

# Non-Linearities

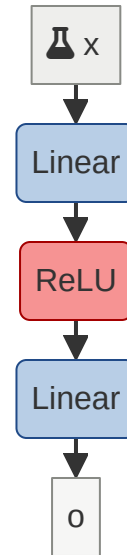
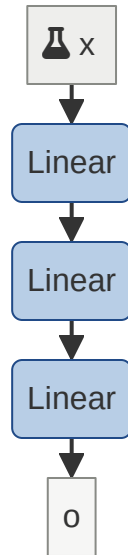
## Recap: A Simple Example



### **Linear models**

A linear model cannot distinguish paws from background

# Deep Networks

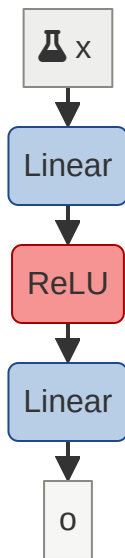
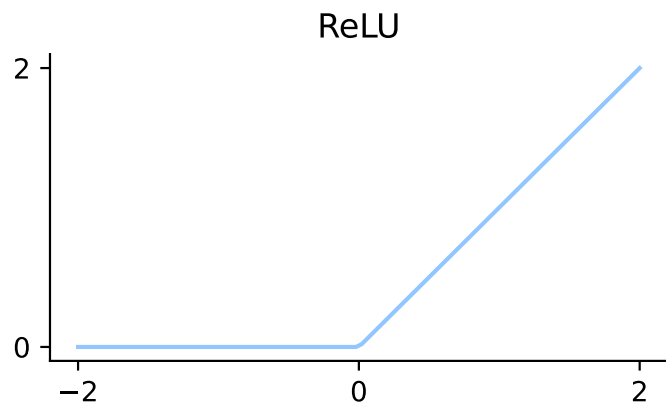


# Non-Linearities

Rectified Linear Unit (ReLU)

$$\text{ReLU}(x) = \max(x, 0)$$

Non-linear and differentiable almost everywhere



# A Simple Example - Why?

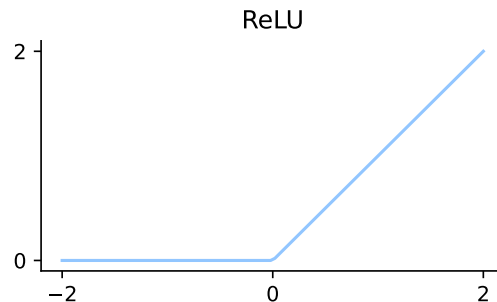
## Intuition

- first layer learns the color categories of the paw (white, black, grey)
- second layer classifies color as paw or not



## How?

$$\text{ReLU}(x) = \max(x, 0)$$



# A Simple Example - Why?

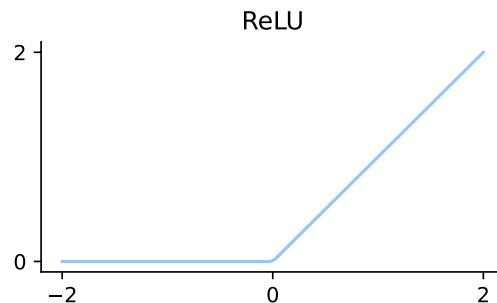
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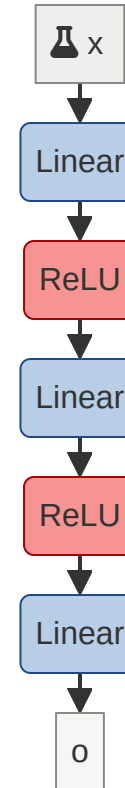
$$f(x) = \text{ReLU}\left(x - \frac{1}{2}\right) + \text{ReLU}\left(\frac{1}{2} - x\right) - \frac{1}{4}$$
$$= \left|x - \frac{1}{2}\right| - \frac{1}{4}$$

$$\text{ReLU}(x) = \max(x, 0)$$



# Deep Networks

Alternates linear and non-linear layers



# Deep Networks

Model:  $f_{\theta} : \mathbb{R}^n \rightarrow \mathbb{R}^c$

Parameters:  $\theta = (\mathbf{W}_1, \mathbf{b}_1, \dots, \mathbf{W}_N, \mathbf{b}_N)$

Computation:

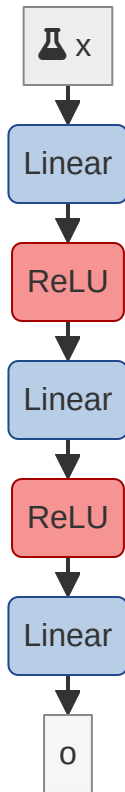
$$\mathbf{h}_1 = \text{ReLU}(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1)$$

$$\mathbf{h}_2 = \text{ReLU}(\mathbf{W}_2 \mathbf{h}_1 + \mathbf{b}_2)$$

$\vdots$

$$\mathbf{h}_{N-1} = \text{ReLU}(\mathbf{W}_{N-1} \mathbf{h}_{N-2} + \mathbf{b}_{N-1})$$

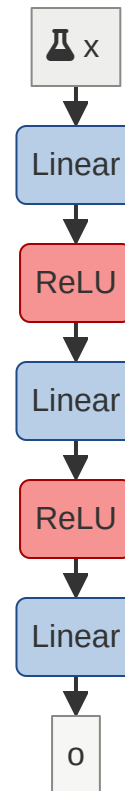
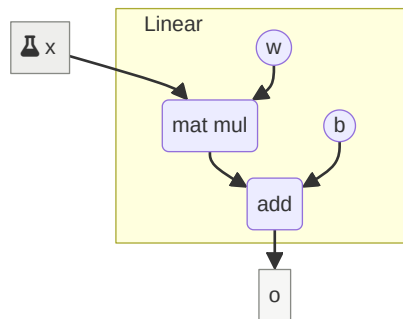
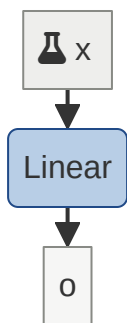
$$f_{\theta}(\mathbf{x}) = \mathbf{W}_N \mathbf{h}_{N-1} + \mathbf{b}_N$$





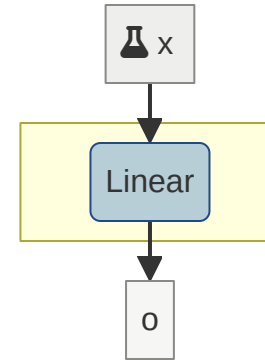
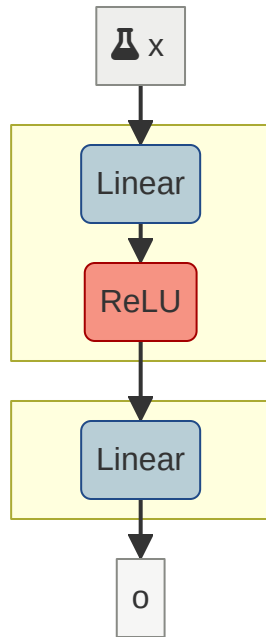
# What Is a Layer?

Largest computational unit that remains unchanged throughout different architectures



# How Many Layers Does a Deep Network Have?

We only count linear layers

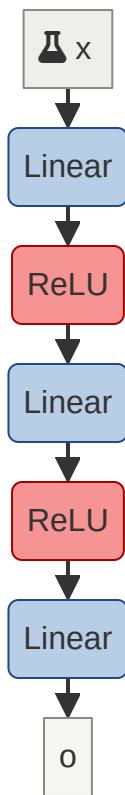


# Universal Approximation Theorem

## Universal Approximation Theorem

A two-layer deep network can approximate any continuous function.

- Constructing is inefficient
- Deep learning exploit structure in data to find efficient approximations



# Non-Linearities - TL;DR

Deep networks are stacks of alternating linear and non-linear layers

Deep networks belong to a class of continuous functions that can approximate **any** continuous function!