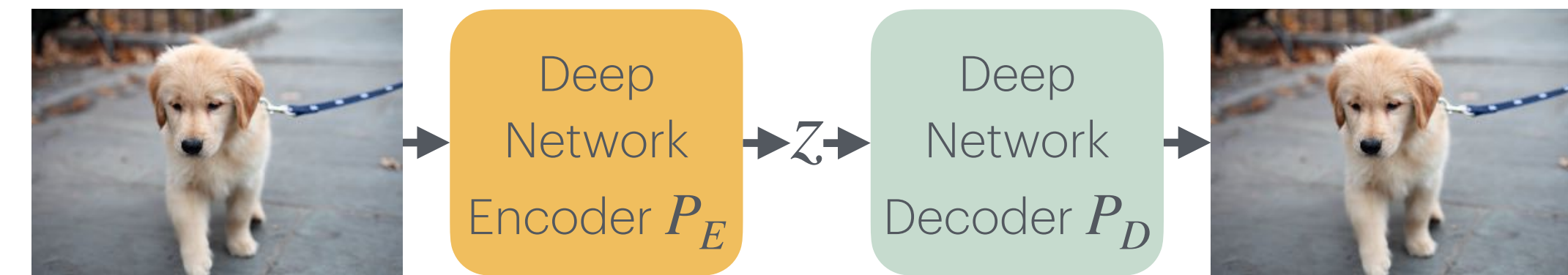




# Variational auto-encoder

A “probabilistic” auto-encoder

- Learn a model of  $P(x) = P_D(x|z)P(z)$  with  $P(z) = \mathcal{N}(z; 0, 1)$
- Training: Maximize  $P(x)$  of data
- Approximate  $Q \approx P_E$



# References

- [1] Auto-Encoding Variational Bayes. Kingma et al. 2014.

# Auto-regressive generation



# Generative models

- Two tasks of a generative model  $P(X)$ 
  - Sampling:  $x \sim P(X)$
  - Density estimation:  $P(X = x)$



Deep Network

$P(X)$



Deep Network



# Generative modeling is hard

- Density estimation  $P(X = x)$ 
  - How to ensure  $\sum_x P(x) = 1$  for all  $x$
  - Impossible to compute (in general)
- Sampling  $x \sim P(X)$ 
  - What is the input to the network?



Deep Network

$P(X)$



Deep Network



# Generative models

## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$

$z$

Deep  
Network



Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation

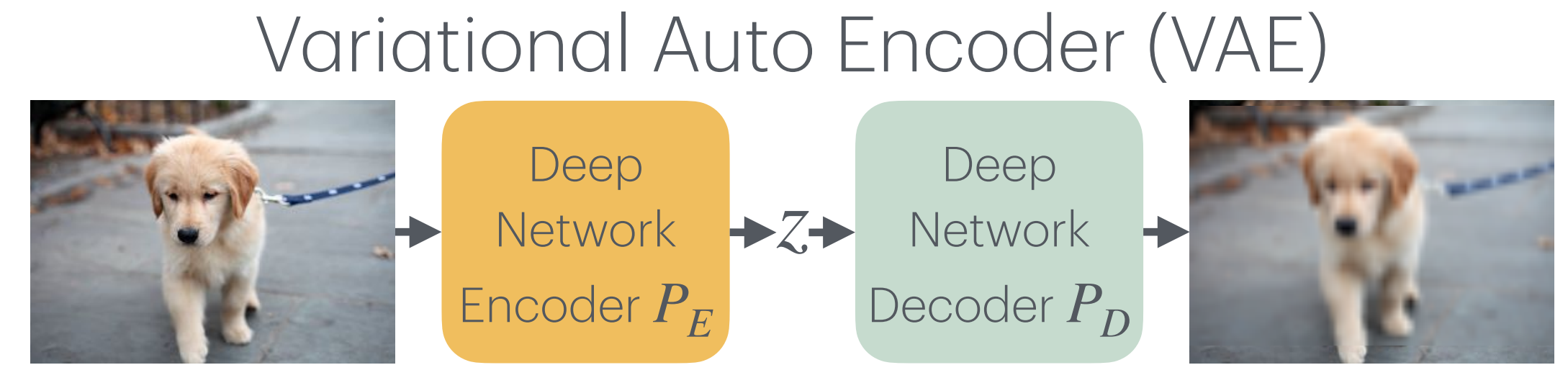


Deep  
Network

$P(X)$

# Recap

- VAE
  - Image -> latent space -> Image
  - Loss encourages Gaussian latent





# Auto-regressive models

$$P(x) = P(x_1)P(x_2 | x_1)P(x_3 | x_1, x_2)P(x_4 | x_1 \dots x_3) \dots$$

- $P(x_i | x_1 \dots x_{i-1}) = \text{softmax}(f(x_1 \dots x_{i-1}))$

- Basis of most LLM models

- Easy estimation of  $P(x)$

- Easy sampling

$$x_1 \sim P(X_1); x_2 \sim P(X_2 | x_1)$$

- Slow sampling



[1] WaveNet: A Generative Model for Raw Audio. Aaron van den Oord, et al. 2016

[2] Long Video Generation with Time-Agnostic VQGAN and Time-Sensitive Transformer. Songwei Ge, et al. 2022

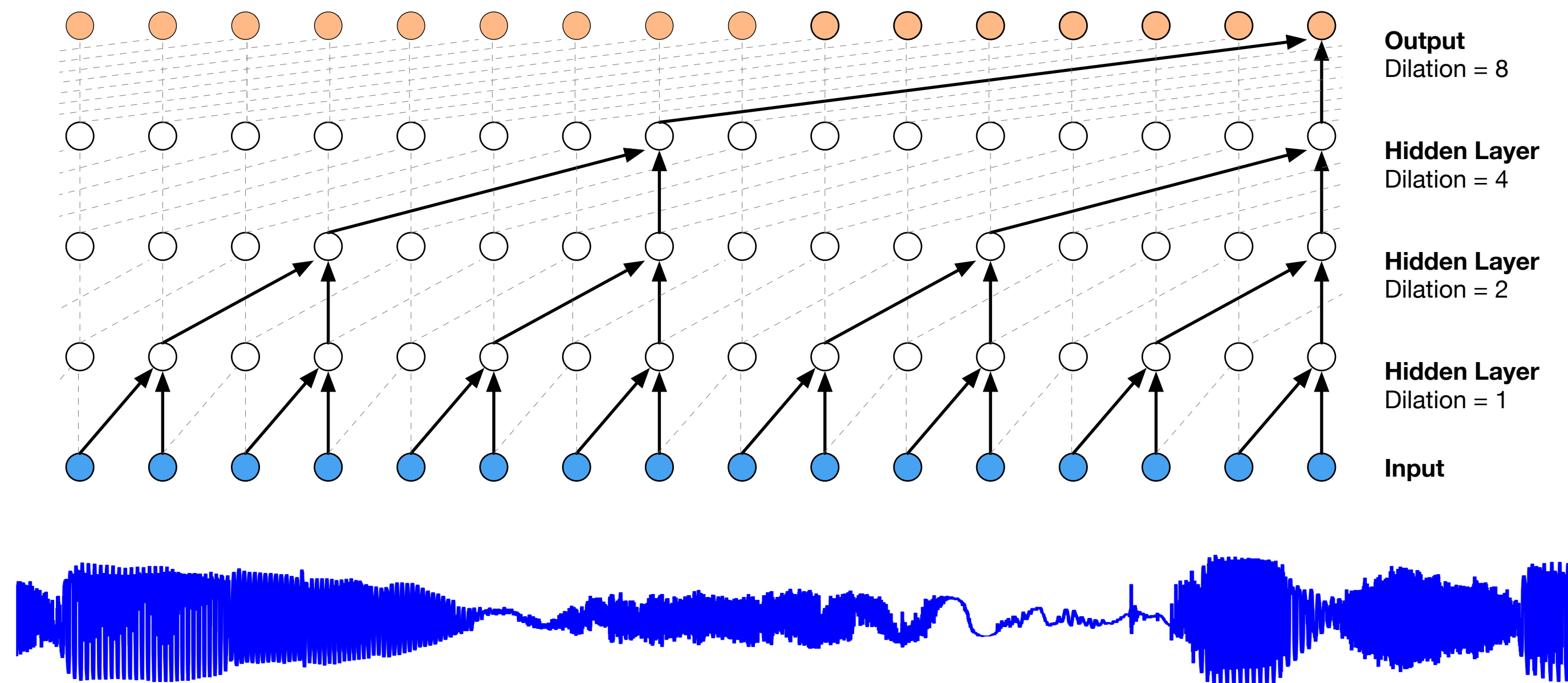
# Example: WaveNet

- Input: Raw waveform  $\mathbf{x}_{1...t-1}$
- Output: Quantized next value  $\mathbf{x}_t \in \{1...256\}$

- Model:  $P(\mathbf{x}) = \prod_{t=1}^T P(x_t | \mathbf{x}_{1...t-1})$

- Conditioned model:

$$P(\mathbf{x} | \mathbf{h}) = \prod_{t=1}^T P(x_t | \mathbf{x}_{1...t-1} | \mathbf{h})$$





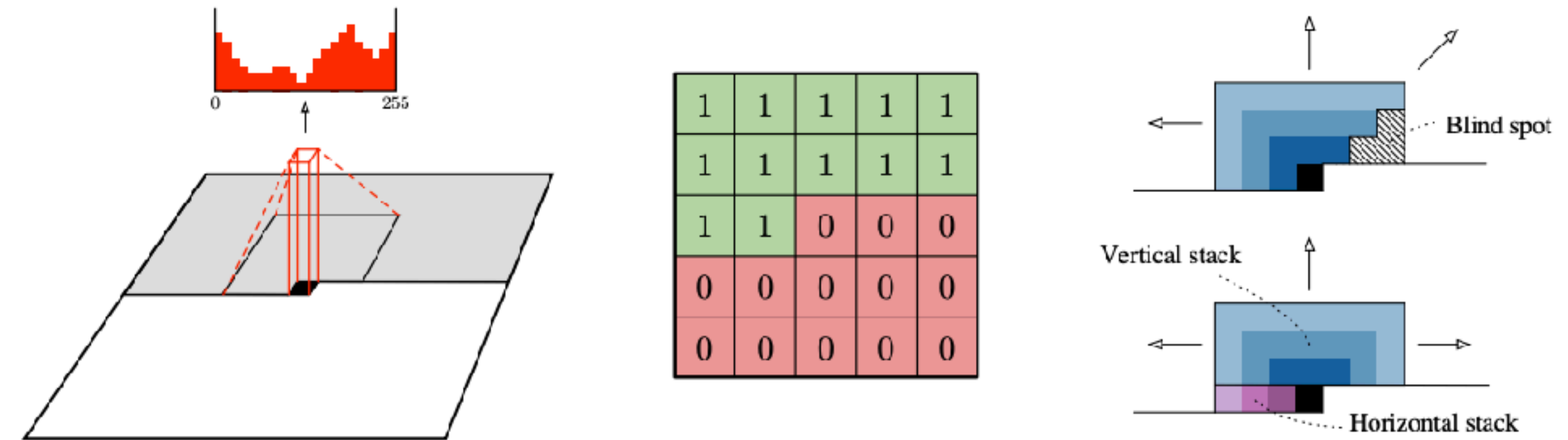
# Example: PixelCNN

- Input: Raw pixels  $\mathbf{x}_{1\dots t-1}$
- Output: Quantized next color value  $\mathbf{x}_t \in \{1\dots 256\}$

- Model:  $P(\mathbf{x}) = \prod_{t=1}^T P(x_t | \mathbf{x}_{1\dots t-1})$

- Conditioned model:

$$P(\mathbf{x} | \mathbf{h}) = \prod_{t=1}^T P(x_t | \mathbf{x}_{1\dots t-1} | \mathbf{h})$$





# Auto-regressive models

## Issues

$$P(x) = P(x_1)P(x_2 | x_1)P(x_3 | x_1, x_2)P(x_4 | x_1 \dots x_3) \dots$$

- Difficult learning problem for long sequences (requires good model)
- Solution: Tokenization/Vector-Quantization (next class)
  - More complex  $x_i$
  - Shorter sequence



[1] WaveNet: A Generative Model for Raw Audio. Aaron van den Oord, et al. 2016

[2] Long Video Generation with Time-Agnostic VQGAN and Time-Sensitive Transformer. Songwei Ge, et al. 2022

# Generation vs Compression

- Knowing  $P(\mathbf{x})$  leads to best lossless compression within one bit
  - $\# \text{bits} = \lfloor -\log_2 P(\mathbf{x}) \rfloor + 1$
- Why?

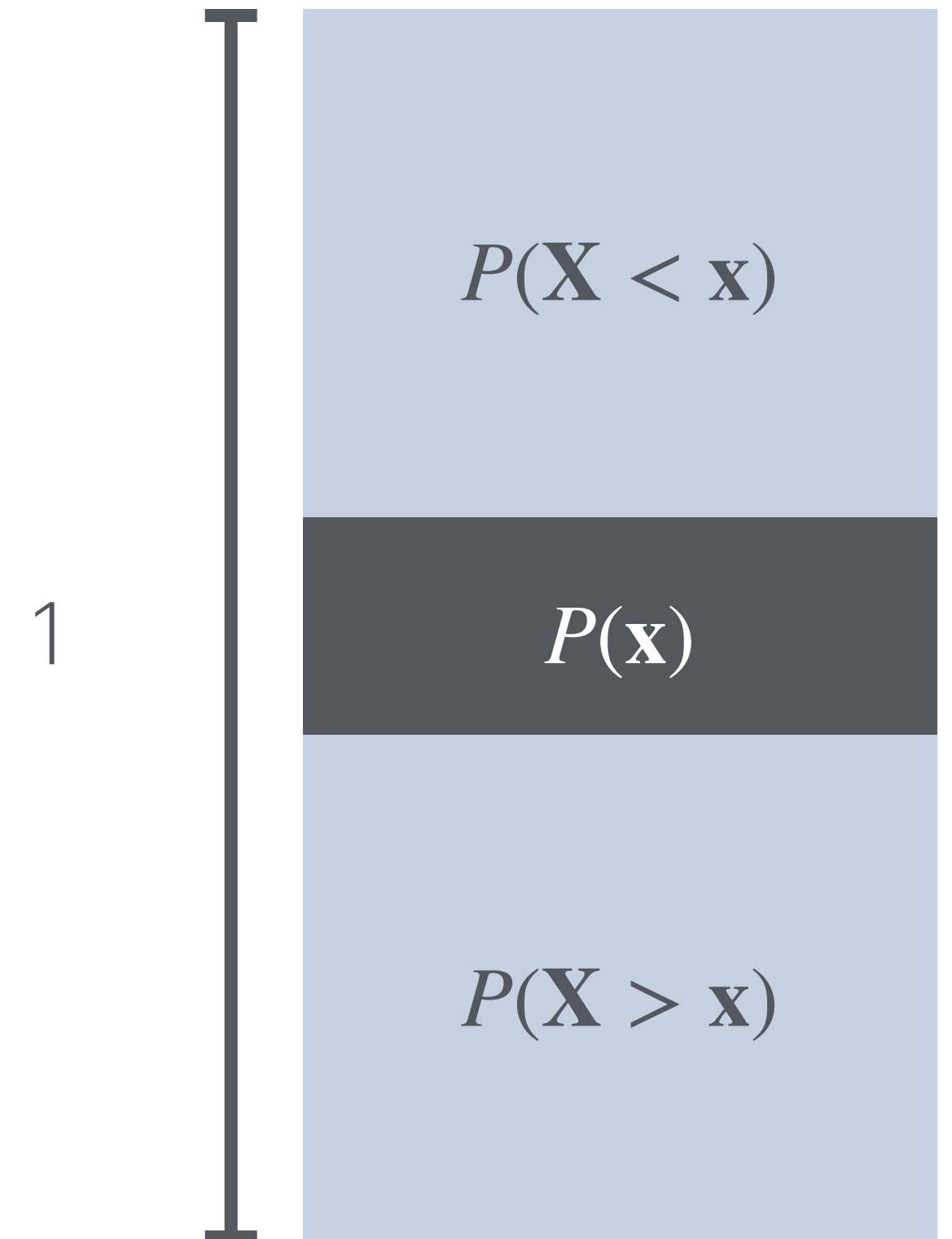
[1] Lossless Image Compression through Super-Resolution. Sheng Cao, et al. 2020

[2] Practical Full Resolution Learned Lossless Image Compression. Fabian Mentzer, et al. 2019

# Arithmetic coding

$\lfloor -\log_2 P(\mathbf{x}) \rfloor + 1$  bit lossless compression

- Sort  $\mathbf{x}$  lexicographically
- Compute CDF  $P(\mathbf{X} < \mathbf{x})$
- Split interval between 0...1 into  $2^{\lfloor -\log_2 P(\mathbf{x}) \rfloor + 1}$  numbers
- Since  $2^{\lfloor -\log_2 P(\mathbf{x}) \rfloor + 1} > \frac{1}{P(\mathbf{x})}$ , at least one number  $n$  will end in range  $P(\mathbf{X} < \mathbf{x}) \dots P(\mathbf{X} \leq \mathbf{x})$
- $n$  is our  $\lfloor -\log_2 P(\mathbf{x}) \rfloor + 1$  code



[1] Lossless Image Compression through Super-Resolution. Sheng Cao, et al. 2020

[2] Practical Full Resolution Learned Lossless Image Compression. Fabian Mentzer, et al. 2019



# Arithmetic coding in practice

- CDF  $P(\mathbf{X} < \mathbf{x})$  generally hard to compute

- Easy for  $P(\mathbf{x}) = \prod_{t=1}^T P(x_t | \mathbf{x}_{1\dots t-1})$

- $P(\mathbf{X} \leq \mathbf{x}) = \prod_{t=1}^T P(X_t \leq x_t | \mathbf{x}_{1\dots t-1})$

- Leads to adaptive arithmetic coding

[1] Lossless Image Compression through Super-Resolution. Sheng Cao, et al. 2020

[2] Practical Full Resolution Learned Lossless Image Compression. Fabian Mentzer, et al. 2019

# Generative models

## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$

$z$

Deep  
Network



Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation



Deep  
Network

$P(X)$

# References

- [1] WaveNet: A Generative Model for Raw Audio. Aaron van den Oord, et al. 2016
- [2] Long Video Generation with Time-Agnostic VQGAN and Time-Sensitive Transformer. Songwei Ge, et al. 2022
- [3] Lossless Image Compression through Super-Resolution. Sheng Cao, et al. 2020
- [4] Practical Full Resolution Learned Lossless Image Compression. Fabian Mentzer, et al. 2019



# Vector Quantization

# Generative models

- Two tasks of a generative model  $P(X)$ 
  - Sampling:  $x \sim P(X)$
  - Density estimation:  $P(X = x)$



Deep Network

$P(X)$



Deep Network



# Generative modeling is hard

- Density estimation  $P(X = x)$ 
  - How to ensure  $\sum_x P(x) = 1$  for all  $x$
  - Impossible to compute (in general)
- Sampling  $x \sim P(X)$ 
  - What is the input to the network?



Deep Network

$P(X)$



Deep Network





# Generative models

## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$

$z$

Deep  
Network



Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation



Deep  
Network

$P(X)$

# Auto-regressive models

## Issues

$$P(x) = P(x_1)P(x_2 | x_1)P(x_3 | x_1, x_2)P(x_4 | x_1 \dots x_3) \dots$$

- Difficult learning problem for long sequences (requires good model)



[1] WaveNet: A Generative Model for Raw Audio. Aaron van den Oord, et al. 2016

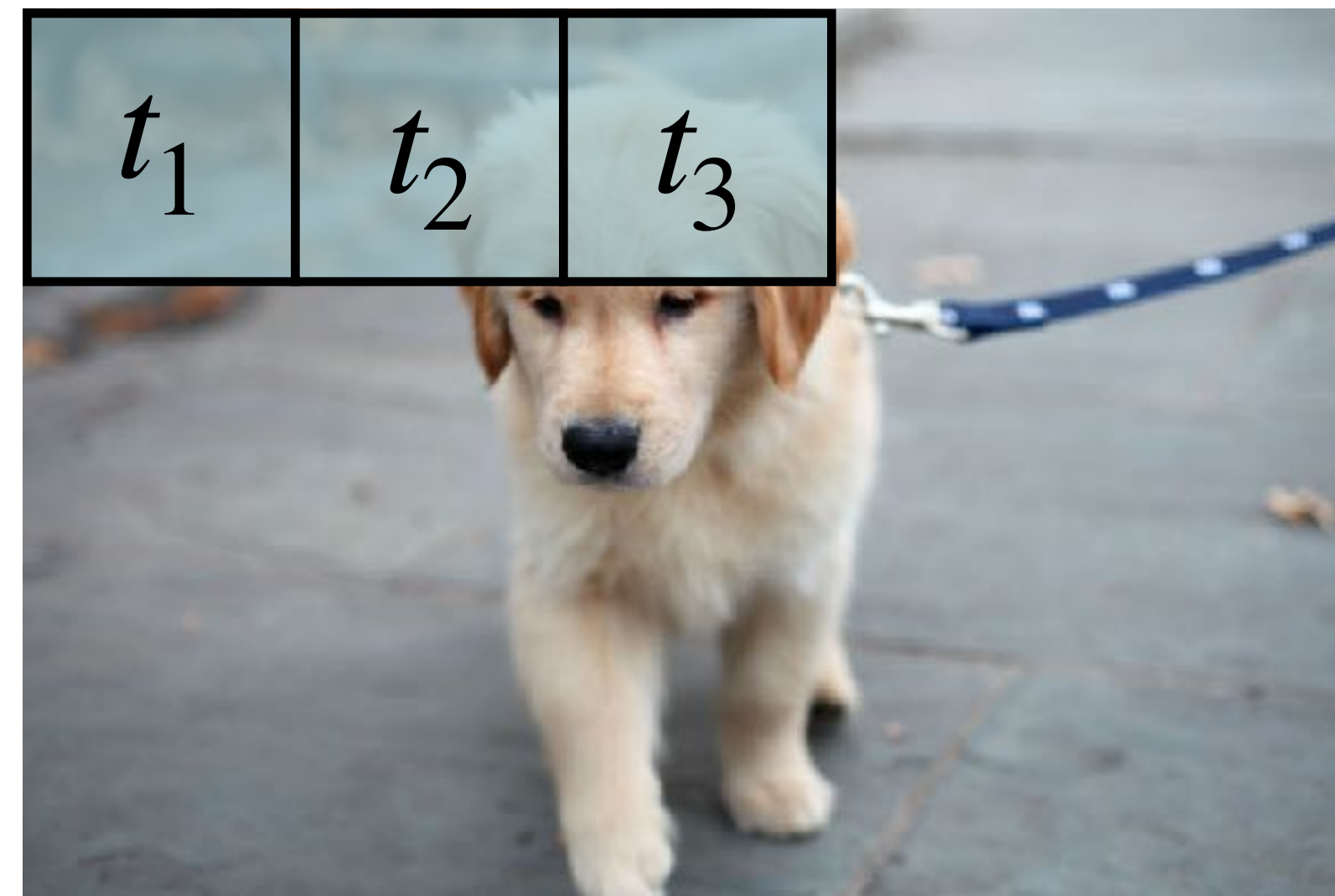
[2] Long Video Generation with Time-Agnostic VQGAN and Time-Sensitive Transformer. Songwei Ge, et al. 2022

# Tokenization

- Image [1]
  - Convert patch  $p_i$  of pixels into token  $t_i \in \{1, \dots, K\}$
- Text [2]
  - Convert set of characters into token
- Protein-sequence [3]
  - Convert local protein structure to token



Vanilla auto-regressive model



Tokenized auto-regressive model

[1] Neural Discrete Representation Learning. Aaron van den Oord, et al. 2017  
[2] Language models are unsupervised multitask learners. Alec Radford, et al. 2019  
[3] Simulating 500 million years of evolution with a language model. Thomas Hayes, et al. 2024



# Auto-regressive models on tokens

$$P(\mathbf{t}) = P(t_1)P(t_2 | t_1)P(t_3 | t_1, t_2)P(t_4 | t_1 \dots t_3) \dots$$

- Shorter sequence = easier to learn structure

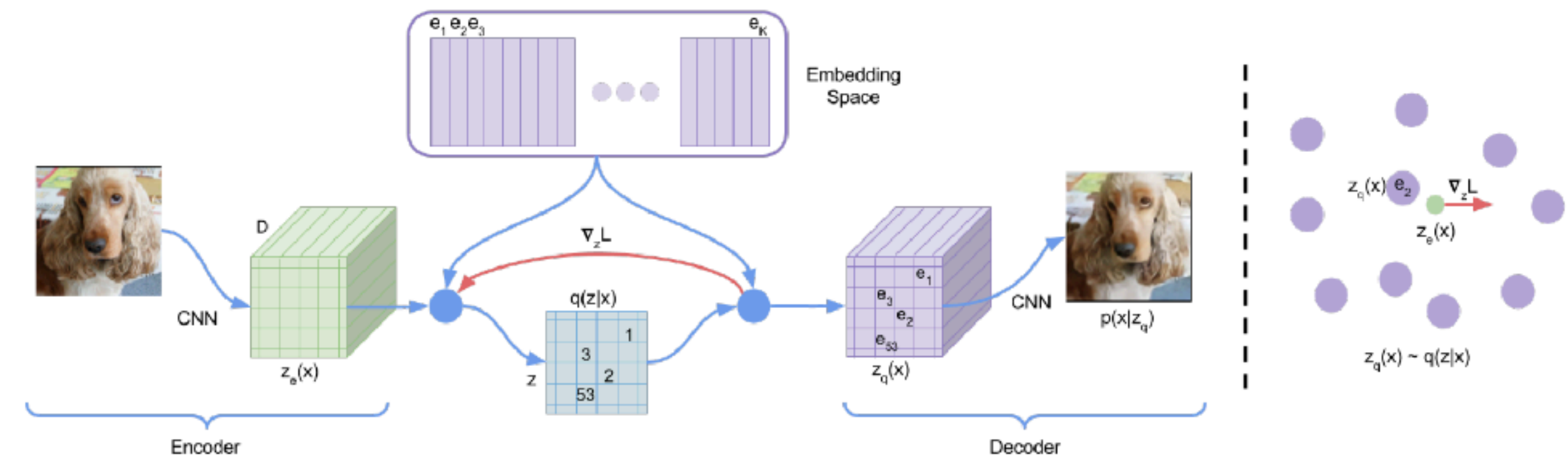




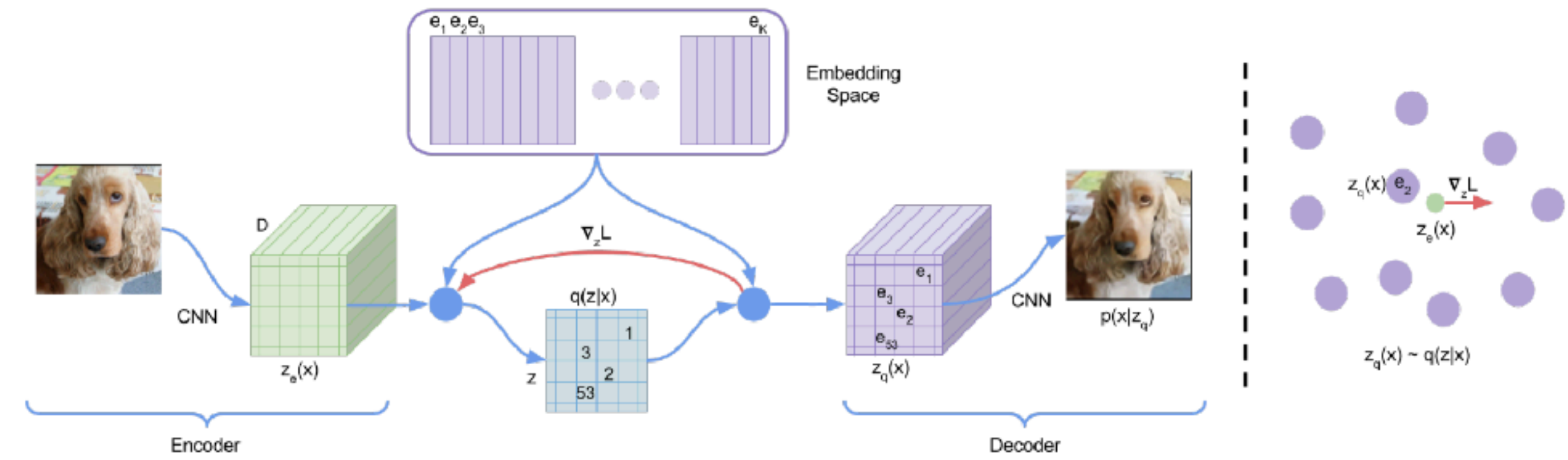
# Learning Tokenization

## Vector Quantization

- Input: Image (or patch)  
 $x \in \mathbb{R}^{H \times W \times 3}$
- Output: “Image” of tokens  
 $z \in \{1 \dots K\}^{h \times w}$
- Why is this hard to learn?
  - $z \rightarrow x$  (easy, reconstruction)
  - $x \rightarrow z \rightarrow x$  (hard,  $z$  is discrete and non-differentiable)



# VQ-VAE

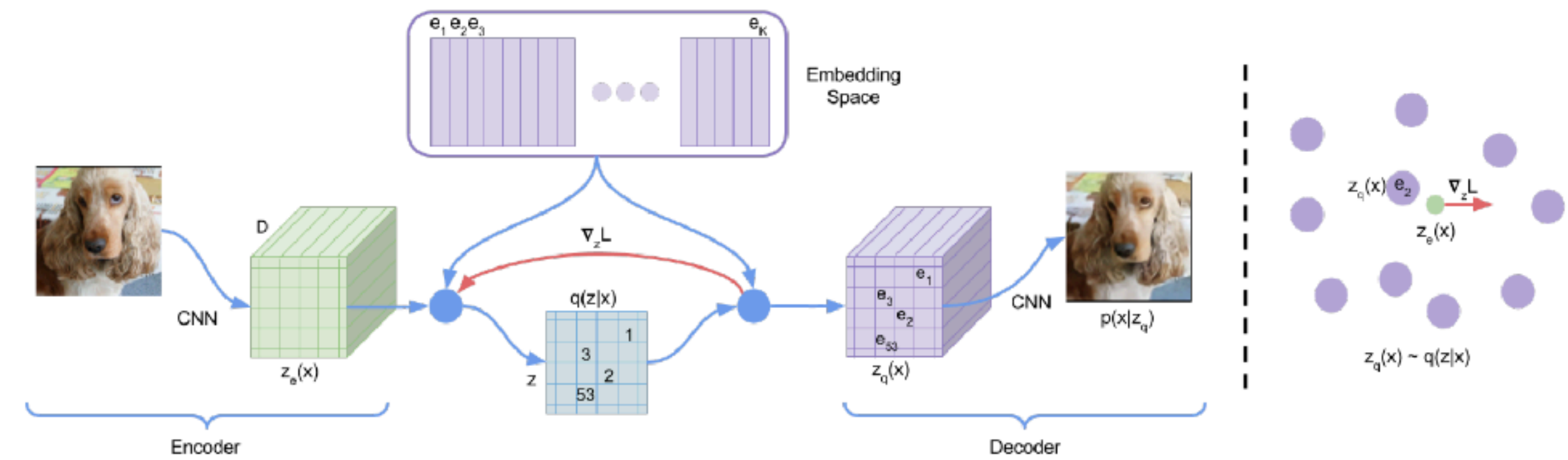


- Variational Auto-Encoder
  - Decoder  $P_D(x|z)$  Encoder  $Q(z|x)$
- Vector Quantizer
  - $q(z) = \arg \min_{e_k} \|z - e_k\|$
  - Learn codebook  $\{e_1 \dots e_K\}$
  - What is  $\nabla q(z)$ ?

# VQ-VAE

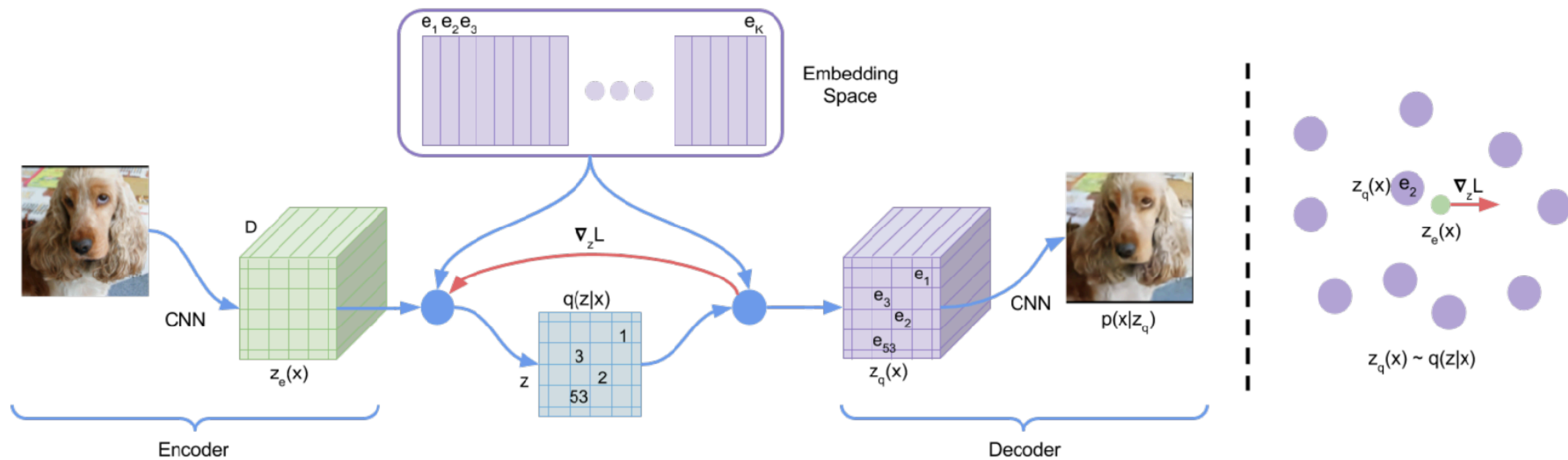
## Gradient

- What is  $\nabla q(z)$ ?
  - Let's assume  $\nabla q(z) = \mathbf{I}$  (identity)
  - Straight-Through Estimator
    - Works in practice because errors average out over large enough batches
    - No reason it should work

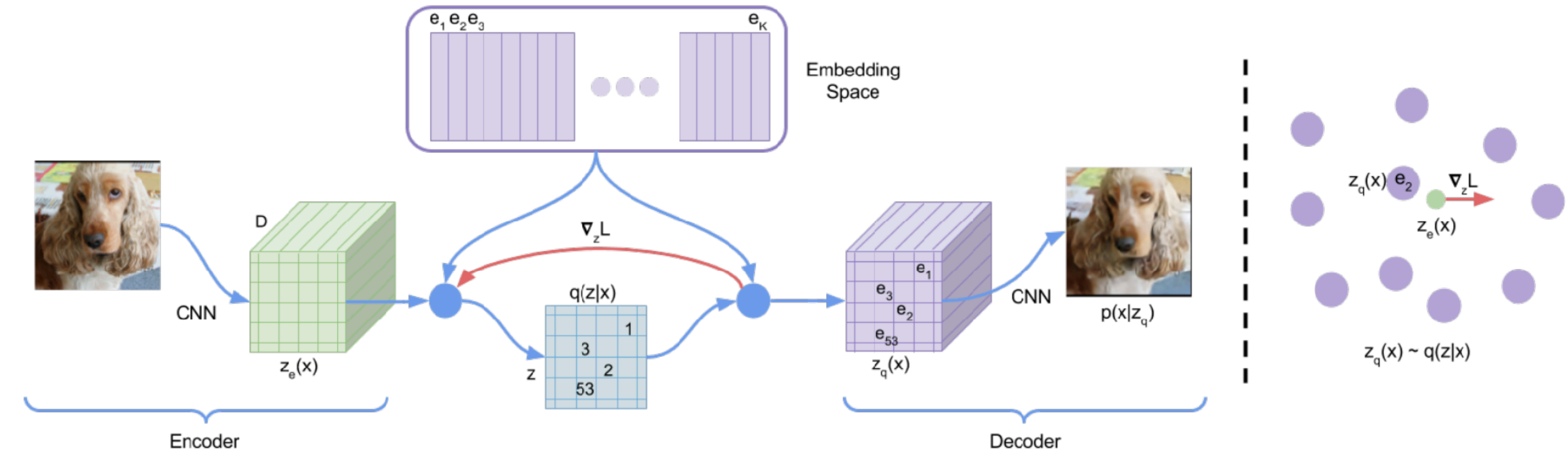




# VQ-VAE



# VQ-VAE



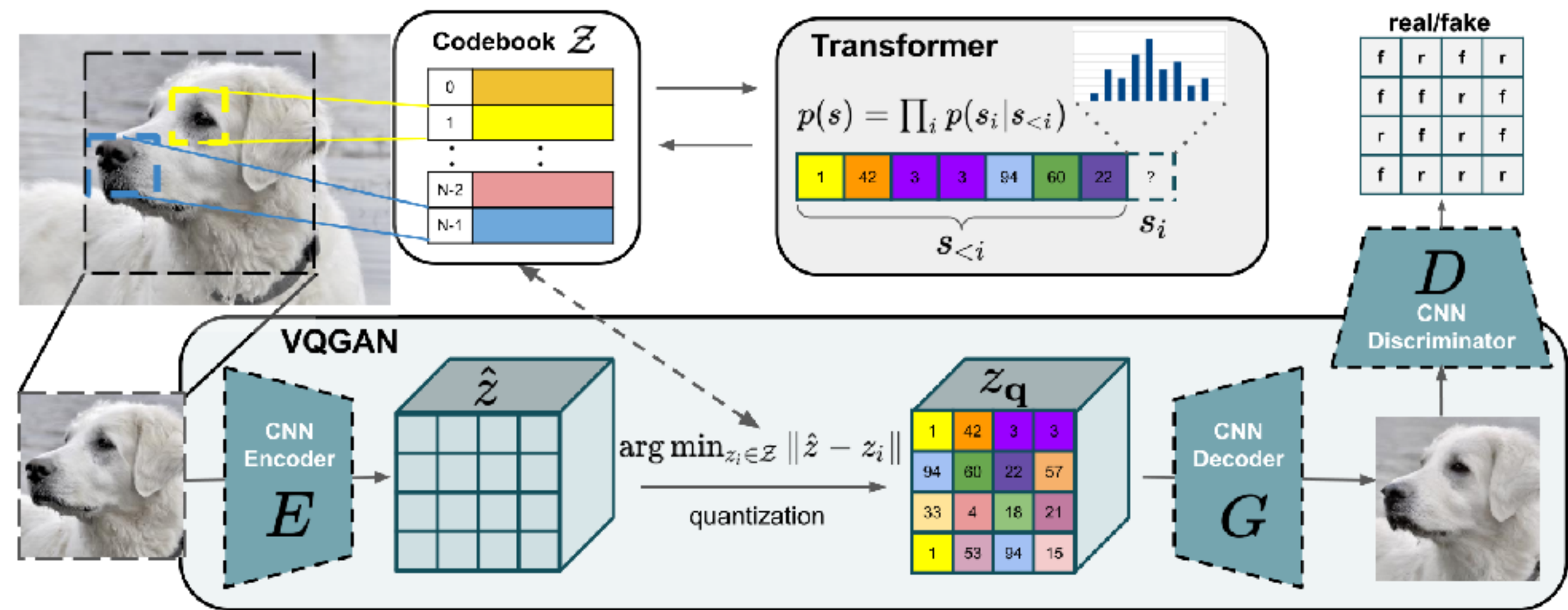
- Only as good as VAE
- Does not scale well with codebook size
  - Codebook grows exponentially in #bits
  - Many entries  $\rightarrow$  sparse gradients
  - Slow



# VQ-GAN

- Replace VAE with GAN
- Auto-encoder with vector quantization  

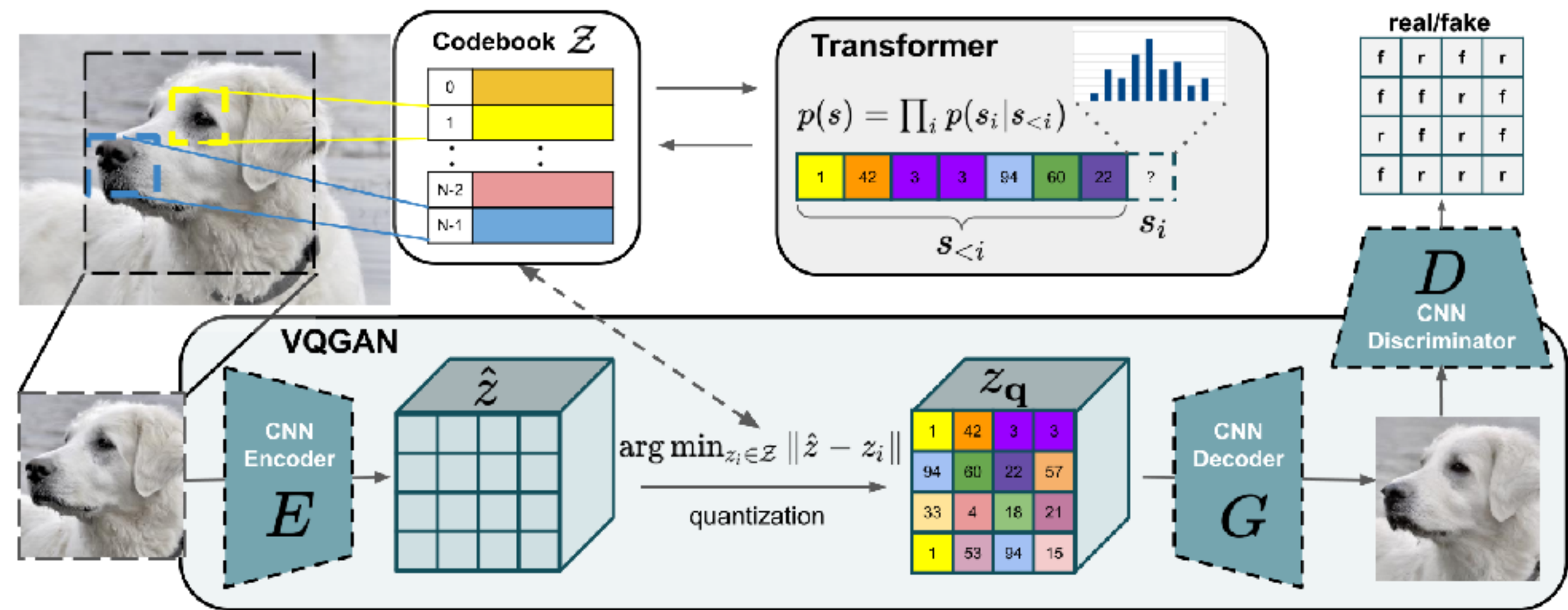
$$q(z) = \arg \min_{e_k} \|z - e_k\|$$
- GAN + Reconstruction loss
- Learn a sequence model on top
- Default image tokenizer nowadays





# VQ-GAN

- Great tokenizer, ok sequence model
- Does not scale well with codebook size
- Codebook grows exponentially in #bits
- Many entries  $\rightarrow$  sparse gradients
- Slow

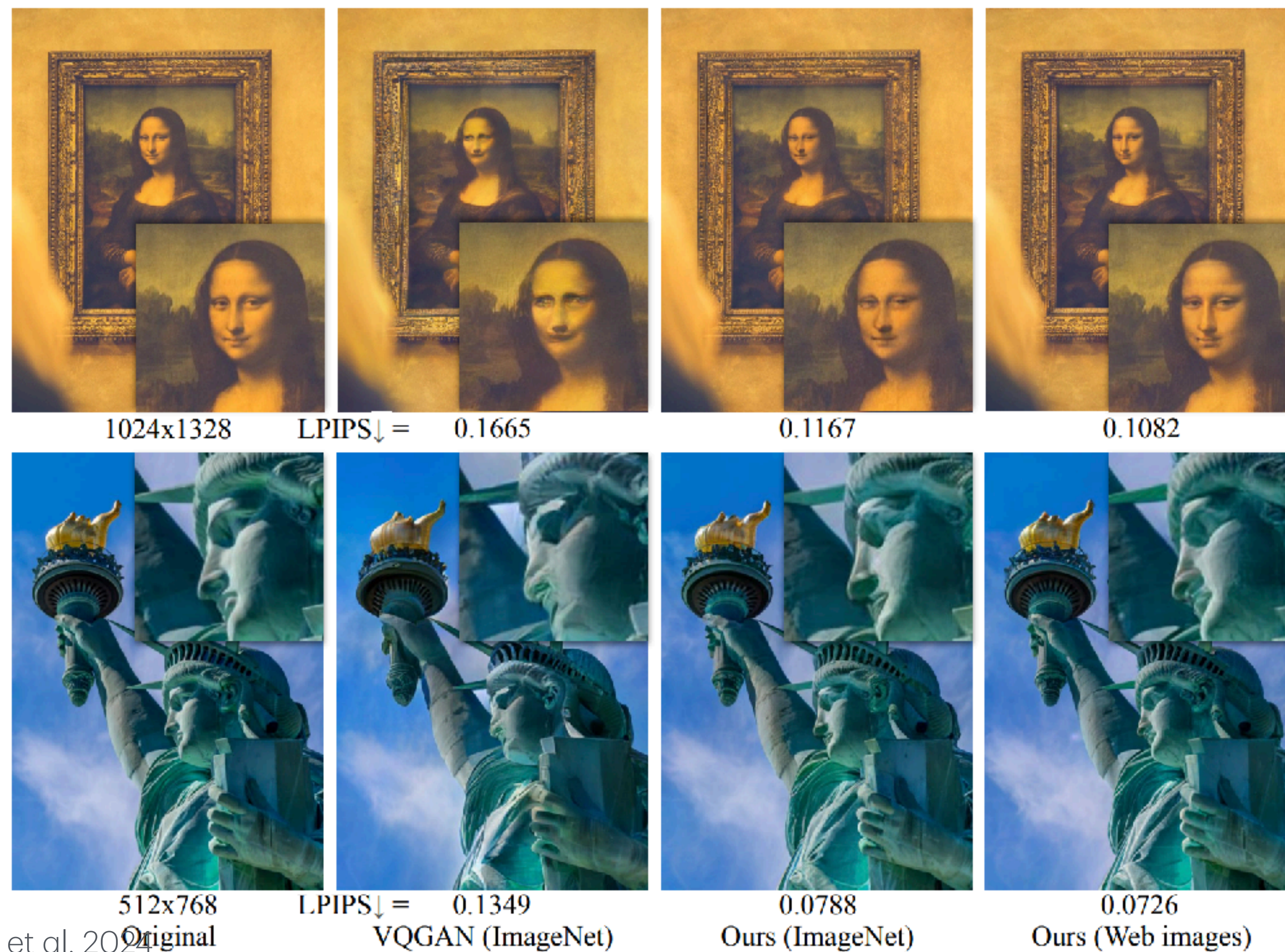
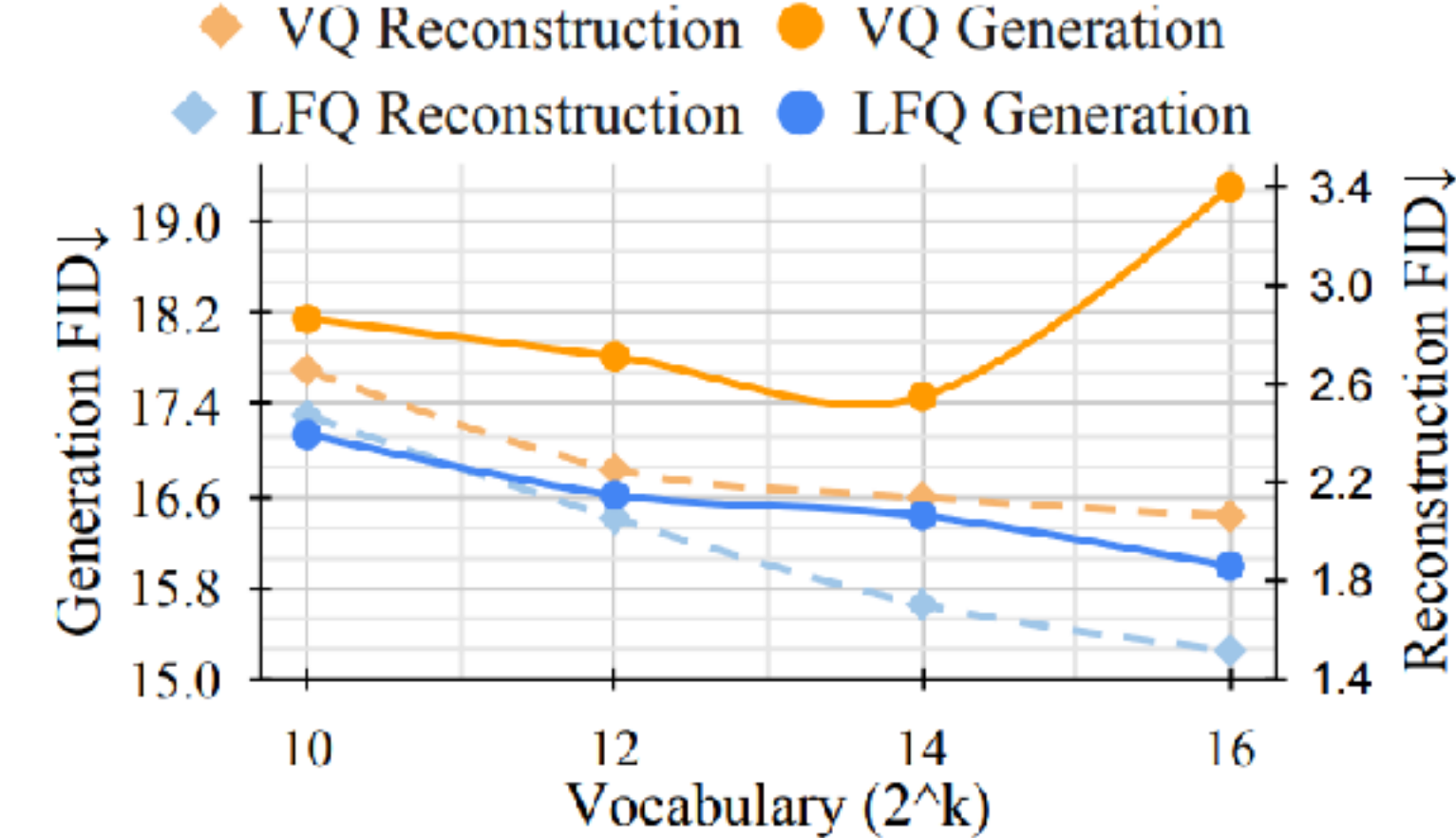




# LFQ

## Lookup-Free Quantization

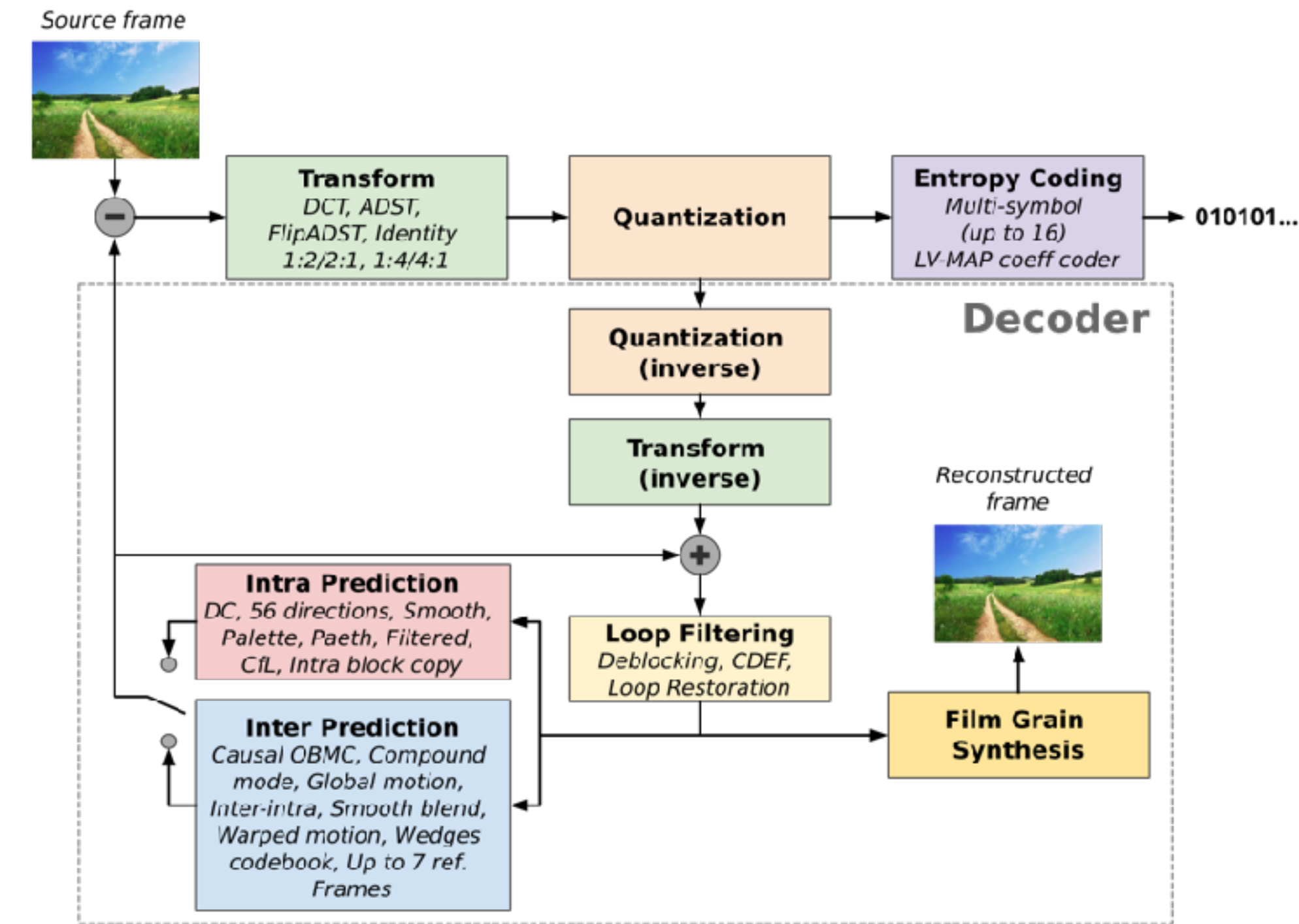
- Different quantizer
  - $q(z) = \text{sign}(z)$  where
$$\text{sign}(z_i) = 1_{[z_i \leq 0]} - 1_{[z_i > 0]}$$
- Scales linearly with #bits in bottleneck
- No learned parameters





# Generation vs Compression

- Auto-regressive model
- Lossless compression (fancy gzip)
- Tokenization (VQ)
- Lossy compression
- Similar to how JPEG most video codecs work



Source: [https://commons.wikimedia.org/wiki/File:The\\_Technology\\_Inside\\_Av1.svg](https://commons.wikimedia.org/wiki/File:The_Technology_Inside_Av1.svg)

# Generative models

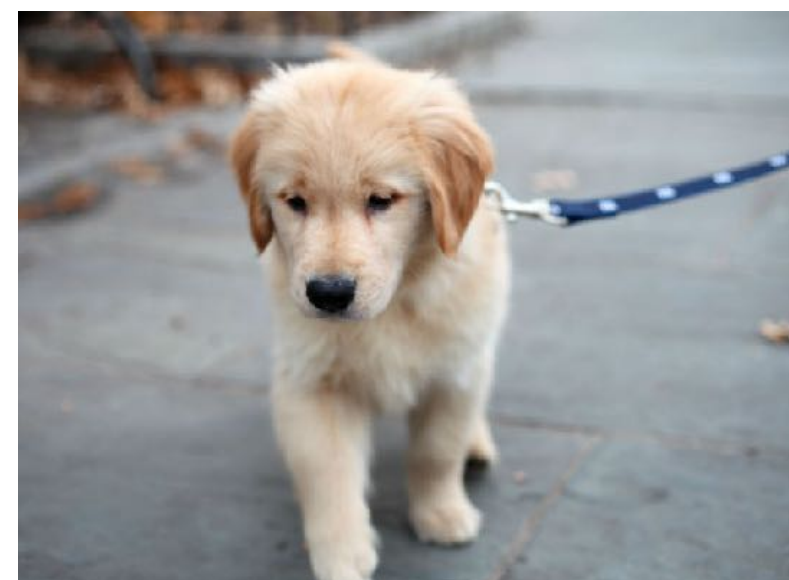
## Two kinds of models

Sampling based  $x \sim P(X)$

- Sample  $z \sim P(Z)$
- Learn transformation
- $P(x|z)$  or  $f: z \rightarrow x$

$z$

Deep  
Network



Density estimation based  $P(X)$

- Learn special form of  $P(X)$
- Model specific sampling / generation



Deep  
Network

$P(X)$



# References

- [1] WaveNet: A Generative Model for Raw Audio. Aaron van den Oord, et al. 2016
- [2] Long Video Generation with Time-Agnostic VQGAN and Time-Sensitive Transformer. Songwei Ge, et al. 2022
- [3] Neural Discrete Representation Learning. Aaron van den Oord, et al. 2017
- [4] Language models are unsupervised multitask learners. Alec Radford, et al. 2019
- [5] Simulating 500 million years of evolution with a language model. Thomas Hayes, et al. 2024
- [6] MAGVIT: Masked Generative Video Transformer. Lijun Yu, et al. 2023
- [7] Estimating or Propagating Gradients Through Stochastic Neurons for Conditional Computation. Yoshua Bengio, et al. 2013
- [8] Taming transformers for high-resolution image synthesis. Patrick Esser et al. 2021
- [9] Language Model Beats Diffusion -- Tokenizer is Key to Visual Generation. Lijun Yu, et al. 2024